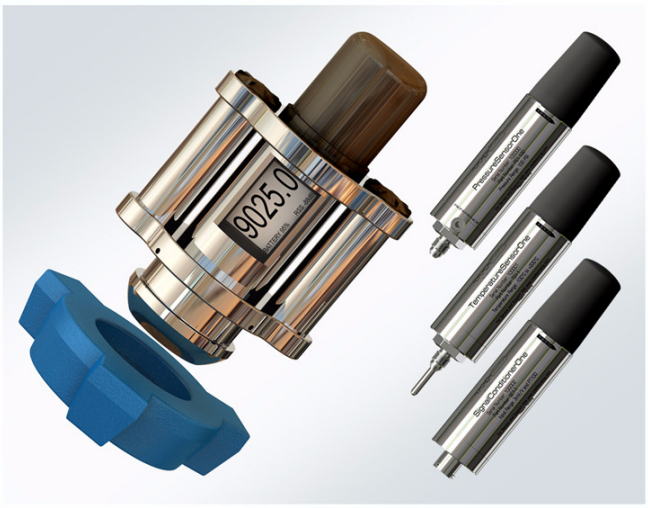
IntelliSensing Wireless Sensor Products

User Manual



Use with Sensor Families PS1, PS2, TS1, FS1, and SC1
Sensor FW 0230+ / Radio FW 0183+
IntelliSensing Document:100444K

The Network is the Sensor™

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CHAPTER 1
Introduction

This chapter provides an overview of IntelliSensing sensors and describes key technologies used by the PressureSensorOne/Two (PS1/PS2) wireless pressure sensor.

The patent-pending PS1/PS2 is a compact, self-contained wireless pressure sensor. Highly accurate pressure measurements are transmitted wirelessly to a base station and passed to a host computer/controller. The internal battery powers the sensor for the entire calibration period of one year.

The following topics are covered in this chapter:

- "Company Information" on page 5
- "PS1/PS2 Description" on page 6
- "Advanced Sensing" on page 6
- "Integrated Data Acquisition" on page 7
- "Cutting Edge ZigBee" on page 7
- "Standards-Based Radio Hardware" on page 7
- "Theory of Operation" on page 7

Company Information

IntelliSensing LLC, an aggressive technology company, stems from a solid footing in the aerospace market. With a strong background in sensing instrumentation design and information technology, the company has combined the trusted methods of physical measurement with embedded technology to produce sensors that interface directly with digital systems.

Our mission is to provide intelligent sensing products that enable advanced applications or improve existing systems with networked extensions. Our slogan, The Network is the Sensor, highlights our commitment to provide a system solution not only incorporating sensors, but also the infrastructure responsible for transporting the measurement data to the destination.

With an increase in the global demand for quality at a reduced cost, a world of ubiquitous sensors is imminent. The integration of intelligence inside the sensor increases the accuracy of the measurement while simultaneously lowering the cost of the system. By reducing cabling and eliminating individual channels of data acquisition, the density of the measurement array becomes less constrained by cost and more driven by the desire for a comprehensive dataset.

IntelliSensing LLC not only produces the sensor, but provides the means to transport the measurement data to the destination. This is accomplished through the careful selection and implementation of key layers of the Open System Interconnection (OSI) networking model, and the development and support of XML-based Web services.

PS1/PS2 Description

The patent-pending IntelliSensing PS1/PS2 is a compact, self-contained wireless pressure sensor. Highly accurate pressure measurements are transmitted wirelessly to a suitable base station and passed to a host system such as a PC or PLC. The internal battery powers the sensor for the entire calibration period of one year.

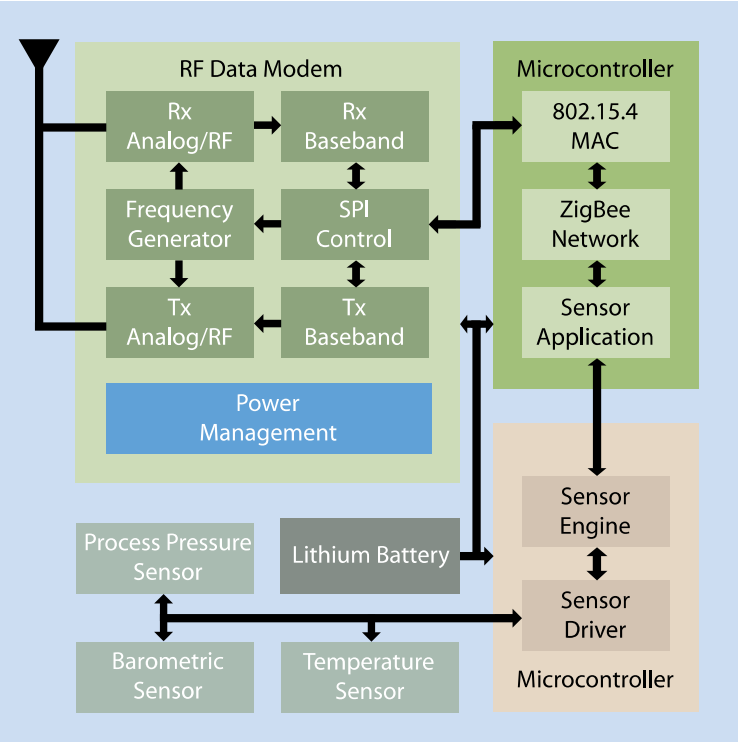

Figure 1-1: PS1 Function Block Diagram

Advanced Sensing

Pressure is measured utilizing an all stainless-steel wetted surface pressure diaphragm with a proprietary sputtered thin-film full-bridge strain gauge circuit. The sputtered metal strain gauge circuit offers superior long term stability and higher temperature capability than other strain gauge technologies. An internal barometric pressure sensor allows the pressure reference to be user-selectable. An external threaded reference port is provided.

Integrated Data Acquisition

Signals are amplified, sampled and digitized into 24-bit words at a rate of up to 1 Ks/S. This is all accomplished using a precision mixed-signal microcontroller (MCU) which integrates an analog-to-digital converter (ADC) and a high-speed 8051-compatible CPU. Accurate measurements are passed to the wireless subsection for transmission.

Cutting Edge ZigBee

ZigBee wireless solutions combines an ultra-low power IEEE 802.15.4 transceiver with ZigBee software to form a transparent wireless communication solution that has self-organizing and self-healing properties. This mesh network allows for ease of installation around obstructions, redundancy in communication paths, and longer range. The 2.4 GHz frequency band is suitable for worldwide use.

Standards-Based Radio Hardware

The IEEE 802.15.4 Standard details the Physical Layer (PHY) and Medium Access Control (MAC) specifications, and offers the building blocks for different types of networking known as "star, mesh, and cluster tree." Network routing schemes are designed to ensure power conservation, and low latency through guaranteed time slots. Communication redundancy is a unique feature of the ZigBee network layer, eliminating "single point of failure" in mesh networks. Key features of the PHY include energy and link-quality detection, and clear channel assessment for improved coexistence with other wireless networks. The MAC specifies automatic packet acknowledgement, provides options for transmission in a range of pre-selected time intervals, and supports 128-bit AES security. The MAC and ZigBee application software is implemented in a code-efficient microcontroller that communicates digitally with the sensor data acquisition hardware.

Theory of Operation

Due to the requirement of long battery life, the PS1/PS2 remains in a low-power state of reduced functionality for the majority of time. It periodically wakes up and transmits a poll message to the base station to check if a command message addressed to the sensor is queued. If no message is waiting, the sensor returns to the low-power state and the cycle starts over. If a message exists that is addressed to the sensor, it is transmitted by the base station, and received by the sensor for processing. Command messages vary in functionality, and have different parameter requirements. All commands return a resulting status code that specifies the success or failure of the operation.

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CHAPTER 2
Installation

This chapter provides a description of the steps required to install the PS1/PS2 wireless pressure sensor. Please have available all the included hardware and documentation that came with your sensor.

The following topics are covered in this chapter:

- "Opening the Case" on page 9
- "Battery" on page 10
- "Closing the Case" on page 11
- "PS1 Installation" on page 11
- "PS2 Installation" on page 12

Opening the Case

While the PS1 must be opened to replace the battery, the PS2 batteries are replaced via the two battery compartments that are accessible from the outside of the housing. There are no user-servicable parts inside the PS2 and should not be opened.

In order to get access to the inside of the PS1, the antenna must be removed by rotating it in a counter-clockwise direction while holding the body of the sensor stationary. There is some initial resistance that is caused by the o-ring that runs along the mating surface of the antenna. The body or outer shell must then be pulled off the remaining portion of the sensor by holding the pressure port stationary and simultaneously rotating the body and pulling outward.

The sensor can be placed in a vise and clamped on the wrench flats to assist with this operation. Once the sensor is open, be careful not to touch the electronic circuitry other than the battery and battery holder.

CAUTION

Be careful not to damage the threaded pressure port by installing the protective cap that shipped with the sensor onto the port. Always work in an clean area that is clear of dust and debrise.

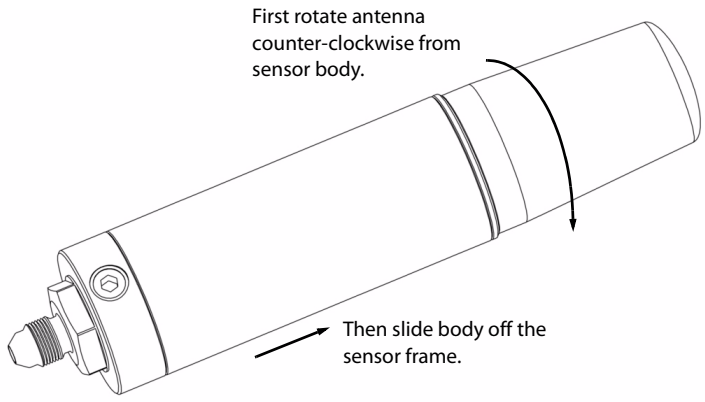


Figure 2-1: Opening the Case

Battery

The PS1 is shipped from the factory with a battery installed, but it is protected from discharging by a Teflon strip that resides between the battery's positive terminal and the battery holder's contact. This strip must be removed in order for the PS1 to operate. With the sensor assembly stationary, simply pull the Teflon strip away from the battery until it is completely free. The strip should be saved for future use.

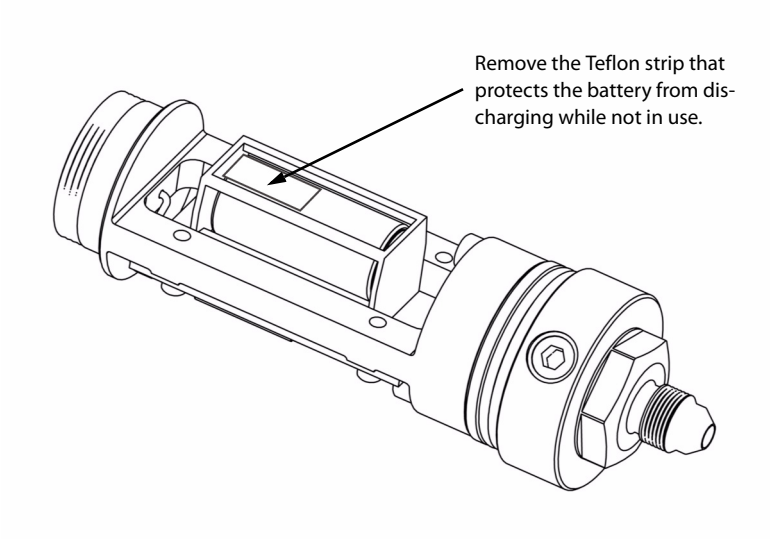


Figure 2-2: Teflon Strip Removal

Closing the Case

The PS1 must be re-assembled and closed in order for proper operation. The body or outer shell must be pushed onto the sensor assembly by holding the pressure port stationary and simultaneously rotating the body and pushing inward. The sensor should be placed in a vise and clamped on the wrench flats to assist with this operation. There is some final resistance that is caused by the o-ring that runs around the perimeter of the pressure cap.

CAUTION

Be careful not to pinch your hand while pushing the body back onto the sensor. This operation should be performed using a vise to hold the sensor stationary.

The antenna must be replaced by rotating it in a clockwise direction while holding the body of the sensor stationary. There is some final resistance that is caused by the o-ring that runs along the mating surface of the antenna. Once the antenna is initially seated, an additional ¼ turn should be made to provide a sufficient friction fit.

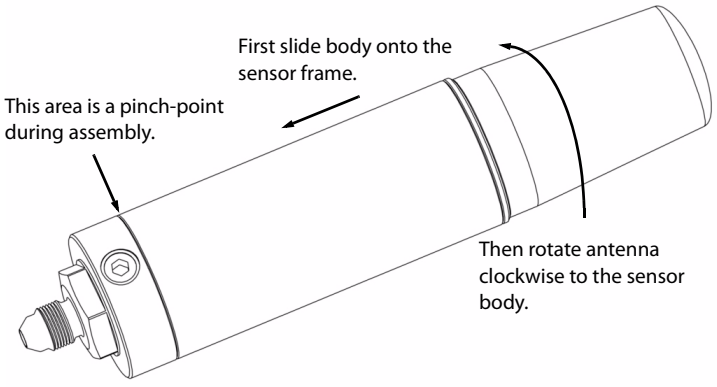

First slide body onto the sensor frame.
This area is a pinch-point during assembly.
Then rotate antenna clockwise to the sensor body.

Figure 2-3: Closing the Case

PS1 Installation

The standard pressure port on the PS1 conforms to the SAE AS4395 E 04 specification. An SAE AS568A-012 o-ring must be used when the sensor is screwed into a mating SAE AS5202 04 compliant port. The sensor's pressure port also can be connected metal-to-metal with a JIC 37° flared fitting.

The PS1 is orientation insensitive with regards to pressure measurement accuracy and performance, but should be mounted vertically when possible in order to maximize the RF coverage.

PS2 Installation

The standard pressure port on the PS2 is described as a 2" Fig 1502 Male Sub or Weco Hammer Union. The port works in conjunction with a 2" Fig 1502 Female Sub and Nut.

The PS2 is orientation insensitive with regards to pressure measurement accuracy and performance, but should be mounted vertically when possible in order to maximize the RF coverage.

Wireless Base Station

The PS1/PS2 uses wireless communication hardware provided by MaxStream, Inc. As such, the base stations available from IntelliSensing are the Xbee-PRO-PKG-R for RS-232 interface applications and the XBee-PRO-PKG-U for USB interface applications. The value added by IntelliSensing includes updating the base station to the latest firmware, pre-configuring the communication parameters for use with IntelliSensing wireless sensor networks, and 100% acceptance testing with actual IntelliSensing sensors. The documentation and software included with the base station hardware must be used to install and configure the base station only. The X-CTU software provided with the base station is used in this manual to provide a clear example on how to communicate with the PS1/PS2.

Since the base station and all wireless sensor products from IntelliSensing conform to the IEEE 802.15.4 specification, the final application solution can include compatible hardware products from other manufacturers.

CHAPTER 3
Getting Started

This chapter provides a description of the steps required to start making accurate wireless pressure measurements with the PS1/PS2 pressure sensor. Please have available all the included hardware and documentation that came with your sensor.

The following topics are covered in this chapter:

- "Communication" on page 13
- "Sample Session" on page 14
- "Starting X-CTU" on page 14
- "Base Station Configuration" on page 15
- "Setting Destination Address" on page 16
- "Terminal Mode" on page 17
- "Measure Single Measurement" on page 18
- "Finishing Up" on page 19

Communication

Due to the requirement of long battery life, the PS1/PS2 remains in a low-power state of reduced functionality for a majority of the time. It periodically wakes up and transmits a poll message to the base station to check if a command message addressed to the sensor is queued. If no message is waiting, the sensor returns to the low-power state and the cycle starts over. If a message exists that is addressed to the sensor, it is transmitted by the base station, and received by the sensor for processing. Command messages vary in functionality, and have different parameter requirements. All commands return a status code that specifies the success or failure of the operation.

Each device has two addresses that identify it on the network: one 16-bit address and one 64-bit address. The 16-bit address or *Source Address* of the sensor is programmed by IntelliSensing to correspond to the last four digits of the sensor's serial number. The sensor's 64-bit address is factory programmed by the manufacturer of the wireless hardware, and is located on a label inside the sensor. In the case of the base stations provided by IntelliSensing, the 16-bit *Source Address* of the base station has already been programmed to a value of *0000* at the factory.

When a base station transmits a message to a specific sensor, the 16-bit or 64-bit *Source Address* of the sensor must be programmed into the base station as the *Destination Address*. When the sensor transmits a message to the base station, the 16-bit *Destination Address* the sensor uses is *0000*. The *Destination Address* used by the sensor can be programmed.

Sample Session

The following screenshots illustrate a sample session of obtaining the sensor's serial number and a test pressure. The sensor's serial number is *115678*.

Starting X-CTU

The X-CTU program provides a direct interface to the wireless base station required to communicate with the PS1 wireless pressure sensor. Below is a screenshot from the opening dialog box.

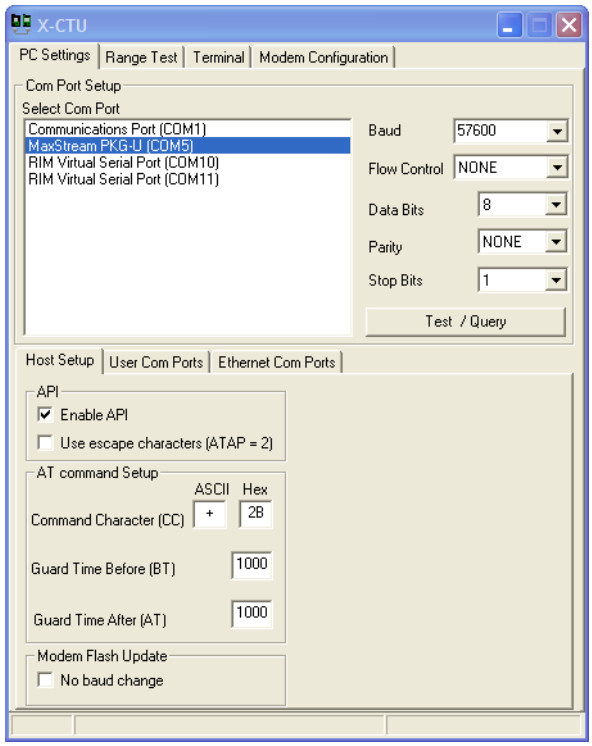


Figure 3-1: Configuring PC Settings

Base Station Configuration

The *Modem Configuration* tab contains buttons used to perform actions on the connected base station. Click the *Read* button and observe the information returned about the connected base station.

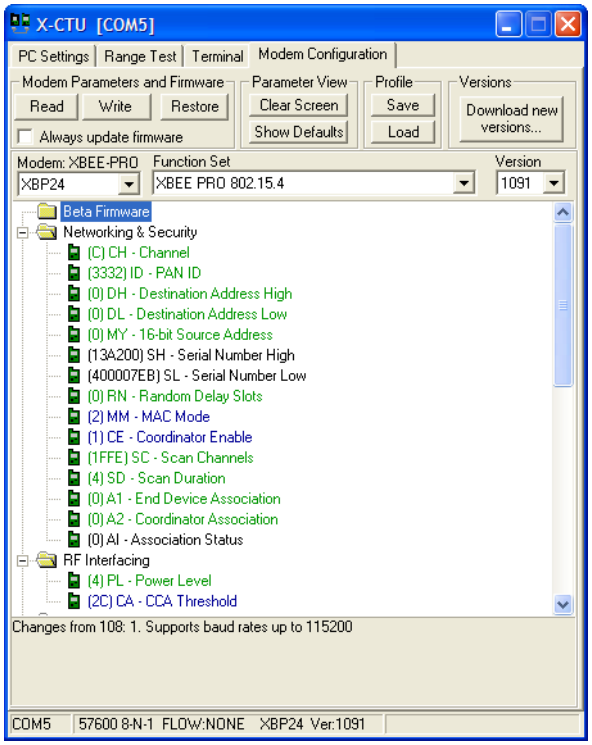


Figure 3-2: Configuring XBee Parameters

There are six settings that must always have specific values in order to communicate with a PS1 wireless pressure sensor. These settings have already been factory programmed with the following hexadecimal values:

Name	Description	Value
MY	16-bit Source Address	0x0000
MM	MAC Mode	0x02
CE	Coordinator Enable	0x01
ST	Time Before Sleep	0x0064
SP	Cyclic Sleep Period	0x03E8
AP	API Enable	0x01

Table 3-1: Mandatory Base Station Settings

It is recommended to change one additional setting that controls the baud rate of the interface between the base station and the computer or controller. The rate of data exchange between the base station and the computer or controller is independant of the fixed 250 Kbps wireless RF data packet transmission rate. Since the PS1 internally communicates with it's internal RF transceiver at 57,600 it is recommended that the base station use the same rate in order to prevent a buffer overrun condition. This setting has already been factory programmed with the following hexadecimal value:

Name	Description	Value
BD	Interface Data Rate	0x06

Table 3-2: Recommended Base Station Setting

Setting Destination Address

The *Destination Address* of the base station corresponds to the *Source Address* of the sensor that is to be communicated with and should be set to hexadecimal value of 5678 in this case since the sensor's serial number is *115678*.

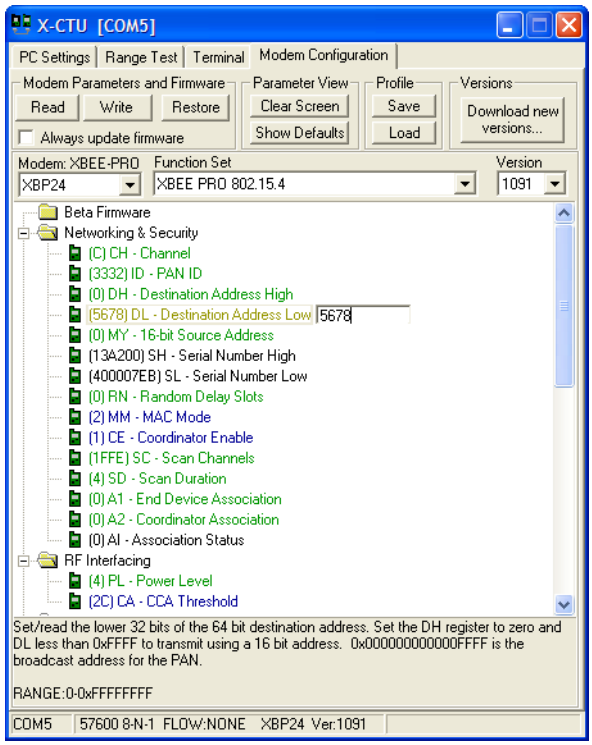


Figure 3-3: Setting Destination Address

Terminal Mode

The *Terminal* tab contains an area that allows typed information to be sent to the base station for processing. Click the *Show Hex* button to reveal hexadecimal values of communicated data.

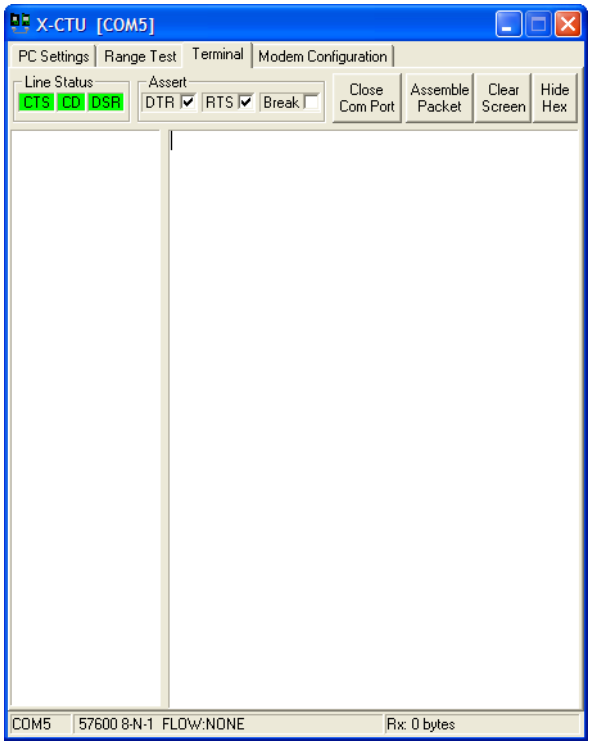


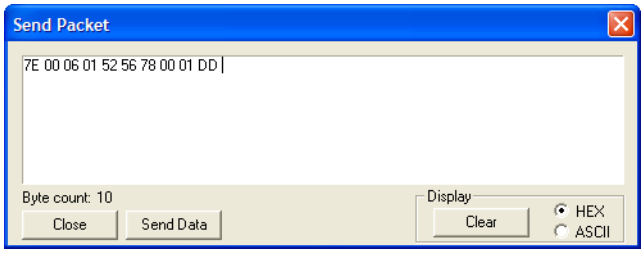
Figure 3-4: Terminal Tab

Measure Single Measurement

Make sure the sensor's test port is open to atmosphere. Click the <Assemble Packet> button and use the Send Packet dialog box to enter the hexadecimal values shown in the example below. Click on the <Send Data> button. This command requests a single pressure measurement from the sensor that is being addressed. Since the sensor wakes up every ten seconds to check for any command messages addressed to it, there will be a delay of up to ten seconds for the sensor to receive and process the command.

The pressure measurement includes five floating point values that describe the primary pressure, internal barometric pressure, sensing element temperature, battery voltage, and electronics temperature. The topic "Measure Single Reading (MSR) Command - 0x01" on page 30 provides an explanation of the data illustrated in this example.

A)



B)

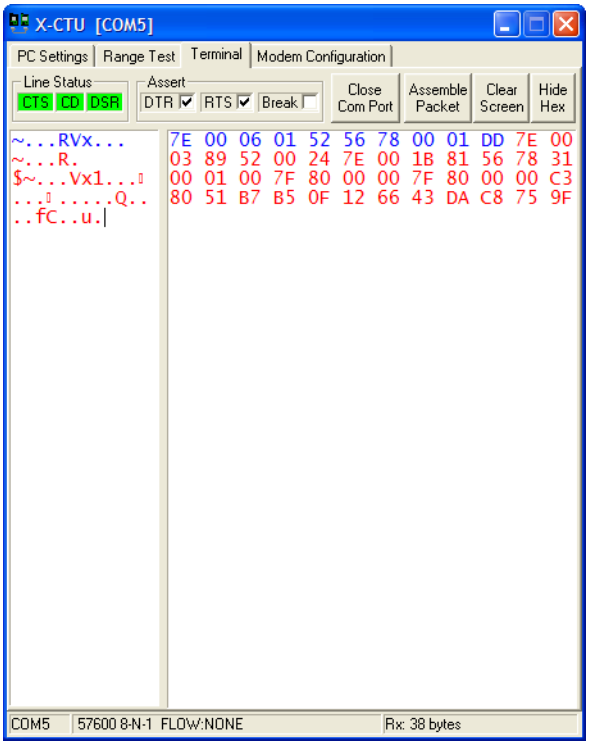


Figure 3-5: A) Sending an RF Data Packet; B) Data Sent (blue) and Received (red)

Finishing Up

Remove the pressure from the sensor's test port. All the steps described in this chapter can be applied to any sensor with the only change being the programming of the *Destination Address* on the base station with a value that matches the sensor's *Source Address*. The base station's *Destination Address* can be changed using the instructions provided in this chapter, or can be accomplished programmatically by following the instructions included with the base station.

The PS1 sensor and the BS1 base station use the Maxstream XBee and XBee Pro RF modules. As such, the IEEE 802.15.4 networking parameters can be changed as needed to configure a custom network. The "XBee™/XBee-PRO™ OEM RF Modules Product Manual" on page 83 is included with this this manual as Appendix B in order to assist you with configuring these parameters. You can consult IntelliSensing or Maxstream for assistance if required.

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CHAPTER 4
API Data Frame Specification

This chapter provides a description of the API Data Frame Specification that is used to communicate with the PS1/PS2 wireless sensor. Please have available all the included hardware and documentation that came with your sensor.

The following topics are covered in this chapter:

- "Introduction" on page 21
- "Data Frame Types" on page 23
- "API Data Types" on page 26

Introduction

IntelliSensing wireless sensor products incorporate wireless components provided by MaxStream, Inc. Specifically, we utilize the *XBee* and *XBee Pro* ZigBee/IEEE 802.15.4 compliant RF modules. Communication with IntelliSensing wireless sensors is accomplished through data frame messages being passed between a host computer/controller and a wireless base station. The *BS1-U* and *BS1-R* wireless base station products from IntelliSensing are based on the *XBee-PRO ZigBee/802.15.4 USB RF Modem* and *XBee-PRO ZigBee/802.15.4 RS-232 RF Modem*, respectively.

This chapter provides information needed to understand and perform communication tasks within the wireless sensor network using the above hardware. Since the IntelliSensing line of wireless sensor products relies on established and standardized RF hardware and protocols, this section will describe the Frame Data portion of the Data Frame Structure only, and will rely heavily on the user's understanding and familiarity of the "XBee™/XBee-PRO™ OEM RF Modules Product Manual" on page 83 labelled as Appendix B. *Section 3.4 API Operation* of Appendix B describes the RF data packet and discusses three modes of API Operation. All IntelliSensing wireless sensor products use API Operation Mode 1 (AP parameter = 1) and are pre-configured from the factory using this mode.

API operations require that communication with the sensor be done using a wireless base station that works with a virtual or physical serial communications port on a host computer or as a physical serial communications port on a controller. See the topic "Base Station Configuration" on page 15 for information on setting up the base station. Data is highly structured and is communicated in frames, in a defined order. The API specifies how commands, command responses and command reply messages are sent to and received from the wireless base station.

Data Frame Structure

Each packet of data sent to and received from the base station is called a *Data Frame* and is organized in a format called the *Data Frame Structure*. The Data Frame Structure is described in detail in the MaxStream documentation. It is passed to and from the wireless base station and is defined as follows:

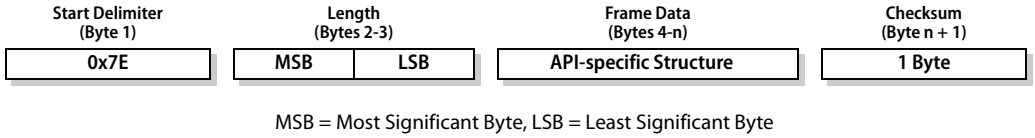

Figure 4-1: Data Frame Structure

Checksum

To test data integrity, a checksum is calculated and verified. If the base station receives a data frame and the checksum is not valid, the entire data frame will be ignored without warning.

To calculate: Not including frame delimiters and length, add all bytes keeping only the lowest 8-bit portion of the result and subtract from 0xFF.

To verify: Add all bytes (including checksum, but not the delimiter and length). If the checksum is correct, the sum will equal 0xFF.

Example - This is a Data Frame Structure for a Measure Single Measurement (MSM) command directed to a sensor having a serial number withe the last four digits of 5678:

0x7E 0x00 0x06 0x01 0x52 0x56 0x78 0x00 0x01 0xDD

In the above example, the length of the raw data (excluding checksum) is 0x0006 and the checksum is calculated as:

$$Checksum = 0xFF - [0x01 + 0x52 + 0x56 + 0x78 + 0x00 + 0x01]$$
$$Checksum = 0xFF - [0x22]$$
$$Checksum = 0xDD$$

Data Frame Types

The three primary types of data frames used when communicating with the PS1/PS2 using a base station are:

Type	Description
Command	Command data is sent to the base station from the computer/controller. This data is subseqently transmitted to the wirless sensor network.
Response	Response data is an acknowledgement sent from the base station to the computer/controller in response to an attempt to transmit command data.
Reply	Reply data is received by the base station from the wireless sensor network. This data is subsequently sent to the computer/controller.

Table 4-1: Data Frame Types

All data frames from every type conform to the same data frame format as described in "Data Frame Structure" on page 22. The differences reside entirely in the *Frame Data* portion of the frame.

Command Data Frame

The PS1/PS2 performs an action as a result of recieving a command. A PS1/PS2 command that is sent to the base station and subsequently transmitted to the sensor, is called a *TX (Transmit) Request* message in the MaxStream documentation but will be referred to here as a *Command* message due to it's PS1/PS2-specific implementation. It contains payload data specific to the PS1/PS2's operation. The format of the Command Data Frame that is sent to the base station is as follows:

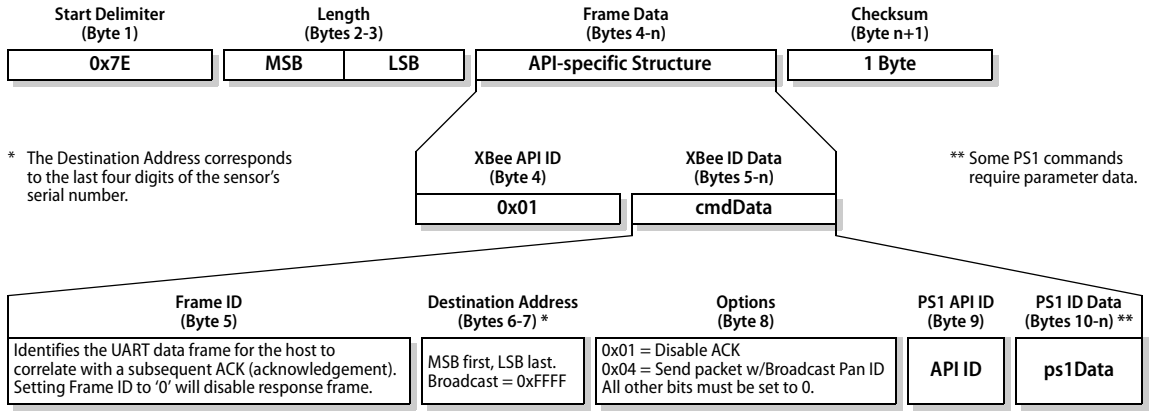
Start Delimiter (Byte 1)
Length (Bytes 2-3)
Frame Data (Bytes 4-n)
Checksum (Byte n+1)
0x7E
MSB
LSB
API-specific Structure
1 Byte
* The Destination Address corresponds to the last four digits of the sensor's serial number.
XBee API ID (Byte 4)
XBee ID Data (Bytes 5-n)
0x01
cmdData
** Some PS1 commands require parameter data.
Frame ID (Byte 5)
Destination Address (Bytes 6-7) *
Options (Byte 8)
PS1 API ID (Byte 9)
PS1 ID Data (Bytes 10-n) **
Identifies the UART data frame for the host to correlate with a subsequent ACK (acknowledgement). Setting Frame ID to '0' will disable response frame.
MSB first, LSB last. Broadcast = 0xFFFF
0x01 = Disable ACK
0x04 = Send packet w/Broadcast Pan ID
All other bits must be set to 0.
API ID
ps1Data

Figure 4-2: Command Data Frame

Command Response Data Frame

As a result of receiving a command, the base station will reply with a status message indicating the success or failure of the packet transmission to the sensor. This status message is called a *TX (Transmit) Status* message in the MaxStream documentation but will be referred to here as a *Command Response* message due to it's PS1/PS2-specific implementation. The format of the Command Response Data Frame returned from the base station as a result of attempting to send a command to the sensor is as follows:

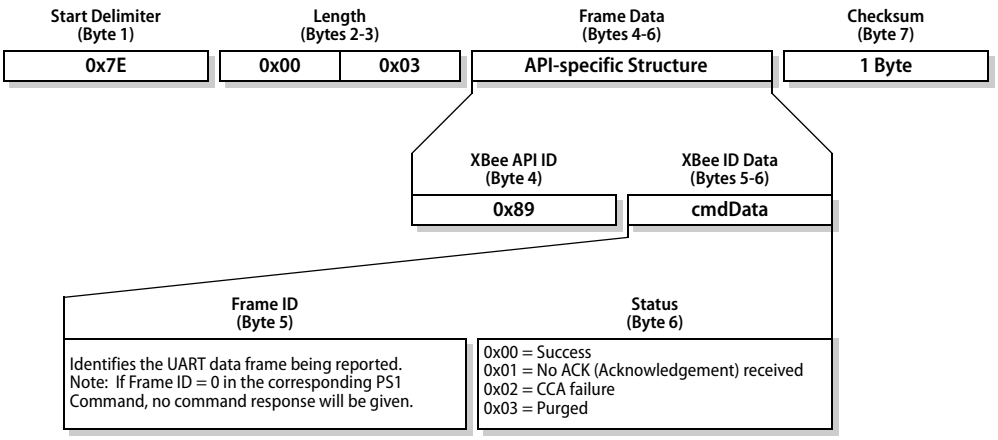

Figure 4-3: Command Response Data Frame

Reply Data Frame

As a result of receiving and executing a command, the PS1/PS2will reply to the base station with a message that contains any requested data along with a status byte indicating the success or failure of the command's execution. This message is subsequently sent to the computer/controller and is called a *RX (Receive) Packet* message in the MaxStream documentation but will be referred to here as a *Command Reply* message due to it's PS1/PS2-specific implementation.

The format of the Command Reply Data Frame returned from the base station as a result of receiving a status message from the sensor is as follows:

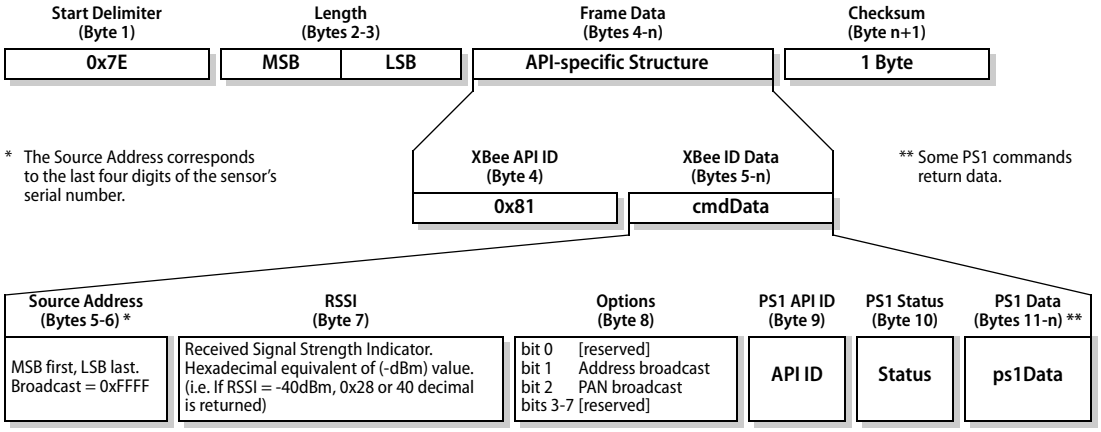
Start Delimiter (Byte 1)
Length (Bytes 2-3)
Frame Data (Bytes 4-n)
Checksum (Byte n+1)
0x7E
MSB
LSB
API-specific Structure
1 Byte
* The Source Address corresponds to the last four digits of the sensor's serial number.
XBee API ID (Byte 4)
XBee ID Data (Bytes 5-n)
0x81
cmdData
** Some PS1 commands return data.
Source Address (Bytes 5-6) *
RSSI (Byte 7)
Options (Byte 8)
PS1 API ID (Byte 9)
PS1 Status (Byte 10)
PS1 Data (Bytes 11-n) **
MSB first, LSB last. Broadcast = 0xFFFF
Received Signal Strength Indicator. Hexadecimal equivalent of (-dBm) value. (i.e. If RSSI = -40dBm, 0x28 or 40 decimal is returned)
bit 0 [reserved]
bit 1 Address broadcast
bit 2 PAN broadcast
bits 3-7 [reserved]
API ID
Status
ps1Data

Figure 4-4: Command Reply Data Frame

API Data Types

Several data types are used to express data that is provided to or returned from the PS1/PS2. These data types and their formats are:

Data Type	Bytes	Value Ranges
CHAR	1	ASCII character code 0 to 255
INT8	1	-128 to +127
UINT8	1	0 to 255
INT16	2	-32,768 to +32,767
UINT16	2	0 to 65,535
INT32	4	-2,147,483,648 to +2,147,483,647
UINT32	4	0 to 4,294,967,295
FLOAT	4	±1.175494E-38 to ±3.402823E+38

Table 4-2: Data Types

Text

Textual information stored using the "Sensor Control Parameter (SCP) Command - 0xA0 / 0x20" on page 36 is simply ASCII encoded bytes of character data.

Integers

Scalars of type INT8 (8-bit signed integer) and UINT8 (8-bit unsigned integer) are represented as a single byte (8 bits).

Scalars of type INT16 (signed 16-bit integer) and UINT16 (unsigned 16-bit integer) are represented as two bytes (16 bits). The high-order byte is shown first, followed by the low-order byte. For example, an integer value of 0x1234 is located in the data frame as follows:

	Index+0	Index+1
Contents	0x12	0x34

Table 4-3: 16-bit Integer Format

Scalars of type INT32 (signed 32-bit integer) and UINT32 (unsigned 32-bit integer) are represented as four bytes (32 bits). The high-order byte is shown first, followed through to the low-order byte. For example, an integer value of 0x12345678 is located in the data frame as follows:

	Index+0	Index+1	Index+2	Index+3
Contents	0x12	0x34	0x56	0x78

Table 4-4: 32-bit Integer Format

Floating Point Numbers

When measurement values of type float are returned in the Data Reply Frame, they are represented using four bytes (32-bits). The format used follows the IEEE-754 standard. A floating-point number is expressed as the product of two parts - the mantissa and a power of two. For example:

$$\pm mantissa \times 2^{\exponent}$$

The mantissa represents the actual binary digits of the floating-point number. The power of two is represented by the exponent. The stored form of the exponent is an 8-bit value from 0 to 255. The actual value of the exponent is calculated by subtracting 127 from the stored value (0 to 255) giving a range of –127 to +128.

The mantissa is a 24-bit value (representing about seven decimal digits) whose most significant bit (MSB) is always 1 and is, therefore, not stored. There is also a sign bit that indicates whether the floating-point number is positive or negative.

Floating-point numbers that are returned as a result of a PS1/PS2 command execution are stored in the Reply Data Frame Structure as follows:

	Index+0	Index+1	Index+2	Index+3
Contents	SEEE EEEE	EMMM MMMM	MMMM MMMM	MMMM MMMM

Table 4-5: Floating Point Format

Where:

- S represents the sign bit where 1 is negative and 0 is positive.
- E is the exponent with an offset of 127.
- M is the 24-bit mantissa (stored in 23 bits).

Zero is a special value denoted with an exponent field of 0 and a mantissa of 0.

Using the above format, the floating-point number -12.5 is stored as a hexadecimal value of 0xC1480000. In memory, this value appears as follows:

	Index+0	Index+1	Index+2	Index+3
Contents	0xC1	0x48	0x00	0x00

Table 4-6: Floating Point Example

It is fairly simple to convert floating-point numbers to and from their hexadecimal storage equivalents. The following example demonstrates how this is done for the value -12.5 shown above.

The floating-point storage representation is not an intuitive format. To convert this to a floating-point number, the bits must be separated as specified in the floating-point number storage format table shown above. For example:

	Index+0	Index+1	Index+2	Index+3
Contents	SEEEEEEE	EMMMMMMM	MMMMMMMM	MMMMMMMM
Binary	11000001	01001000	00000000	00000000
Hexadecimal	0xC1	0x48	0x00	0x00

Table 4-7: Floating Point Example Breakdown

From this illustration, you can determine the following:

- The sign bit is 1, indicating a negative number.
- The exponent value is 10000010 binary or 130 decimal. Subtracting 127 from 130 leaves 3, which is the actual exponent.
- The mantissa appears as the following binary number: 10010000000000000000000

There is an understood binary point at the left of the mantissa that is always preceded by a 1. This digit is omitted from the stored form of the floating-point number. Adding 1 and the binary point to the beginning of the mantissa gives the following value:

1.10010000000000000000000

To adjust the mantissa for the exponent, move the decimal point to the left for negative exponent values or right for positive exponent values. Since the exponent is three, the mantissa is adjusted as follows:

1100.10000000000000000000

The result is a binary floating-point number. Binary digits to the left of the decimal point represent the power of two corresponding to their position. For example, 1100 represents (1 × 23) + (1 × 22) + (0 × 21) + (0 × 20), which is 12.

Binary digits to the right of the decimal point also represent the power of two corresponding to their position. However, the powers are negative. For example, .100... represents (1 × 2-1) + (0 × 2-2) + (0 × 2-3) + ... which equals .5.

The sum of these values is 12.5. Because the sign bit was set, this number should be negative. So, the hexadecimal value 0xC1480000 is -12.5.

CHAPTER 5
API Commands

This chapter provides a description of the application programming interface (API) commands used to communicate with the PS1/PS2 wireless sensor. Please have available all the included hardware and documentation that came with your sensor.

Introduction

There are many API commands used to communicate to the PS1/PS2 using a wireless base station product from IntelliSensing. The assumption is that 16-bit addressing mode is being used and therfore the details illustrate the use of 16-bit Transmit Request Data Frame Structures. If 64-bit addressing mode is desired, the Data Frame portion of the Data Frame Structure remains the same. The 64-bit Transmit Request Data Frame Structure description and content can be found in chapter "XBee™/XBee-PRO™ OEM RF Modules Product Manual" on page 77.

Measure Single Reading (MSR) Command - 0x01

Performs a single full measurement and returns all readings associated with the measurement.

MSR Command Data Frame

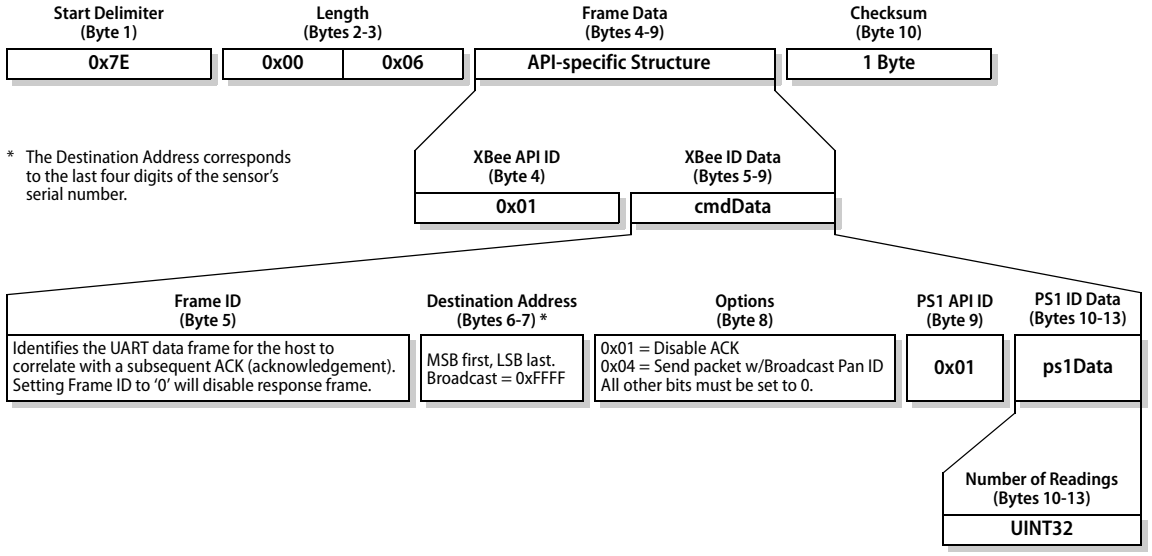
Start Delimiter (Byte 1)
Length (Bytes 2-3)
Frame Data (Bytes 4-9)
Checksum (Byte 10)
0x7E
0x00
0x06
API-specific Structure
1 Byte
* The Destination Address corresponds to the last four digits of the sensor's serial number.
XBee API ID (Byte 4)
XBee ID Data (Bytes 5-9)
0x01
cmdData
Frame ID (Byte 5)
Identifies the UART data frame for the host to correlate with a subsequent ACK (acknowledgement). Setting Frame ID to '0' will disable response frame.
Destination Address (Bytes 6-7) *
MSB first, LSB last. Broadcast = 0xFFFF
Options (Byte 8)
0x01 = Disable ACK
0x04 = Send packet w/Broadcast Pan ID
All other bits must be set to 0.
PS1 API ID (Byte 9)
0x01
PS1 ID Data (Bytes 10-13)
ps1Data
Number of Readings (Bytes 10-13)
UINT32

Figure 5-1: MSR Command Data Frame Structure

Byte Index	Data Type	Description
10	UINT32	Number of readings to measure. Each reading is retrurned in its own data packet. If this parameter is omitted, only one reading is measured.

Table 5-1: MMR Command Data Items

MSR Reply Data Frame

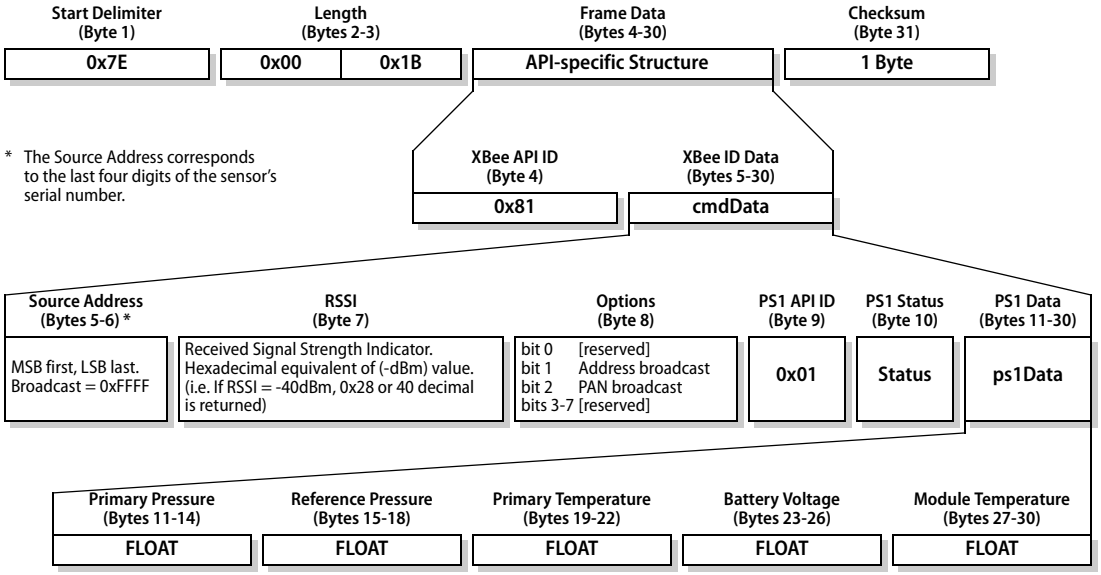

Figure 5-2: MSR Reply Data Frame Structure

Byte Index	Data Type	Description
10	UINT8	0x00 - Successful command status.
		0x01 - Bad command error.
11	FLOAT	Primary pressure expressed in engineering units of measure.
15	FLOAT	Internal reference pressure expressed in engineering units of measure.
19	FLOAT	Temperature of primary sensing element expressed in engineering units of measure.
23	FLOAT	Battery voltage expressed in volts.
27	FLOAT	Temperature of sensor engine module expressed in engineering units.

Table 5-2: MSR Reply Data Items

Several sensor control parameters will influence how the measurement is acquired and how the results are computed. These sensor control parameters and their values are described in the topic "Sensor Control Parameter (SCP) Command - 0xA0 / 0x20" on page 36.

Measure Multiple Reading (MMR) Command - 0x02

Performs a single full measurement as described in topic "Measure Single Reading (MSR) Command - 0x01" on page 30, followed by a several higher speed measurements containing only primary pressure results. All readings associated with the full measurement are first returned in its own data packet followed by one or more additional data packets each containing fifty (50) encoded primary pressure readings only.

MMR Command Data Frame

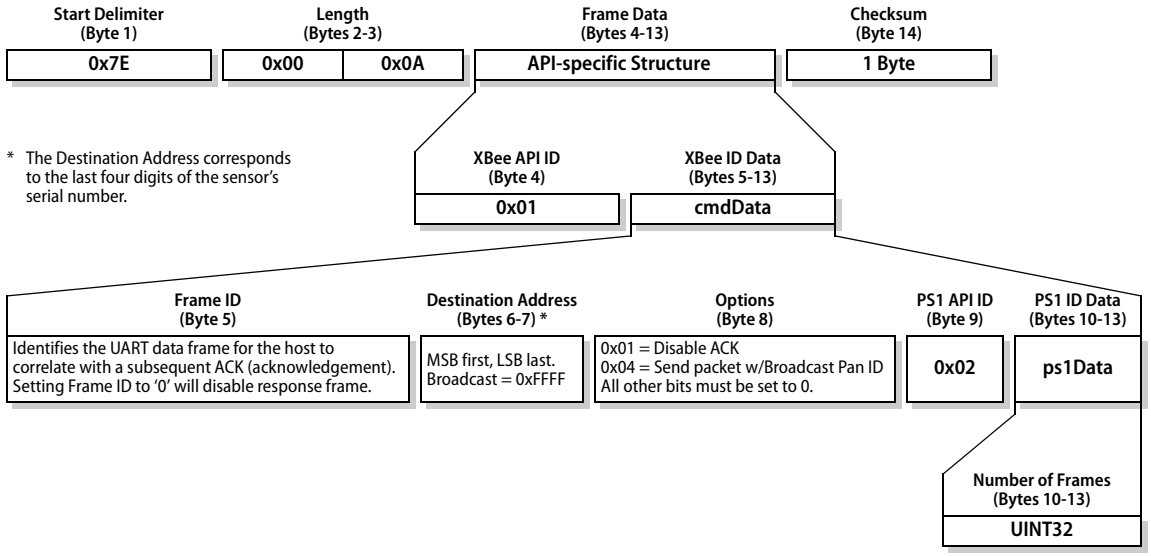
Start Delimiter (Byte 1)
0x7E
Length (Bytes 2-3)
0x00
0x0A
Frame Data (Bytes 4-13)
API-specific Structure
Checksum (Byte 14)
1 Byte
* The Destination Address corresponds to the last four digits of the sensor's serial number.
XBee API ID (Byte 4)
0x01
XBee ID Data (Bytes 5-13)
cmdData
Frame ID (Byte 5)
Identifies the UART data frame for the host to correlate with a subsequent ACK (acknowledgement). Setting Frame ID to '0' will disable response frame.
Destination Address (Bytes 6-7) *
MSB first, LSB last. Broadcast = 0xFFFF
Options (Byte 8)
0x01 = Disable ACK
0x04 = Send packet w/Broadcast Pan ID
All other bits must be set to 0.
PS1 API ID (Byte 9)
0x02
PS1 ID Data (Bytes 10-13)
ps1Data
Number of Frames (Bytes 10-13)
UINT32

Figure 5-3: MMR Command Data Frame Structure

Byte Index	Data Type	Description
10	UINT32	Number of fifty-reading groups to measure. Each group of fifty (50) readings is returned as a single data packet containing all fifty readings. If this parameter is omitted, only one group of readings is measured.

Table 5-3: MMR Command Data Items

MMR Reply Data Frame

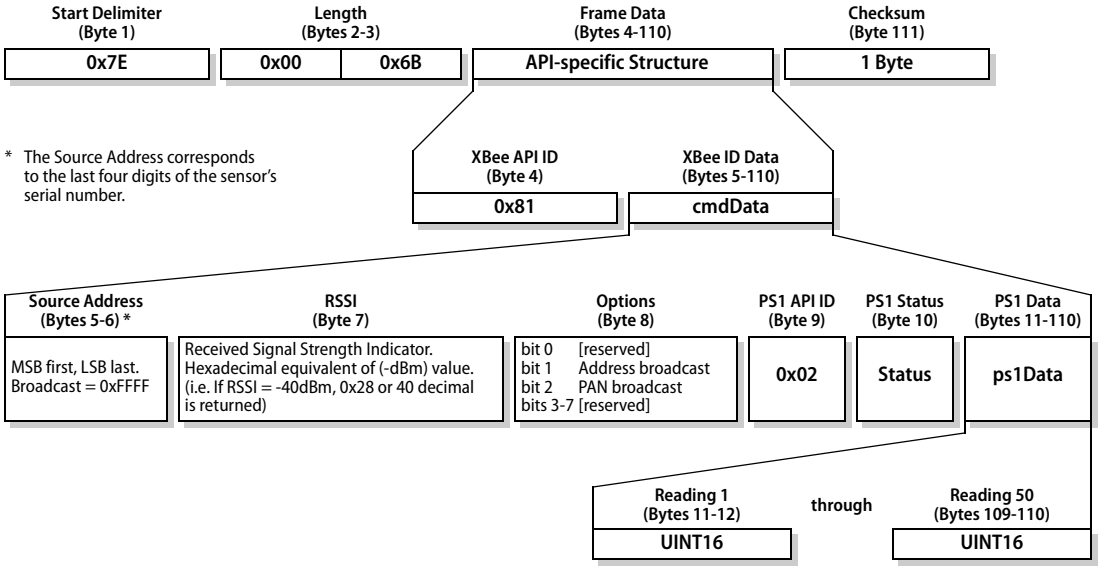

Figure 5-4: MMR Reply Data Frame Structure

Byte Index	Data Type	Description
10	UINT8	0x00 - Successful command status.
		0x01 - Bad command error.
		0x02 - Bad argument.
11	UINT16	1st pressure reading in group. Counts of 2,500 equals 0% of full scale range. Counts of 62,500 equals 100% of full scale range.
through		
109	UINT16	50th pressure reading in group.

Table 5-4: MMR Reply Data Items

Since pressure measurements that are normally formatted as floating point numbers are now represented as 16-bit integers, the pressure is calculated as follows:

$$pressure = \frac{counts - 2500}{60000} \times range$$

An example of how to calculate a single pressure that is represented as 5350 counts in a sensor having a pressure range of 1500 PSI is as follows:

$$pressure = \frac{5350 - 2500}{60000} \times 1500.0 = 0.0475 \times 1500.0 = 71.25$$

Measure Tare Offset (MTO) Command - 0x03

Performs a nulling operation on the primary pressure measurement.

MTO Command Data Frame

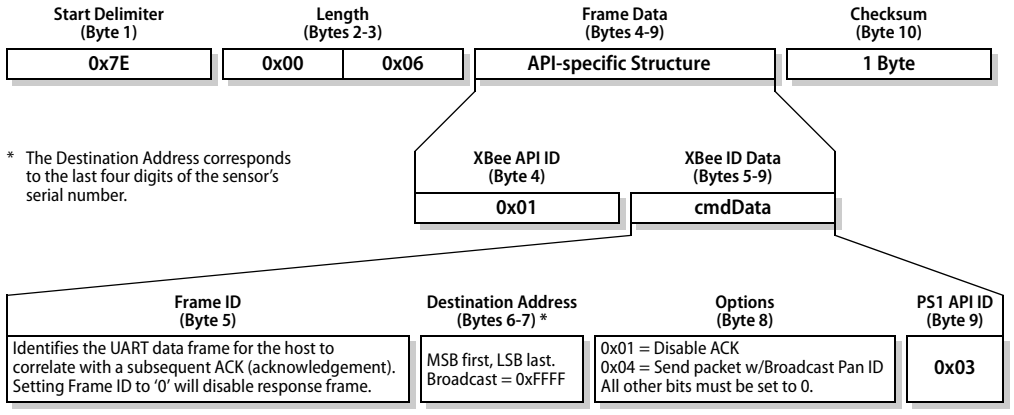
Start Delimiter (Byte 1)
Length (Bytes 2-3)
Frame Data (Bytes 4-9)
Checksum (Byte 10)
0x7E
0x00
0x06
API-specific Structure
1 Byte
* The Destination Address corresponds to the last four digits of the sensor's serial number.
XBee API ID (Byte 4)
XBee ID Data (Bytes 5-9)
0x01
cmdData
Frame ID (Byte 5)
Destination Address (Bytes 6-7) *
Options (Byte 8)
PS1 API ID (Byte 9)
Identifies the UART data frame for the host to correlate with a subsequent ACK (acknowledgement). Setting Frame ID to '0' will disable response frame.
MSB first, LSB last. Broadcast = 0xFFFF
0x01 = Disable ACK
0x04 = Send packet w/Broadcast Pan ID
All other bits must be set to 0.
0x03

Figure 5-5: MTO Command Data Frame Structure

This nulling operation involves the following steps:

1. Zero the Primary Pressure Offset parameter.
2. Perform a single full measurement.
3. Store the measured primary pressure to the Primary Pressure Offset parameter.

After the nulling process successfully completes, the next primary pressure measurement will be at or close to 0% full scale pressure.

NOTE

The sensor's factory lock protection system must be first unlocked before executing the MTO command. See the topic "Sensor Factory Unlock (SFU) Command - 0x28" on page 60 for a description on how to unlock the sensor control parameters.

MTO Reply Data Frame

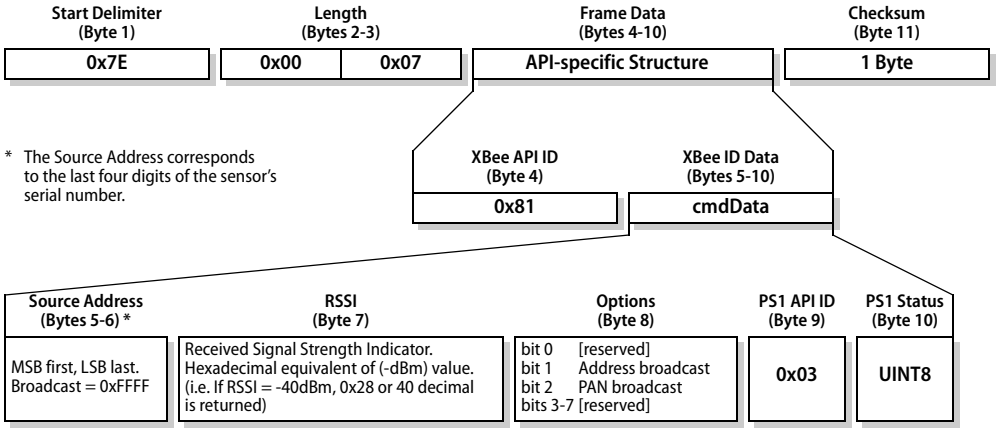
Start Delimiter (Byte 1)
0x7E
Length (Bytes 2-3)
0x00
0x07
Frame Data (Bytes 4-10)
API-specific Structure
Checksum (Byte 11)
1 Byte
* The Source Address corresponds to the last four digits of the sensor's serial number.
XBee API ID (Byte 4)
0x81
XBee ID Data (Bytes 5-10)
cmdData
Source Address (Bytes 5-6) *
MSB first, LSB last. Broadcast = 0xFFFF
RSSI (Byte 7)
Received Signal Strength Indicator. Hexadecimal equivalent of (-dBm) value. (i.e. If RSSI = -40dBm, 0x28 or 40 decimal is returned)
Options (Byte 8)
bit 0 [reserved]
bit 1 Address broadcast
bit 2 PAN broadcast
bits 3-7 [reserved]
PS1 API ID (Byte 9)
0x03
PS1 Status (Byte 10)
UINT8

Figure 5-6: MTO Reply Data Frame Structure

Byte Index	Data Type	Description
10	UINT8	0x00 - Successful command status.
		0x01 - Bad command error.
		0x03 - Factory settings locked.

Table 5-5: MTO Reply Data Items

CAUTION

All changes to the active Sensor Control Parameters are stored in RAM and will not persist if the battery is removed or if the sensor is reset as described in the topic "Sensor Reset (SR) Command - 0x22" on page 46. To save changed Sensor Control Parameters permanently, see the topic "Sensor Memory Save (SMS) Command - 0x27" on page 58.

Sensor Control Parameter (SCP) Command - 0xA0 / 0x20

Writes (0xA0) values to or reads (0x20) values from the sensor control parameters.

SCP-Write Command Data Frame

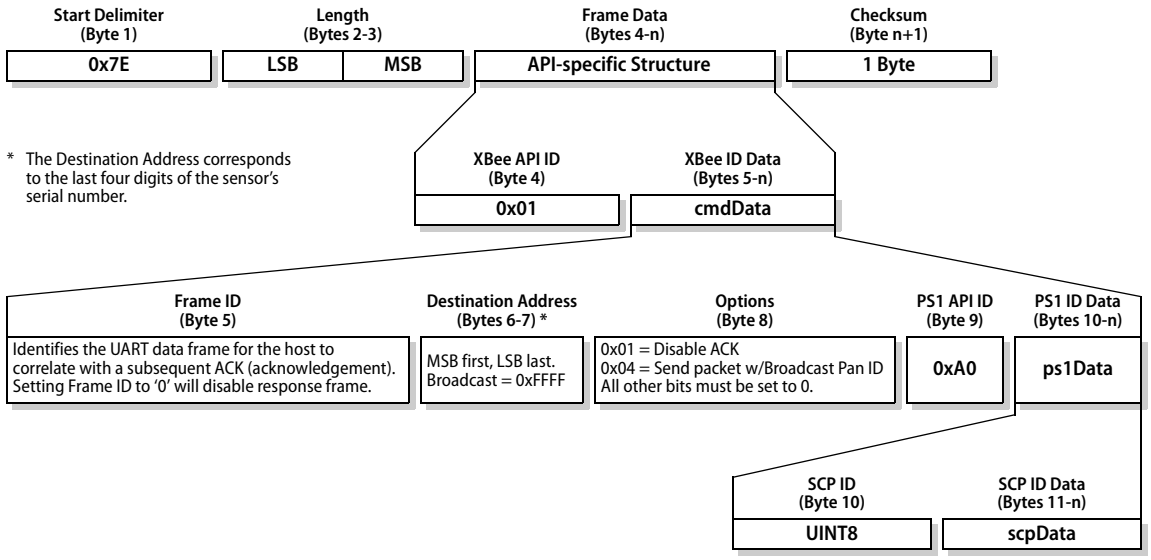
Start Delimiter (Byte 1)
Length (Bytes 2-3)
Frame Data (Bytes 4-n)
Checksum (Byte n+1)
0x7E
LSB
MSB
API-specific Structure
1 Byte
* The Destination Address corresponds to the last four digits of the sensor's serial number.
XBee API ID (Byte 4)
XBee ID Data (Bytes 5-n)
0x01
cmdData
Frame ID (Byte 5)
Destination Address (Bytes 6-7) *
Options (Byte 8)
PS1 API ID (Byte 9)
PS1 ID Data (Bytes 10-n)
Identifies the UART data frame for the host to correlate with a subsequent ACK (acknowledgement). Setting Frame ID to '0' will disable response frame.
MSB first, LSB last. Broadcast = 0xFFFF
0x01 = Disable ACK
0x04 = Send packet w/Broadcast Pan ID
All other bits must be set to 0.
0xA0
ps1Data
SCP ID (Byte 10)
SCP ID Data (Bytes 11-n)
UINT8
scpData

Figure 5-7: SCP-Write Command Data Frame Structure

Byte Index	Data Type	Description
10	UINT8	Sensor Control Parameter (SCP) Identifier as described in the table "Sensor Control Parameters" on page 40.
11-n	varies	Data specific to SCP Identifier.

Table 5-6: SCP-Write Command Data Items

See the table "Sensor Control Parameters" on page 40 for a list and description of SCP identifiers.

NOTE

The sensor's factory lock protection system must be first unlocked before writing values to the Sensor Control Parameters. See the topic "Sensor Factory Unlock (SFU) Command - 0x28" on page 60 for a description on how to unlock the sensor control parameters.

SCP-Write Reply Data Frame

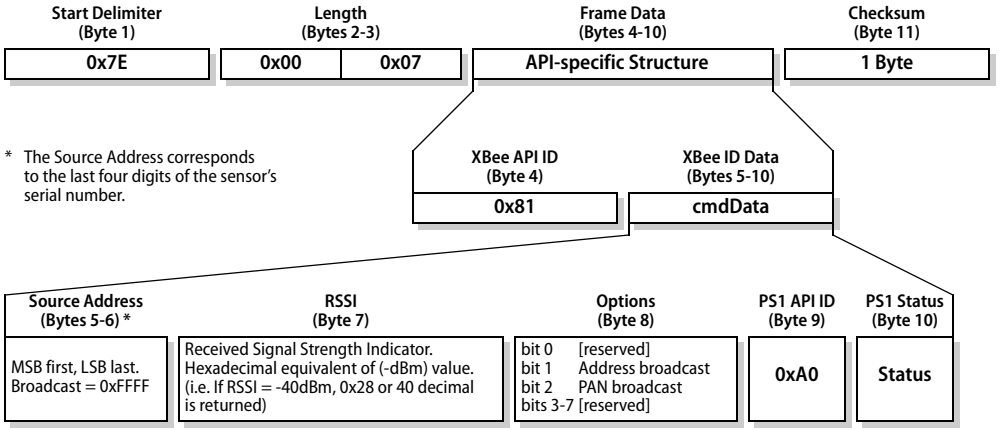
Start Delimiter (Byte 1)
0x7E
Length (Bytes 2-3)
0x00
0x07
Frame Data (Bytes 4-10)
API-specific Structure
Checksum (Byte 11)
1 Byte
* The Source Address corresponds to the last four digits of the sensor's serial number.
XBee API ID (Byte 4)
0x81
XBee ID Data (Bytes 5-10)
cmdData
Source Address (Bytes 5-6) *
MSB first, LSB last. Broadcast = 0xFFFF
RSSI (Byte 7)
Received Signal Strength Indicator. Hexadecimal equivalent of (-dBm) value. (i.e. If RSSI = -40dBm, 0x28 or 40 decimal is returned)
Options (Byte 8)
bit 0 [reserved]
bit 1 Address broadcast
bit 2 PAN broadcast
bits 3-7 [reserved]
PS1 API ID (Byte 9)
0xA0
PS1 Status (Byte 10)
Status

Figure 5-8: SCP-Write Reply Data Frame Structure

Byte Index	Data Type	Description
10	UINT8	0x00 - Successful command status.
		0x01 - Bad command error.
		0x02 - Bad argument.
		0x03 - Factory settings locked.

Table 5-7: SCP-Write Reply Data Items

CAUTION

All changes to the active Sensor Control Parameters are stored in RAM and will not persist if the battery is removed or if the sensor is reset as described in the topic "Sensor Reset (SR) Command - 0x22" on page 46. To save changed Sensor Control Parameters permanently, see the topic "Sensor Memory Save (SMS) Command - 0x27" on page 58.

SCP-Read Command Data Frame

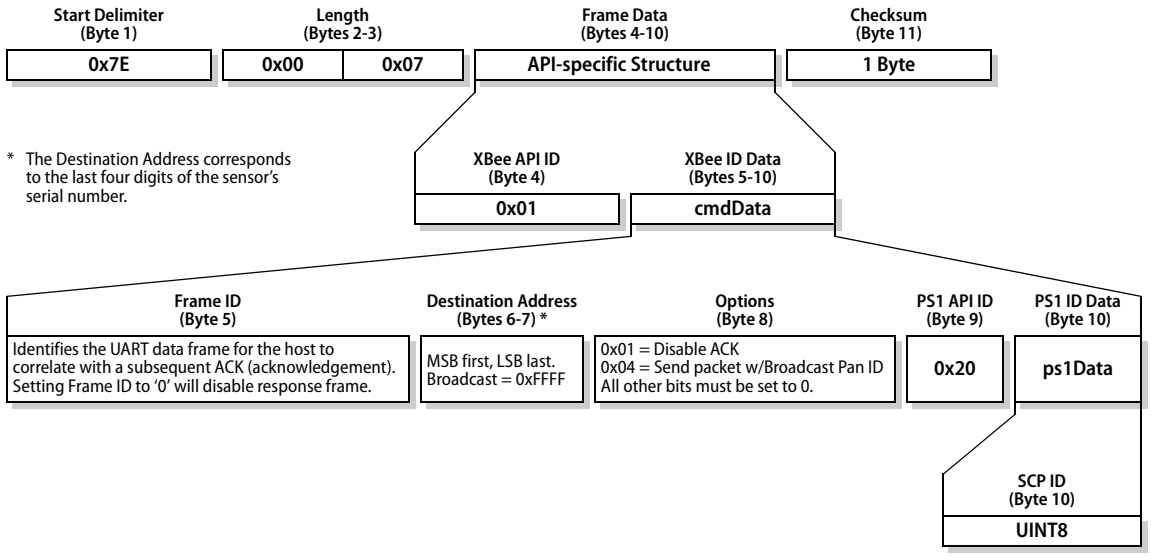
Start Delimiter (Byte 1)
0x7E
Length (Bytes 2-3)
0x00
0x07
Frame Data (Bytes 4-10)
API-specific Structure
Checksum (Byte 11)
1 Byte
* The Destination Address corresponds to the last four digits of the sensor's serial number.
XBee API ID (Byte 4)
0x01
XBee ID Data (Bytes 5-10)
cmdData
Frame ID (Byte 5)
Identifies the UART data frame for the host to correlate with a subsequent ACK (acknowledgement). Setting Frame ID to '0' will disable response frame.
Destination Address (Bytes 6-7) *
MSB first, LSB last. Broadcast = 0xFFFF
Options (Byte 8)
0x01 = Disable ACK
0x04 = Send packet w/Broadcast Pan ID
All other bits must be set to 0.
PS1 API ID (Byte 9)
0x20
PS1 ID Data (Byte 10)
ps1Data
SCP ID (Byte 10)
UINT8

Figure 5-9: SCP-Read Command Data Frame Structure

Byte Index	Data Type	Description
10	UINT8	Sensor Control Parameter (SCP) Identifier as described in the table "Sensor Control Parameters" on page 40.

Table 5-8: SCP-Read Command Data Items

See the table "Sensor Control Parameters" on page 40 for a list and description of SCP identifiers.

SCP-Read Reply Data Frame

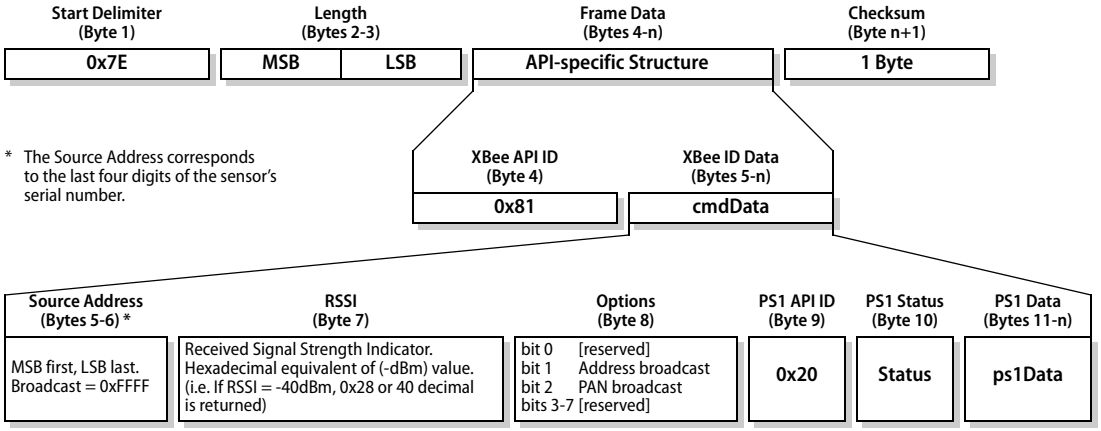
Start Delimiter (Byte 1)
0x7E
Length (Bytes 2-3)
MSB
LSB
Frame Data (Bytes 4-n)
API-specific Structure
Checksum (Byte n+1)
1 Byte
* The Source Address corresponds to the last four digits of the sensor's serial number.
XBee API ID (Byte 4)
0x81
XBee ID Data (Bytes 5-n)
cmdData
Source Address (Bytes 5-6) *
MSB first, LSB last. Broadcast = 0xFFFF
RSSI (Byte 7)
Received Signal Strength Indicator. Hexadecimal equivalent of (-dBm) value. (i.e. If RSSI = -40dBm, 0x28 or 40 decimal is returned)
Options (Byte 8)
bit 0 [reserved]
bit 1 Address broadcast
bit 2 PAN broadcast
bits 3-7 [reserved]
PS1 API ID (Byte 9)
0x20
PS1 Status (Byte 10)
Status
PS1 Data (Bytes 11-n)
ps1Data

Figure 5-10: SCP-Read Reply Data Frame Structure

Byte Index	Data Type	Description
10	UINT8	0x00 - Successful command status.
		0x01 - Bad command error.
		0x02 - Bad argument.
11-n	varies	Data specific to SCP Identifier.

Table 5-9: SCP-Read Reply Data Items

See the table "Sensor Control Parameters" on page 40 for a list and description of SCP identifiers.

Name	Identifier	Data Type	Comments (* default)
Serial Number	0x01	UINT32	The 16-bit source address of the sensor's XBee module is factory programmed with the two least significant bytes of the sensor's serial number.
Part Number	0x02	CHAR(15)	ASCII representation of part number.
Date of Manufacture	0x03	UINT32	byte 0 = Month
			byte 1 = Day
			byte 2 = Year (MSB)
			byte 3 = Year (LSB)
Date of Calibration	0x04	UINT32	byte 0 = Month
			byte 1 = Day
			byte 2 = Year (MSB)
			byte 3 = Year (LSB)
Customer Data	0x05	CHAR(20)	Any data up to 20 bytes long.
Decimation Ratio	0x06	UINT16	0x0013 to 0x07FF (default is 0x00BF). When using FAST filter type, the value of [DR + 1] must be divisable by 8.
Filter Type	0x07	UINT8	0x00 = SINC3 filter *
			0x01 = FAST filter
Pressure Units of Measure	0x08	UINT8	0x00 = Pounds per Square Inch (PSI) *
			0x01 = Inches of Mercury @ 0°C
			0x02 = Feet of Water @ 4°C
			0x03 = Kilopascals
			0x04 = Millibar
			0x05 = Torr
Temperature Units of Measure	0x09	UINT8	0x00 = Degrees Fahrenheit (°F) *
			0x01 = Degrees Celsius
Pressure Range	0x0A	FLOAT	Expressed in units of PSI.
Primary Pressure Offset	0x0B	FLOAT	Value is subtracted from measurement and is expressed in units of PSI.
Barometric Pressure Offset	0x0C	FLOAT	Value is subtracted from measurement and is expressed in units of PSI.
Primary Temperature Offset	0x0D	FLOAT	Value is subtracted from measurement and is expressed in units of °F.
New Battery Capacity	0x0E	FLOAT	Value is expressed in units of mAHr.

Table 5-10: Sensor Control Parameters

Name	Identifier	Data Type	Comments (* default)
Display Update Threshold	0x0F	FLOAT	0.0 to 100.0 (default is 1.0). A percentage of full scale pressure that constitutes a significant pressure variation worthy of displaying on integrated LCD.
Display Update Count	0x10	UINT16	0x0000 to 0xFFFF (default is 0x0001). The number of times the measured pressure must vary by the Display Update Threshold in order to update the LCD.

Table 5-10: Sensor Control Parameters

Sensor Control Parameter Details

Serial Number

While the serial number field accommodates a UINT32 value, the two least significant bytes have special meaning. The values of these two bytes are programmed into the *MY* 16-bit address field located in the sensor's XBee module. This allows for quick identification of the sensor's 16-bit address when setting up a wireless base station for communication.

Customer Data

Any customer information including ASCII, Extended ASCII or binary data can be stored in this field.

Decimation Ratio

The decimation ratio of the sensor's analog-to-digital converter (ADC) filters is selected by the decimation ratio value (DR). The decimation ratio determines how many modulator samples are used to generate a single output word. The ADC output word rate is equal to the modulator sampling rate divided by the decimation ratio. Higher decimation ratios will produce lower-noise results over a longer conversion period. The minimum decimation ratio value is 19.

NOTE

When using the FAST filter type, the decimation ratio value must be set so that the sum of [Decimation Ratio value + 1] must be a multiple of 8.

There are five channels of data acquisition required to accurately calculate the primary pressure:

1. Primary pressure sensing element deflection.
2. Internal barometric pressure sensor output.
3. Primary pressure sensing element temperature.
4. Battery voltage.
5. Sensor engine module temperature.

Each channel is sampled once or three times, depending on the setting of the filter type as explained in the topic "Filter Type" on page 42. The conversion period (in seconds) of each sample is calculated as follows:

$$period = \frac{(DR + 1) \times 128}{2.4576 \times 10^6}$$

Filter Type

The ADC's digital filter gives two options for output: FAST and SINC3. The FAST filter uses results from only the current conversion cycle or period, while the SINC3 filter uses three conversion cycles. The fast filter output reacts more quickly to changes on the analog input, while the SINC3 filter output produces lower-noise results. Additionally, the SINC3 filter is designed to reject 50 and 60 Hz frequencies. When it is necessary to respond quickly to signal changes, the FAST filter should be used. In most cases, the SINC3 filter is used for best noise performance.

New Battery Capacity

This value is programmed with the mAhr capacity rating of the replacement battery that will be used with the sensor. The battery capacity of the battery shipped with the sensor is programmed at the factory and will not require change if the same replacement battery type is used. The remaining battery life is available for query as explained in the topic "Sensor Battery Life (SBL) Command - 0x29" on page 62. The correct energy capacity of a new battery is required for accurate calculation.

Display Update Threshold

This parameter is related only to sensors having an integrated cholesteric liquid crystal display (ChLCD). Since the ChLCD consumes energy only when changing the information being displayed, the display update threshold value represents the minimum percentage of full scale pressure that constitutes a significant pressure change worthy of displaying. This parameter works in conjuction with the parameter "Display Update Count" on page 42. When the consecutive number of times the update threshold has been met equals the display update count, the ChLCD is updated.

Display Update Count

This parameter is related only to sensors having an integrated cholesteric liquid crystal display (ChLCD). See the topic "Display Update Threshold" on page 42 for a description of this parameter.

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Sensor Firmware Version (SFV) Command - 0x21

Returns the Sensor Engine's firmware version number.

SFV Command Data Frame

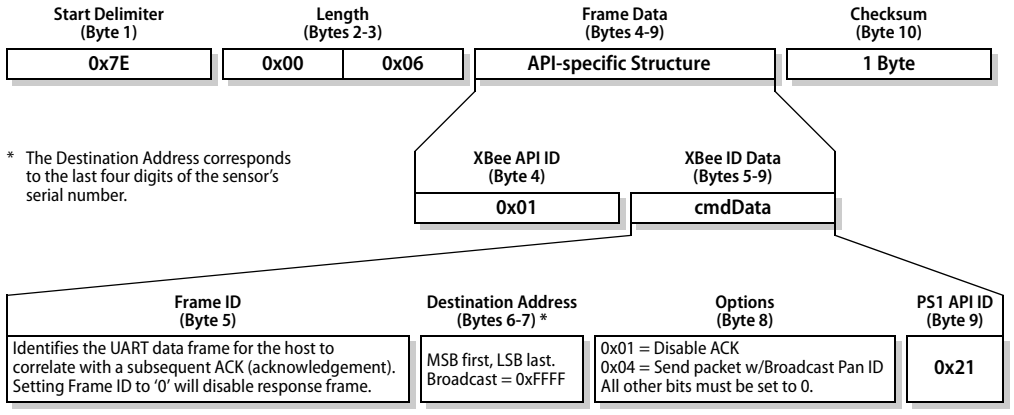
Start Delimiter (Byte 1)
Length (Bytes 2-3)
Frame Data (Bytes 4-9)
Checksum (Byte 10)
0x7E
0x00
0x06
API-specific Structure
1 Byte
* The Destination Address corresponds to the last four digits of the sensor's serial number.
XBee API ID (Byte 4)
XBee ID Data (Bytes 5-9)
0x01
cmdData
Frame ID (Byte 5)
Destination Address (Bytes 6-7) *
Options (Byte 8)
PS1 API ID (Byte 9)
Identifies the UART data frame for the host to correlate with a subsequent ACK (acknowledgement). Setting Frame ID to '0' will disable response frame.
MSB first, LSB last. Broadcast = 0xFFFF
0x01 = Disable ACK
0x04 = Send packet w/Broadcast Pan ID
All other bits must be set to 0.
0x21

Figure 5-11: SFV Command Data Frame Structure

The firmware and hardware versions of the XBee module can be queried using the "Radio AT (RAT) Command - 0x42" on page 68.

SFV Reply Data Frame

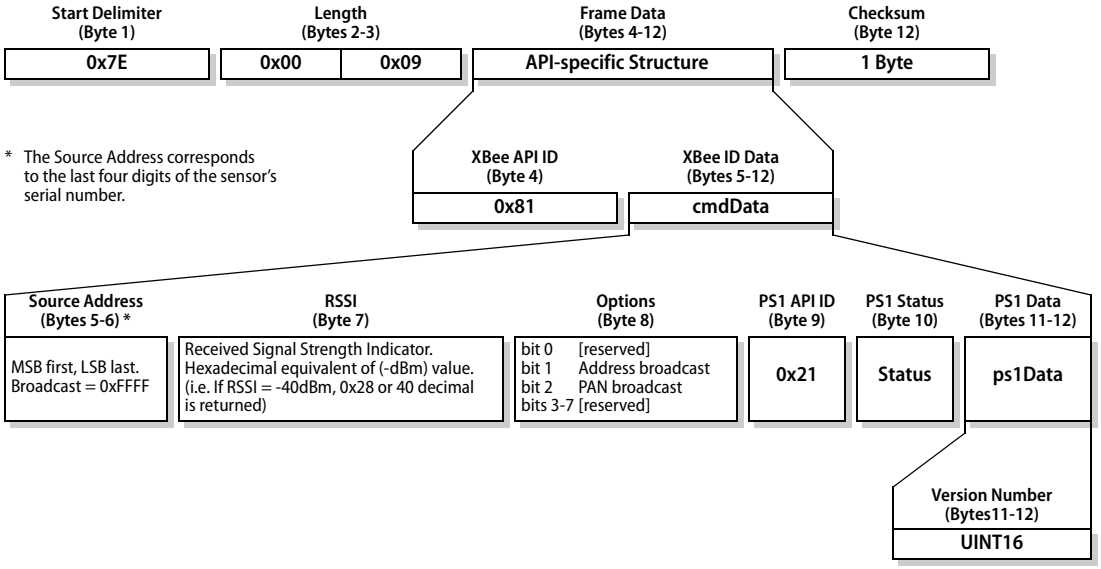

Figure 5-12: SFV Reply Data Frame Structure

Byte Index	Data Type	Description
10	UINT8	0x00 - Successful command status.
		0x01 - Bad command error.
11	UINT16	Firmware version number.

Table 5-11: SFV Reply Data Items

Sensor Reset (SR) Command - 0x22

Resets the Sensor Engine.

SR Command Data Frame

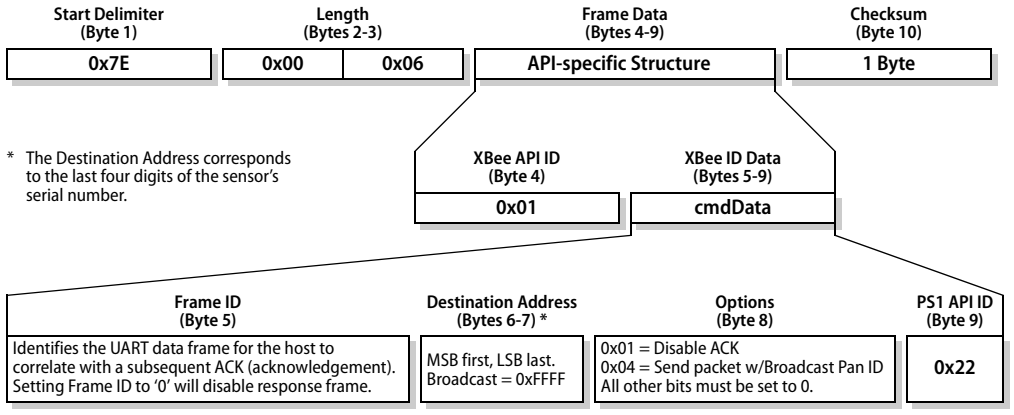
Start Delimiter (Byte 1)
Length (Bytes 2-3)
Frame Data (Bytes 4-9)
Checksum (Byte 10)
0x7E
0x00
0x06
API-specific Structure
1 Byte
* The Destination Address corresponds to the last four digits of the sensor's serial number.
XBee API ID (Byte 4)
XBee ID Data (Bytes 5-9)
0x01
cmdData
Frame ID (Byte 5)
Destination Address (Bytes 6-7) *
Options (Byte 8)
PS1 API ID (Byte 9)
Identifies the UART data frame for the host to correlate with a subsequent ACK (acknowledgement). Setting Frame ID to '0' will disable response frame.
MSB first, LSB last. Broadcast = 0xFFFF
0x01 = Disable ACK
0x04 = Send packet w/Broadcast Pan ID
All other bits must be set to 0.
0x22

Figure 5-13: SR Command Data Frame Structure

CAUTION

All changes to the active Sensor Control Parameters and all queued commands are stored in RAM and will not persist if the battery is removed or if the sensor is reset as described in the topic "Sensor Reset (SR) Command - 0x22" on page 46. To save changed Sensor Control Parameters permanently, see the topic "Sensor Memory Save (SMS) Command - 0x27" on page 58.

SR Reply Data Frame

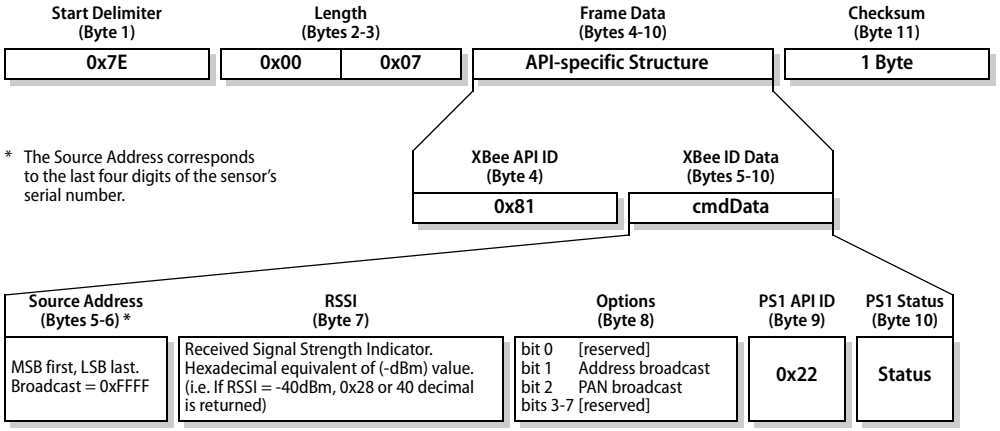

Figure 5-14: SR Reply Data Frame Structure

Byte Index	Data Type	Description
10	UINT8	0x00 - Successful command status.
		0x01 - Bad command error.

Table 5-12: SR Reply Data Items

The SR Reply Data Frame is returned before the sensor is reset.

Sensor Queue Configuration (SQC) Command - 0xA3 / 0x23

Writes (0xA3) a command to or reads (0x23) a command from a command queue slot.

SQC-Write Command Data Frame

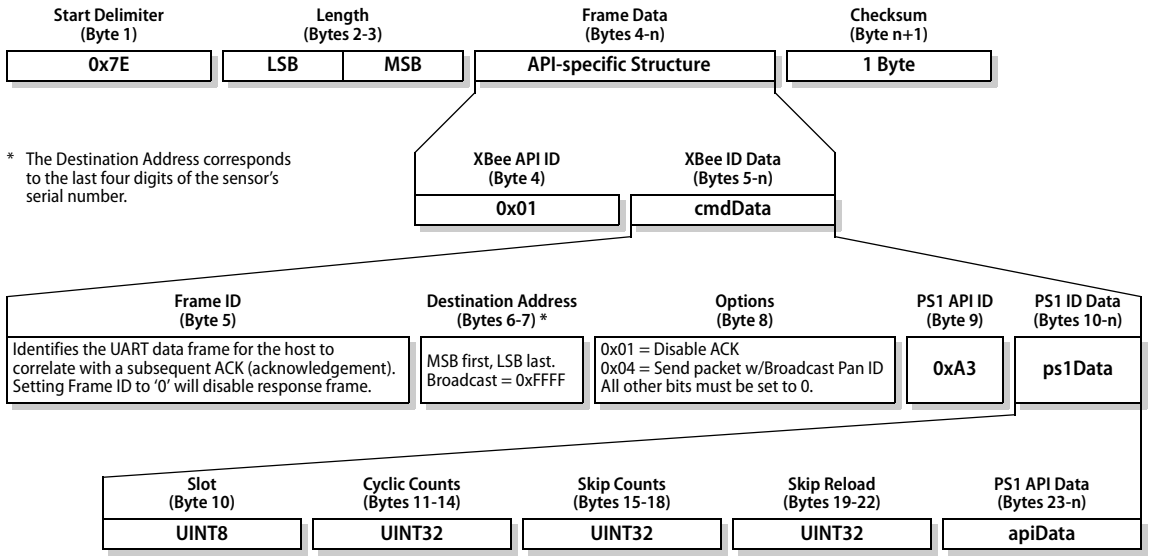
Start Delimiter (Byte 1)
Length (Bytes 2-3)
Frame Data (Bytes 4-n)
Checksum (Byte n+1)
0x7E
LSB
MSB
API-specific Structure
1 Byte
* The Destination Address corresponds to the last four digits of the sensor's serial number.
XBee API ID (Byte 4)
XBee ID Data (Bytes 5-n)
0x01
cmdData
Frame ID (Byte 5)
Destination Address (Bytes 6-7) *
Options (Byte 8)
PS1 API ID (Byte 9)
PS1 ID Data (Bytes 10-n)
Identifies the UART data frame for the host to correlate with a subsequent ACK (acknowledgement). Setting Frame ID to '0' will disable response frame.
MSB first, LSB last. Broadcast = 0xFFFF
0x01 = Disable ACK
0x04 = Send packet w/Broadcast Pan ID
All other bits must be set to 0.
0xA3
ps1Data
Slot (Byte 10)
Cyclic Counts (Bytes 11-14)
Skip Counts (Bytes 15-18)
Skip Reload (Bytes 19-22)
PS1 API Data (Bytes 23-n)
UINT8
UINT32
UINT32
UINT32
apiData

Figure 5-15: SQC-Write Command Data Frame Structure

Byte Index	Data Type	Description
10	UINT8	Slot number 0x00 to 0x04.
11	UINT32	Cyclic counts remaining. The value 0xFFFFFFFF will not decrease the remaining count.
15	UINT32	Skip cycle counts remaining.
19	UINT32	Skip cycle counts reload value. The value 0x00000000 will prevent cycle skipping.
23-n	varies	The API ID and all data for one PS1/PS2 command.

Table 5-13: SQC-Write Command Data Items

NOTE

The sensor's factory lock protection system must be first unlocked before writing command to a command queue slot. See the topic "Sensor Factory Unlock (SFU) Command - 0x28" on page 60 for a description on how to unlock the sensor control parameters.

SQC-Write Reply Data Frame

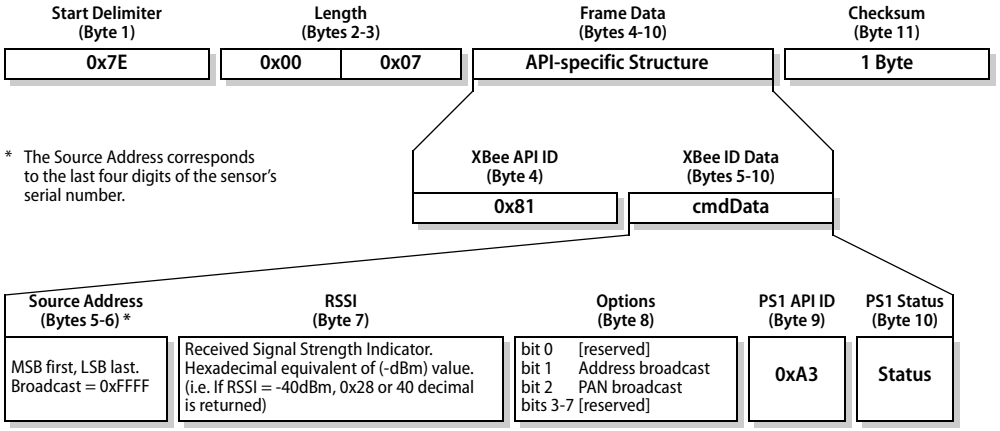
Start Delimiter (Byte 1)
0x7E
Length (Bytes 2-3)
0x00
0x07
Frame Data (Bytes 4-10)
API-specific Structure
Checksum (Byte 11)
1 Byte
* The Source Address corresponds to the last four digits of the sensor's serial number.
XBee API ID (Byte 4)
0x81
XBee ID Data (Bytes 5-10)
cmdData
Source Address (Bytes 5-6) *
MSB first, LSB last. Broadcast = 0xFFFF
RSSI (Byte 7)
Received Signal Strength Indicator. Hexadecimal equivalent of (-dBm) value. (i.e. If RSSI = -40dBm, 0x28 or 40 decimal is returned)
Options (Byte 8)
bit 0 [reserved]
bit 1 Address broadcast
bit 2 PAN broadcast
bits 3-7 [reserved]
PS1 API ID (Byte 9)
0xA3
PS1 Status (Byte 10)
Status

Figure 5-16: SQC-Write Reply Data Frame Structure

Byte Index	Data Type	Description
10	UINT8	0x00 - Successful command status.
		0x01 - Bad command error.
		0x02 - Bad argument.
		0x03 - Factory settings locked.

Table 5-14: SQC-Write Reply Data Items

CAUTION

All queued commands are stored in RAM and will not persist if the battery is removed or if the sensor is reset as described in the topic "Sensor Reset (SR) Command - 0x22" on page 46.

SQC-Read Command Data Frame

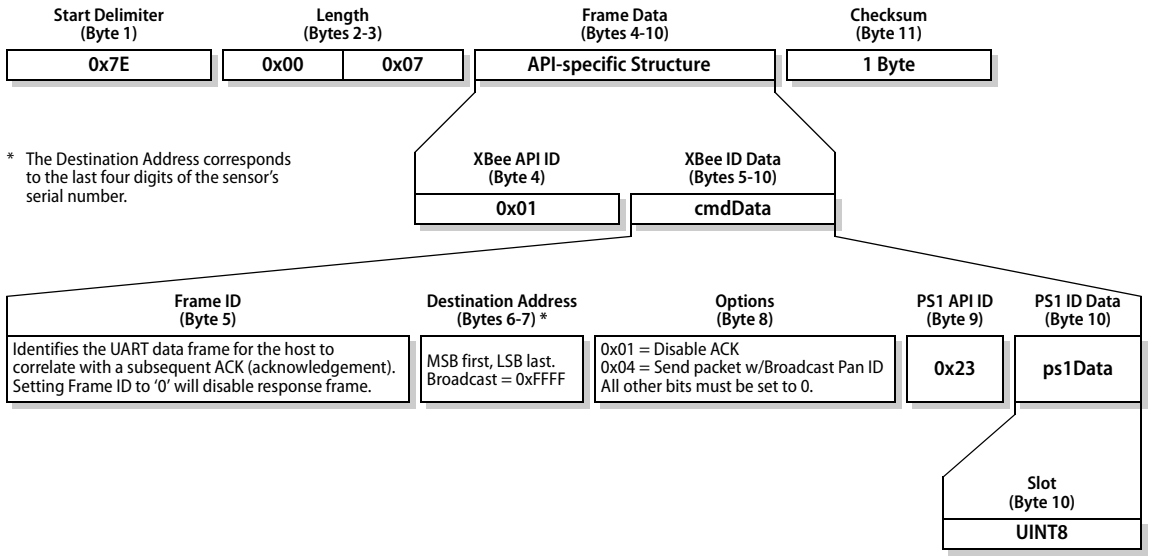
Start Delimiter (Byte 1)
0x7E
Length (Bytes 2-3)
0x00
0x07
Frame Data (Bytes 4-10)
API-specific Structure
Checksum (Byte 11)
1 Byte
* The Destination Address corresponds to the last four digits of the sensor's serial number.
XBee API ID (Byte 4)
0x01
XBee ID Data (Bytes 5-10)
cmdData
Frame ID (Byte 5)
Identifies the UART data frame for the host to correlate with a subsequent ACK (acknowledgement). Setting Frame ID to '0' will disable response frame.
Destination Address (Bytes 6-7) *
MSB first, LSB last. Broadcast = 0xFFFF
Options (Byte 8)
0x01 = Disable ACK
0x04 = Send packet w/Broadcast Pan ID
All other bits must be set to 0.
PS1 API ID (Byte 9)
0x23
PS1 ID Data (Byte 10)
ps1Data
Slot (Byte 10)
UINT8

Figure 5-17: SQC-Read Command Data Frame Structure

Byte Index	Data Type	Description
10	UINT8	Slot number 0x00 to 0x04.

Table 5-15: SQC-Read Command Data Items

SQC-Read Reply Data Frame

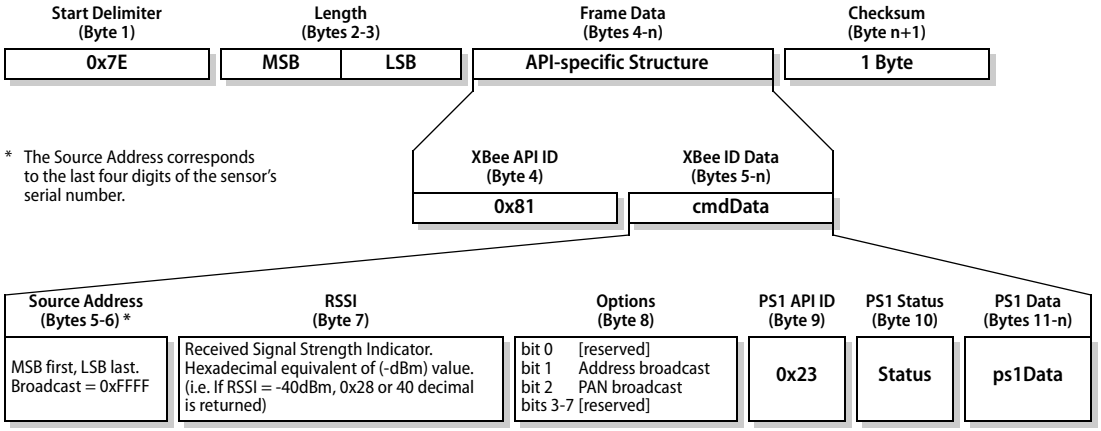
Start Delimiter (Byte 1)
0x7E
Length (Bytes 2-3)
MSB
LSB
Frame Data (Bytes 4-n)
API-specific Structure
Checksum (Byte n+1)
1 Byte
* The Source Address corresponds to the last four digits of the sensor's serial number.
XBee API ID (Byte 4)
0x81
XBee ID Data (Bytes 5-n)
cmdData
Source Address (Bytes 5-6) *
MSB first, LSB last. Broadcast = 0xFFFF
RSSI (Byte 7)
Received Signal Strength Indicator. Hexadecimal equivalent of (-dBm) value. (i.e. If RSSI = -40dBm, 0x28 or 40 decimal is returned)
Options (Byte 8)
bit 0 [reserved]
bit 1 Address broadcast
bit 2 PAN broadcast
bits 3-7 [reserved]
PS1 API ID (Byte 9)
0x23
PS1 Status (Byte 10)
Status
PS1 Data (Bytes 11-n)
ps1Data

Figure 5-18: SQC-Read Reply Data Frame Structure

Byte Index	Data Type	Description
10	UINT8	0x00 - Successful command status.
		0x01 - Bad command error.
		0x02 - Bad argument.
11-n	varies	Data specific to SCP Identifier.

Table 5-16: SQC-Read Reply Data Items

CAUTION

All queued commands are stored in RAM and will not persist if the battery is removed or if the sensor is reset as described in the topic "Sensor Reset (SR) Command - 0x22" on page 46.

Sensor Queue Start (SQS) Command - 0x24

Enables the processing of queued commands.

SQS Command Data Frame

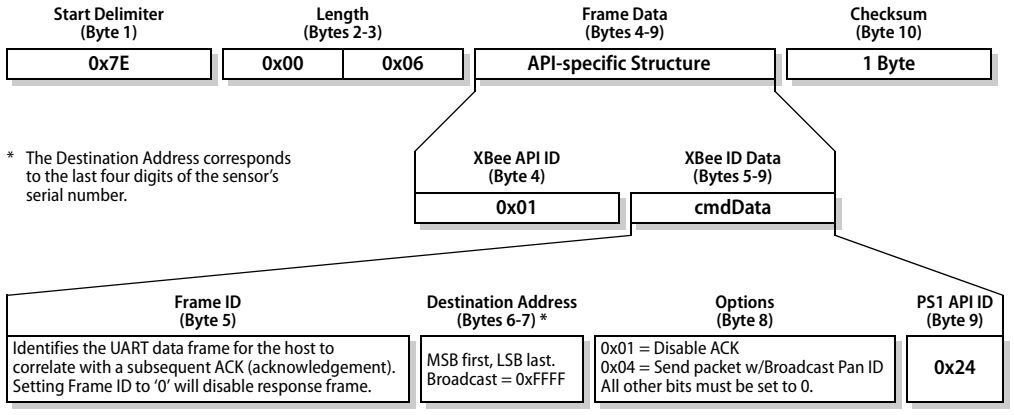
Start Delimiter (Byte 1)
Length (Bytes 2-3)
Frame Data (Bytes 4-9)
Checksum (Byte 10)
0x7E
0x00
0x06
API-specific Structure
1 Byte
* The Destination Address corresponds to the last four digits of the sensor's serial number.
XBee API ID (Byte 4)
XBee ID Data (Bytes 5-9)
0x01
cmdData
Frame ID (Byte 5)
Destination Address (Bytes 6-7) *
Options (Byte 8)
PS1 API ID (Byte 9)
Identifies the UART data frame for the host to correlate with a subsequent ACK (acknowledgement). Setting Frame ID to '0' will disable response frame.
MSB first, LSB last. Broadcast = 0xFFFF
0x01 = Disable ACK
0x04 = Send packet w/Broadcast Pan ID
All other bits must be set to 0.
0x24

Figure 5-19: SQS Command Data Frame Structure

SQS Reply Data Frame

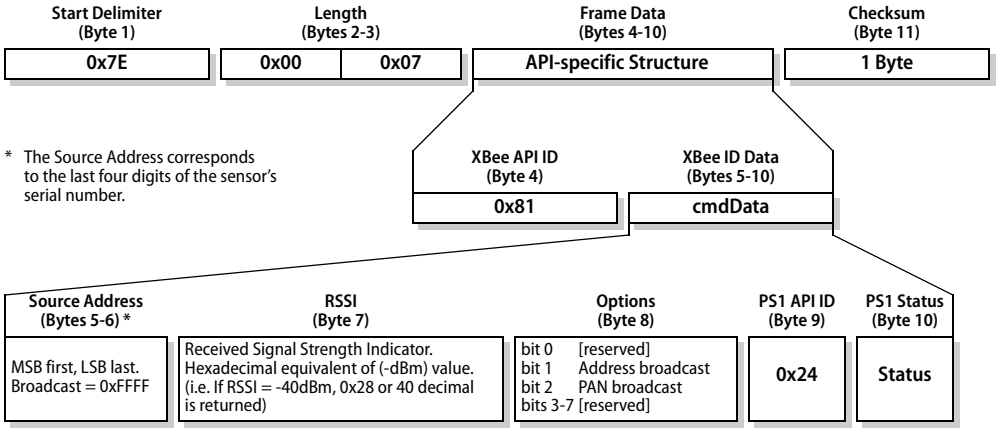
Start Delimiter (Byte 1)
0x7E
Length (Bytes 2-3)
0x00
0x07
Frame Data (Bytes 4-10)
API-specific Structure
Checksum (Byte 11)
1 Byte
* The Source Address corresponds to the last four digits of the sensor's serial number.
XBee API ID (Byte 4)
0x81
XBee ID Data (Bytes 5-10)
cmdData
Source Address (Bytes 5-6) *
MSB first, LSB last. Broadcast = 0xFFFF
RSSI (Byte 7)
Received Signal Strength Indicator. Hexadecimal equivalent of (-dBm) value. (i.e. If RSSI = -40dBm, 0x28 or 40 decimal is returned)
Options (Byte 8)
bit 0 [reserved]
bit 1 Address broadcast
bit 2 PAN broadcast
bits 3-7 [reserved]
PS1 API ID (Byte 9)
0x24
PS1 Status (Byte 10)
Status

Figure 5-20: SQS Reply Data Frame Structure

Byte Index	Data Type	Description
10	UINT8	0x00 - Successful command status.
		0x01 - Bad command error.

Table 5-17: SQS Reply Data Items

Sensor Queue Stop (SQP) Command - 0x25

Disables the processing of queued commands.

SQS Command Data Frame

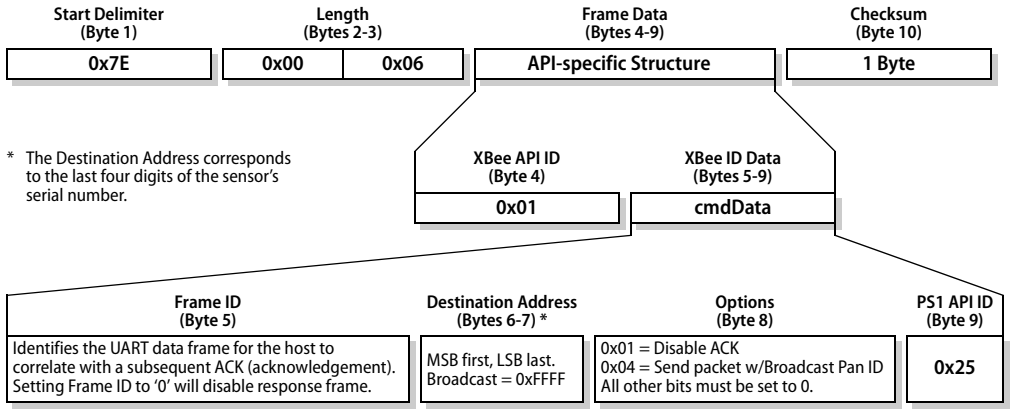
Start Delimiter (Byte 1)
Length (Bytes 2-3)
Frame Data (Bytes 4-9)
Checksum (Byte 10)
0x7E
0x00
0x06
API-specific Structure
1 Byte
* The Destination Address corresponds to the last four digits of the sensor's serial number.
XBee API ID (Byte 4)
XBee ID Data (Bytes 5-9)
0x01
cmdData
Frame ID (Byte 5)
Destination Address (Bytes 6-7) *
Options (Byte 8)
PS1 API ID (Byte 9)
Identifies the UART data frame for the host to correlate with a subsequent ACK (acknowledgement). Setting Frame ID to '0' will disable response frame.
MSB first, LSB last. Broadcast = 0xFFFF
0x01 = Disable ACK
0x04 = Send packet w/Broadcast Pan ID
All other bits must be set to 0.
0x25

Figure 5-21: SQP Command Data Frame Structure

SQP Reply Data Frame

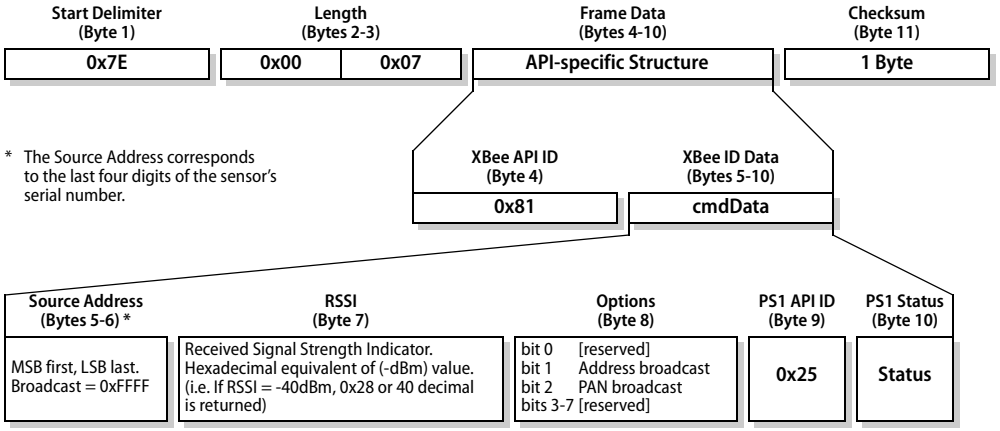

Figure 5-22: SQS Reply Data Frame Structure

Byte Index	Data Type	Description
10	UINT8	0x00 - Successful command status.
		0x01 - Bad command error.

Table 5-18: SQP Reply Data Items

Sensor Save Enable (SSE) Command - 0x26

Enables the saving of data in RAM to FLASH memory.

SSE Command Data Frame

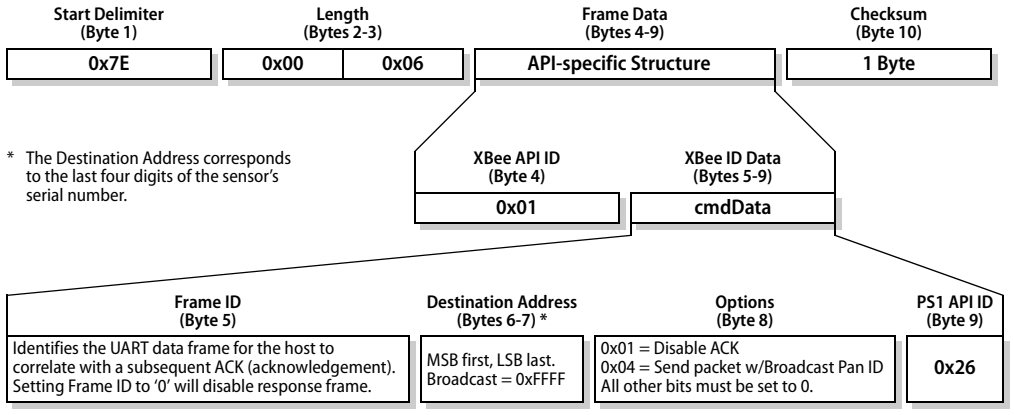
Start Delimiter (Byte 1)
Length (Bytes 2-3)
Frame Data (Bytes 4-9)
Checksum (Byte 10)
0x7E
0x00
0x06
API-specific Structure
1 Byte
* The Destination Address corresponds to the last four digits of the sensor's serial number.
XBee API ID (Byte 4)
XBee ID Data (Bytes 5-9)
0x01
cmdData
Frame ID (Byte 5)
Destination Address (Bytes 6-7) *
Options (Byte 8)
PS1 API ID (Byte 9)
Identifies the UART data frame for the host to correlate with a subsequent ACK (acknowledgement). Setting Frame ID to '0' will disable response frame.
MSB first, LSB last. Broadcast = 0xFFFF
0x01 = Disable ACK
0x04 = Send packet w/Broadcast Pan ID
All other bits must be set to 0.
0x26

Figure 5-23: SSE Command Data Frame Structure

The save-enabled state of the sensor remains only up until the next command is executed, which will most likely be the "Sensor Memory Save (SMS) Command - 0x27" on page 58. The SSE command is designed to prevent the accidental saving of data by requiring this extra step.

SSE Reply Data Frame

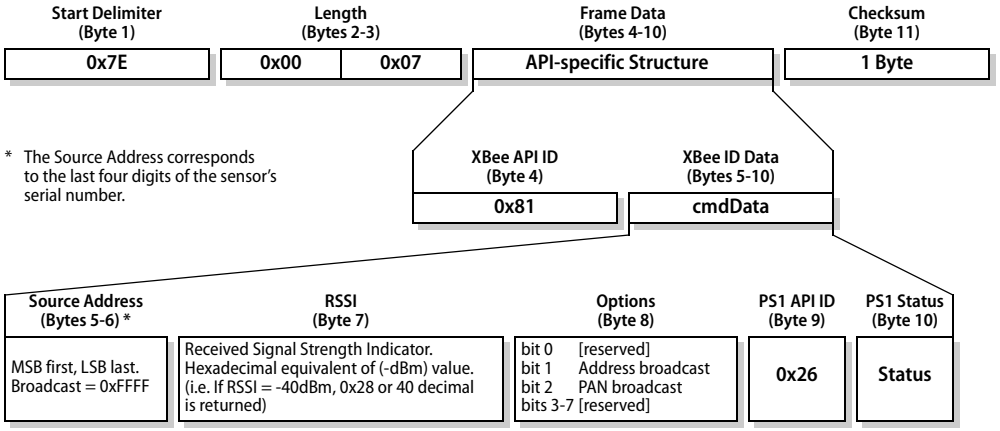

Figure 5-24: SSE Reply Data Frame Structure

Byte Index	Data Type	Description
10	UINT8	0x00 - Successful command status.
		0x01 - Bad command error.

Table 5-19: SSE Reply Data Items

Sensor Memory Save (SMS) Command - 0x27

Saves the data in RAM to FLASH memory.

SMS Command Data Frame

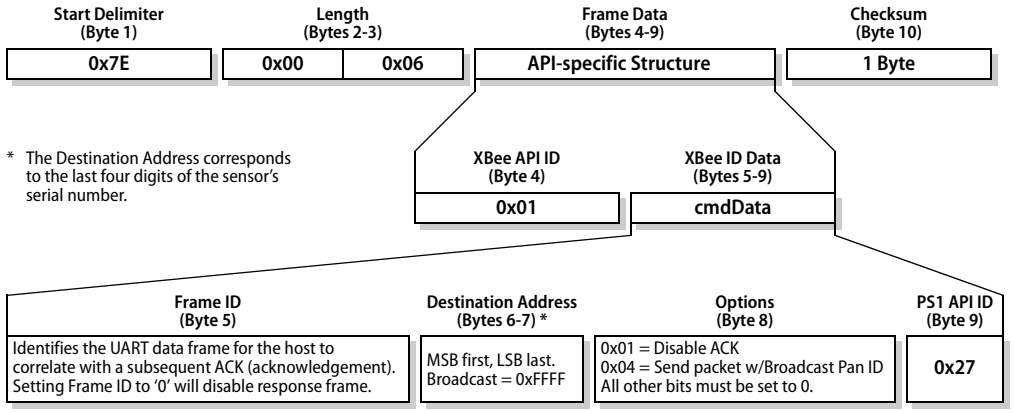
Start Delimiter (Byte 1)
Length (Bytes 2-3)
Frame Data (Bytes 4-9)
Checksum (Byte 10)
0x7E
0x00
0x06
API-specific Structure
1 Byte
* The Destination Address corresponds to the last four digits of the sensor's serial number.
XBee API ID (Byte 4)
XBee ID Data (Bytes 5-9)
0x01
cmdData
Frame ID (Byte 5)
Destination Address (Bytes 6-7) *
Options (Byte 8)
PS1 API ID (Byte 9)
Identifies the UART data frame for the host to correlate with a subsequent ACK (acknowledgement). Setting Frame ID to '0' will disable response frame.
MSB first, LSB last. Broadcast = 0xFFFF
0x01 = Disable ACK
0x04 = Send packet w/Broadcast Pan ID
All other bits must be set to 0.
0x27

Figure 5-25: SMS Command Data Frame Structure

NOTE

The sensor's FLASH memory is protected from being written to. See the topic "Sensor Save Enable (SSE) Command - 0x26" on page 56 for a description on how to enable the save command.

SMS Reply Data Frame

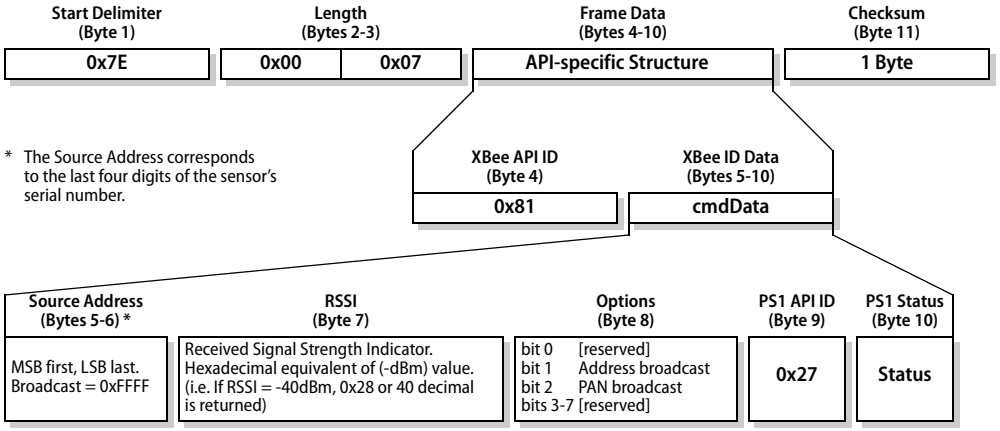
Start Delimiter (Byte 1)
0x7E
Length (Bytes 2-3)
0x00
0x07
Frame Data (Bytes 4-10)
API-specific Structure
Checksum (Byte 11)
1 Byte
* The Source Address corresponds to the last four digits of the sensor's serial number.
XBee API ID (Byte 4)
0x81
XBee ID Data (Bytes 5-10)
cmdData
Source Address (Bytes 5-6) *
MSB first, LSB last. Broadcast = 0xFFFF
RSSI (Byte 7)
Received Signal Strength Indicator. Hexadecimal equivalent of (-dBm) value. (i.e. If RSSI = -40dBm, 0x28 or 40 decimal is returned)
Options (Byte 8)
bit 0 [reserved]
bit 1 Address broadcast
bit 2 PAN broadcast
bits 3-7 [reserved]
PS1 API ID (Byte 9)
0x27
PS1 Status (Byte 10)
Status

Figure 5-26: SMS Reply Data Frame Structure

Byte Index	Data Type	Description
10	UINT8	0x00 - Successful command status.
		0x01 - Bad command error.

Table 5-20: SMS Reply Data Items

Sensor Factory Unlock (SFU) Command - 0x28

Enables the overwriting of data in RAM.

SFU Command Data Frame

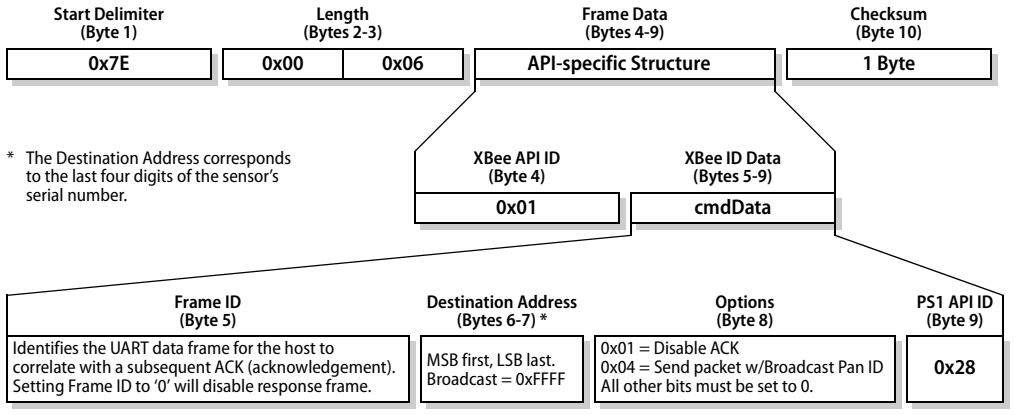
Start Delimiter (Byte 1)
Length (Bytes 2-3)
Frame Data (Bytes 4-9)
Checksum (Byte 10)
0x7E
0x00
0x06
API-specific Structure
1 Byte
* The Destination Address corresponds to the last four digits of the sensor's serial number.
XBee API ID (Byte 4)
XBee ID Data (Bytes 5-9)
0x01
cmdData
Frame ID (Byte 5)
Destination Address (Bytes 6-7) *
Options (Byte 8)
PS1 API ID (Byte 9)
Identifies the UART data frame for the host to correlate with a subsequent ACK (acknowledgement). Setting Frame ID to '0' will disable response frame.
MSB first, LSB last. Broadcast = 0xFFFF
0x01 = Disable ACK
0x04 = Send packet w/Broadcast Pan ID
All other bits must be set to 0.
0x28

Figure 5-27: SFU Command Data Frame Structure

The factory-unlocked state of the sensor remains only up until the next command. The SFU command is designed to prevent the accidental overwriting of data by requiring this extra step.

SFU Reply Data Frame

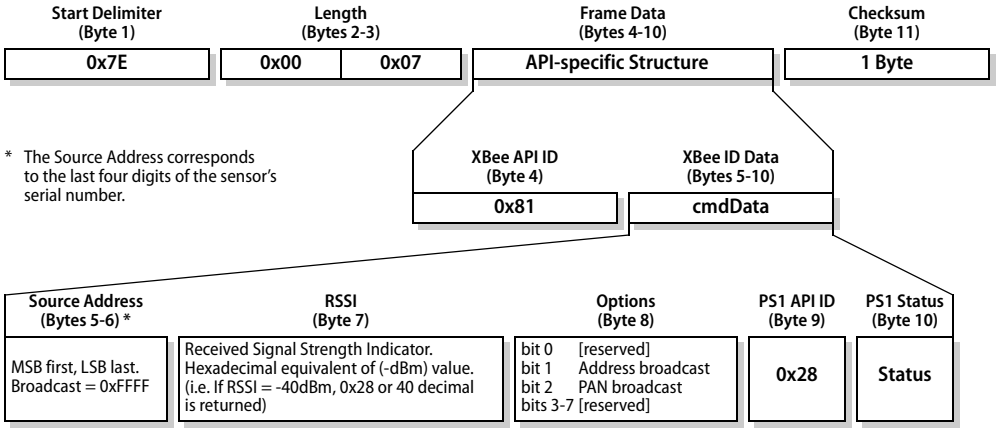

Figure 5-28: SFU Reply Data Frame Structure

Byte Index	Data Type	Description
10	UINT8	0x00 - Successful command status.
		0x01 - Bad command error.

Table 5-21: SFU Reply Data Items

Sensor Battery Life (SBL) Command - 0x29

Returns the estimated remaining battery life.

SBL Command Data Frame

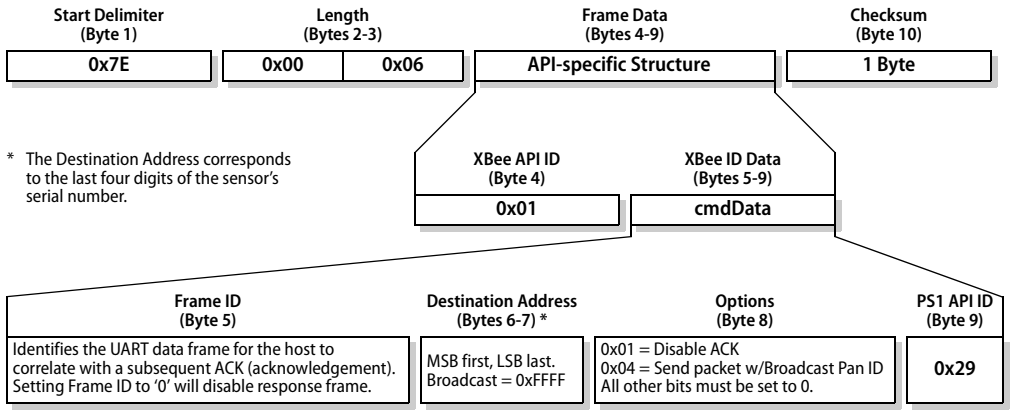
Start Delimiter (Byte 1)
Length (Bytes 2-3)
Frame Data (Bytes 4-9)
Checksum (Byte 10)
0x7E
0x00
0x06
API-specific Structure
1 Byte
* The Destination Address corresponds to the last four digits of the sensor's serial number.
XBee API ID (Byte 4)
XBee ID Data (Bytes 5-9)
0x01
cmdData
Frame ID (Byte 5)
Destination Address (Bytes 6-7) *
Options (Byte 8)
PS1 API ID (Byte 9)
Identifies the UART data frame for the host to correlate with a subsequent ACK (acknowledgement). Setting Frame ID to '0' will disable response frame.
MSB first, LSB last. Broadcast = 0xFFFF
0x01 = Disable ACK
0x04 = Send packet w/Broadcast Pan ID
All other bits must be set to 0.
0x29

Figure 5-29: SBL Command Data Frame Structure

SBL Reply Data Frame

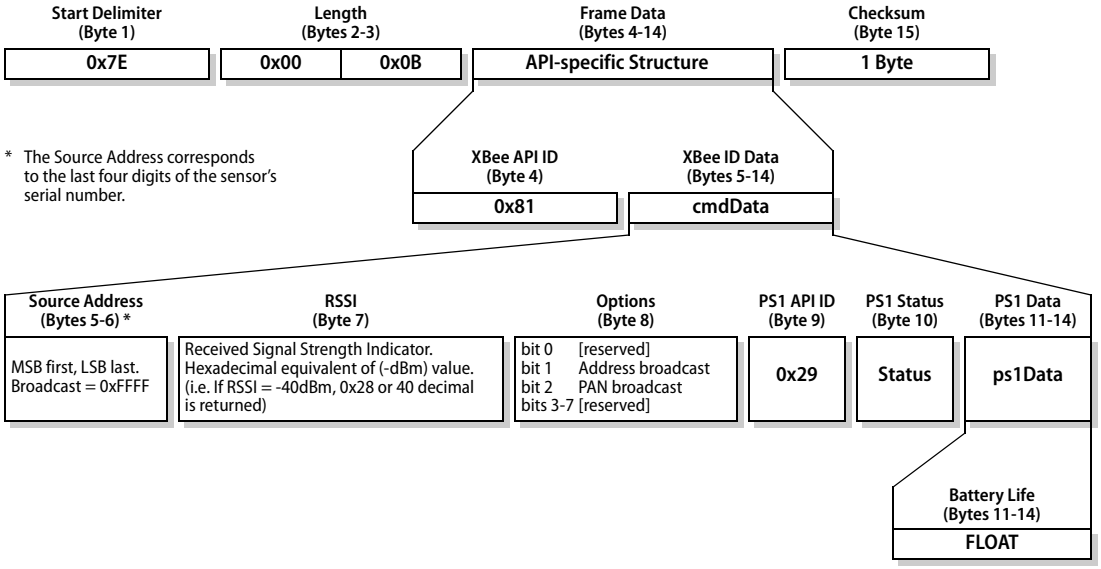

Figure 5-30: SBL Reply Data Frame Structure

Byte Index	Data Type	Description
10	UINT8	0x00 - Successful command status.
		0x01 - Bad command error.
11-14	FLOAT	Battery life as a percentage of full.

Table 5-22: SBL Reply Data Items

The battery life is returned as a percentage of full capacity. The Sensor Control Parameter called New Battery Capacity stores the energy capacity of a new batery. See the topic "Sensor Control Parameter (SCP) Command - 0xA0 / 0x20" on page 36 for a complete description.

Radio Status (RS) Command - 0x40

Returns the sensor XBee module's last status value.

RS Command Data Frame

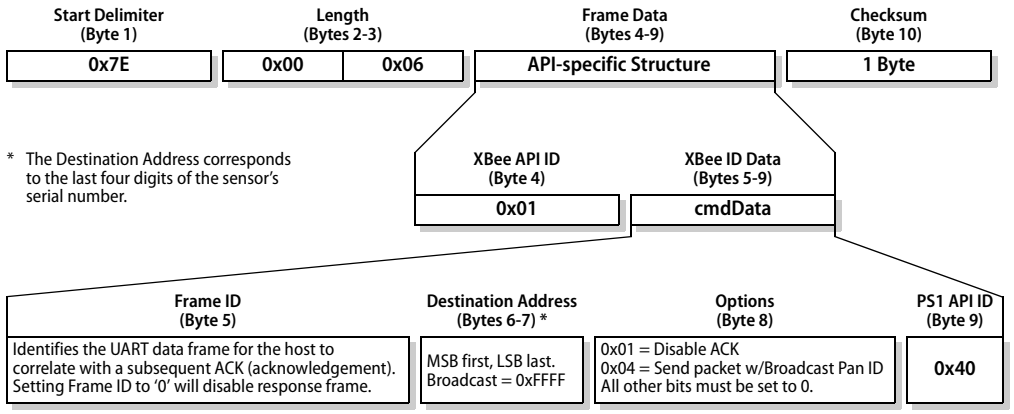
Start Delimiter (Byte 1)
Length (Bytes 2-3)
Frame Data (Bytes 4-9)
Checksum (Byte 10)
0x7E
0x00
0x06
API-specific Structure
1 Byte
* The Destination Address corresponds to the last four digits of the sensor's serial number.
XBee API ID (Byte 4)
XBee ID Data (Bytes 5-9)
0x01
cmdData
Frame ID (Byte 5)
Destination Address (Bytes 6-7) *
Options (Byte 8)
PS1 API ID (Byte 9)
Identifies the UART data frame for the host to correlate with a subsequent ACK (acknowledgement). Setting Frame ID to '0' will disable response frame.
MSB first, LSB last. Broadcast = 0xFFFF
0x01 = Disable ACK
0x04 = Send packet w/Broadcast Pan ID
All other bits must be set to 0.
0x40

Figure 5-31: RS Command Data Frame Structure

RS Reply Data Frame

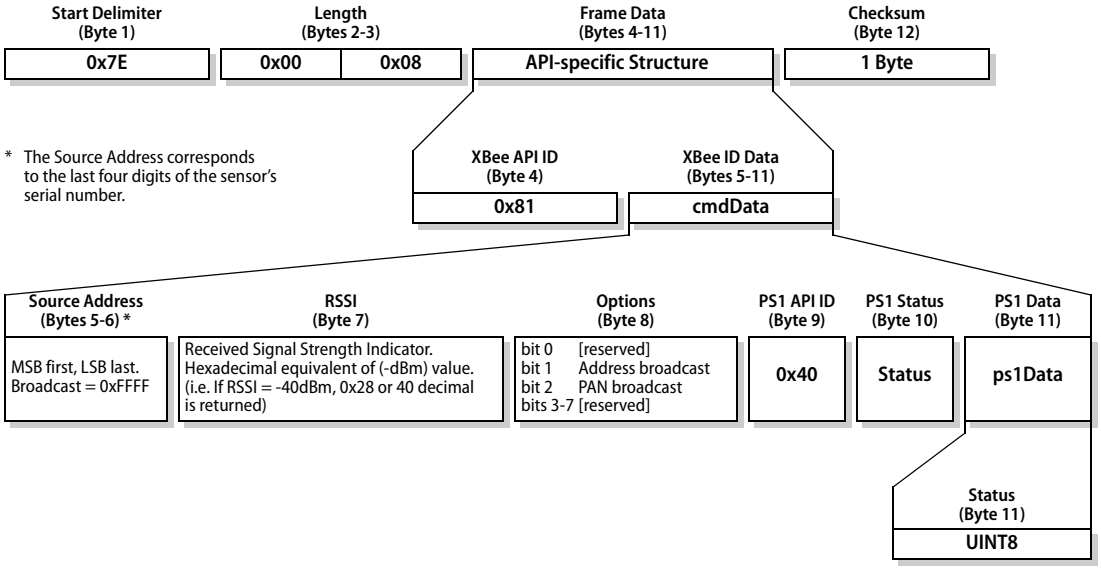

Figure 5-32: RS Reply Data Frame Structure

Byte Index	Data Type	Description
10	UINT8	0x00 - Successful command status.
		0x01 - Bad command error.
11	UINT8	0x00 - Hardware reset.
		0x01 - Watchdog timer reset.
		0x02 - Associated.
		0x03 - Disassociated.
		0x04 - Synchronization lost (Beacon-enabled).
		0x05 - Coordinator realignment.
		0x06 - Coordinator reset.

Table 5-23: RS Reply Data Items

Additional information about the XBee module status value is found in the appendix "XBee™/XBee-PRO™ OEM RF Modules Product Manual" on page 83.

Radio RSSI Command (RSS) Command - 0x41

Returns the sensor's Received Signal Strength Indicator value.

RSS Command Data Frame

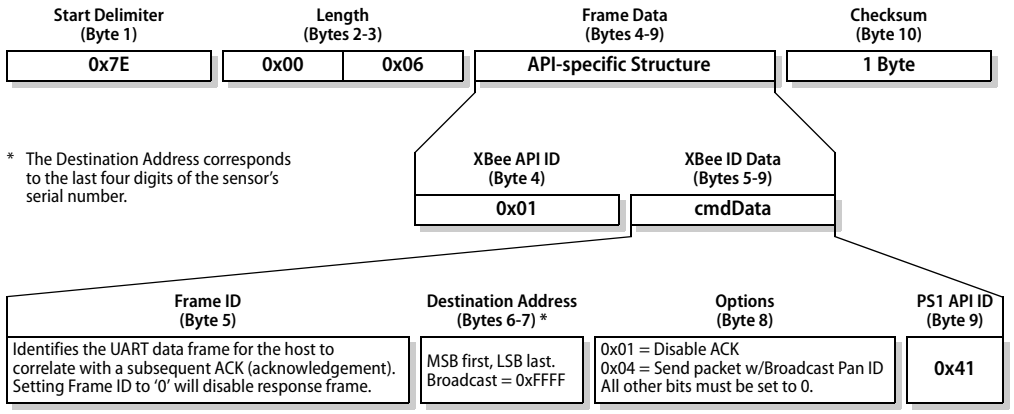
Start Delimiter (Byte 1)
Length (Bytes 2-3)
Frame Data (Bytes 4-9)
Checksum (Byte 10)
0x7E
0x00
0x06
API-specific Structure
1 Byte
* The Destination Address corresponds to the last four digits of the sensor's serial number.
XBee API ID (Byte 4)
XBee ID Data (Bytes 5-9)
0x01
cmdData
Frame ID (Byte 5)
Destination Address (Bytes 6-7) *
Options (Byte 8)
PS1 API ID (Byte 9)
Identifies the UART data frame for the host to correlate with a subsequent ACK (acknowledgement). Setting Frame ID to '0' will disable response frame.
MSB first, LSB last. Broadcast = 0xFFFF
0x01 = Disable ACK
0x04 = Send packet w/Broadcast Pan ID
All other bits must be set to 0.
0x41

Figure 5-33: RSS Command Data Frame Structure

RSS Reply Data Frame

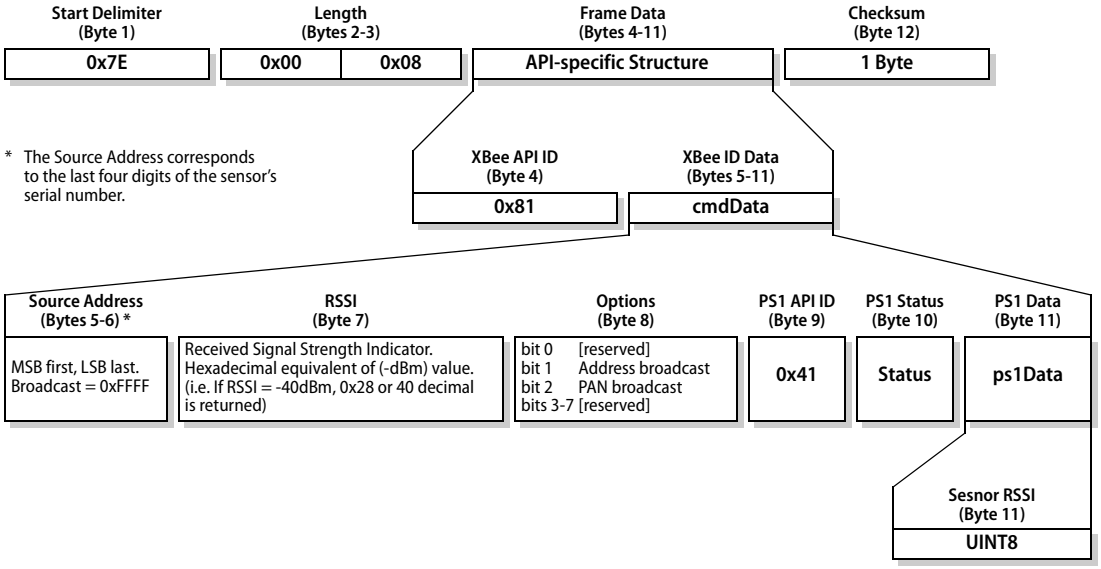

Figure 5-34: RS Reply Data Frame Structure

Byte Index	Data Type	Description
10	UINT8	0x00 - Successful command status.
		0x01 - Bad command error.
11	UINT8	Received Signal Strength Indicator. Hexadecimal equivalent of (-dBm) value. (i.e. 0x28 = -40 dBm)

Table 5-24: RS Reply Data Items

The Sensor RSSI value is a measurement of the sensor's reception strength of data transmitted from the base station, as opposed to all data frame RSSI values which are measurements of the base station's reception quality of data from the sensor.

Radio AT (RAT) Command - 0x42

Writes a value to or reads a value from a sensor XBee module AT register.

RAT Command Data Frame

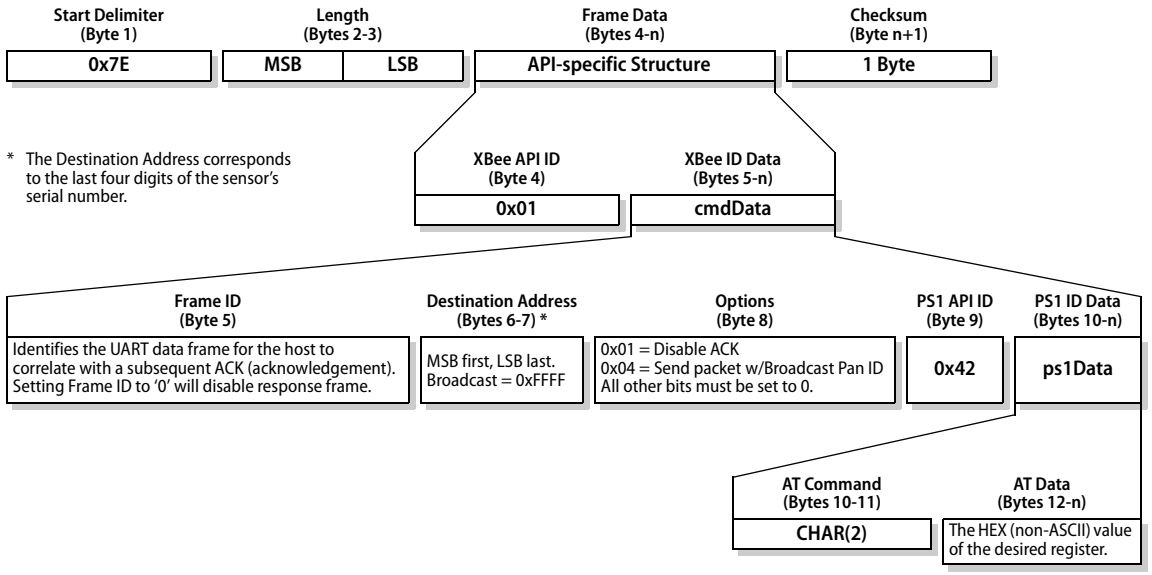
Start Delimiter (Byte 1)
Length (Bytes 2-3)
Frame Data (Bytes 4-n)
Checksum (Byte n+1)
0x7E
MSB
LSB
API-specific Structure
1 Byte
* The Destination Address corresponds to the last four digits of the sensor's serial number.
XBee API ID (Byte 4)
XBee ID Data (Bytes 5-n)
0x01
cmdData
Frame ID (Byte 5)
Identifies the UART data frame for the host to correlate with a subsequent ACK (acknowledgement). Setting Frame ID to '0' will disable response frame.
Destination Address (Bytes 6-7) *
MSB first, LSB last. Broadcast = 0xFFFF
Options (Byte 8)
0x01 = Disable ACK
0x04 = Send packet w/Broadcast Pan ID
All other bits must be set to 0.
PS1 API ID (Byte 9)
0x42
PS1 ID Data (Bytes 10-n)
ps1Data
AT Command (Bytes 10-11)
CHAR(2)
AT Data (Bytes 12-n)
The HEX (non-ASCII) value of the desired register.

Figure 5-35: RAT Command Data Frame Structure

Byte Index	Data Type	Description
10-11	CHAR(2)	Two ASCII characters of AT command.
12-n	varies	Optional AT command parameter value.

Table 5-25: RAT Command Data Items

RAT Reply Data Frame

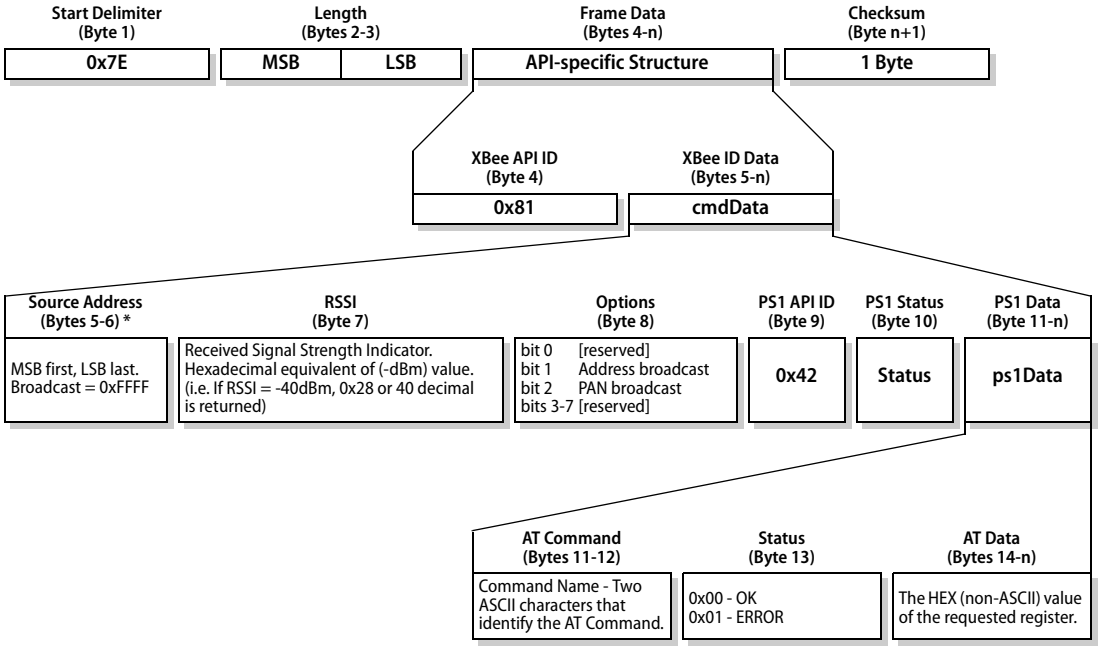

Figure 5-36: RAT Reply Data Frame Structure

NOTE

Some AT commands will send back multiple frames. See the appendix "XBee™/XBee-PRO™ OEM RF Modules Product Manual" on page 83 for AT command descriptions.

Calibrate (CAL) Command - 0x60

Performs a calibration step as part of the sensor's overall calibration process.

CAL Command Data Frame

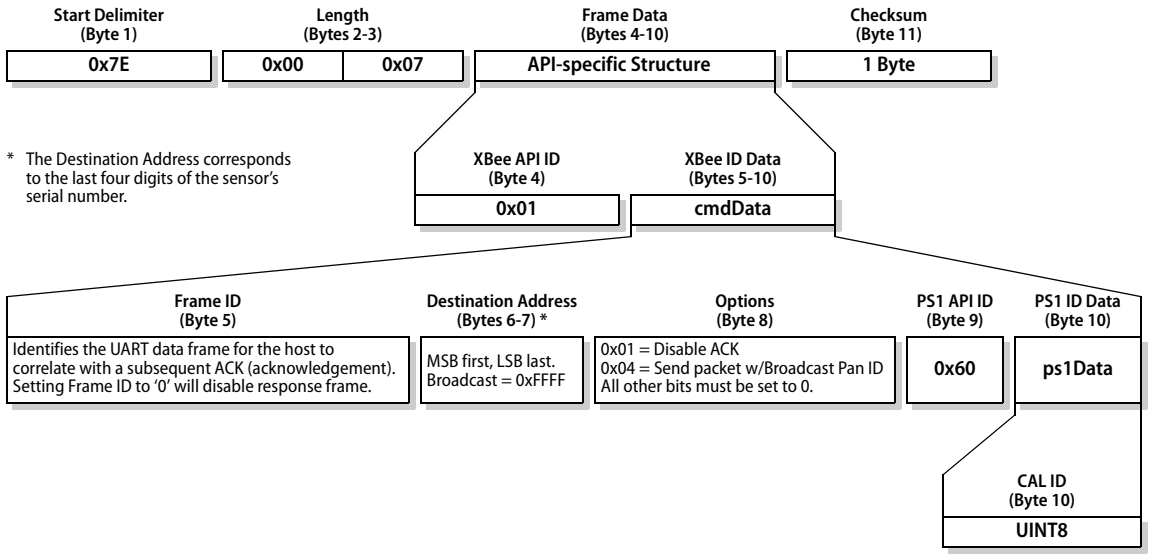
Start Delimiter (Byte 1)
Length (Bytes 2-3)
Frame Data (Bytes 4-10)
Checksum (Byte 11)
0x7E
0x00
0x07
API-specific Structure
1 Byte
* The Destination Address corresponds to the last four digits of the sensor's serial number.
XBee API ID (Byte 4)
XBee ID Data (Bytes 5-10)
0x01
cmdData
Frame ID (Byte 5)
Destination Address (Bytes 6-7) *
Options (Byte 8)
PS1 API ID (Byte 9)
PS1 ID Data (Byte 10)
Identifies the UART data frame for the host to correlate with a subsequent ACK (acknowledgement). Setting Frame ID to '0' will disable response frame.
MSB first, LSB last. Broadcast = 0xFFFF
0x01 = Disable ACK
0x04 = Send packet w/Broadcast Pan ID
All other bits must be set to 0.
0x60
ps1Data
CAL ID (Byte 10)
UINT8

Figure 5-37: CAL Command Data Frame Structure

Byte Index	Data Type	Description
10	UINT8	Calibration (CAL) Identifier as described in the table "Calibration Identifiers" on page 72.

Table 5-26: CAL Command Data Items

CAUTION

The calibration process requires a suitable environment and NIST traceable pressure and temperature standards. Minimum accuracy requirements are specified in the ANSI Z540 standard. Sensor calibration requires a thorough understanding of the process and could invalidate the sensor's warranty if performed incorrectly.

NOTE

The sensor's factory lock protection system must be first unlocked before executing every CAL command. See the topic "Sensor Factory Unlock (SFU) Command - 0x28" on page 60 for a description on how to unlock the sensor control parameters.

CAL Reply Data Frame

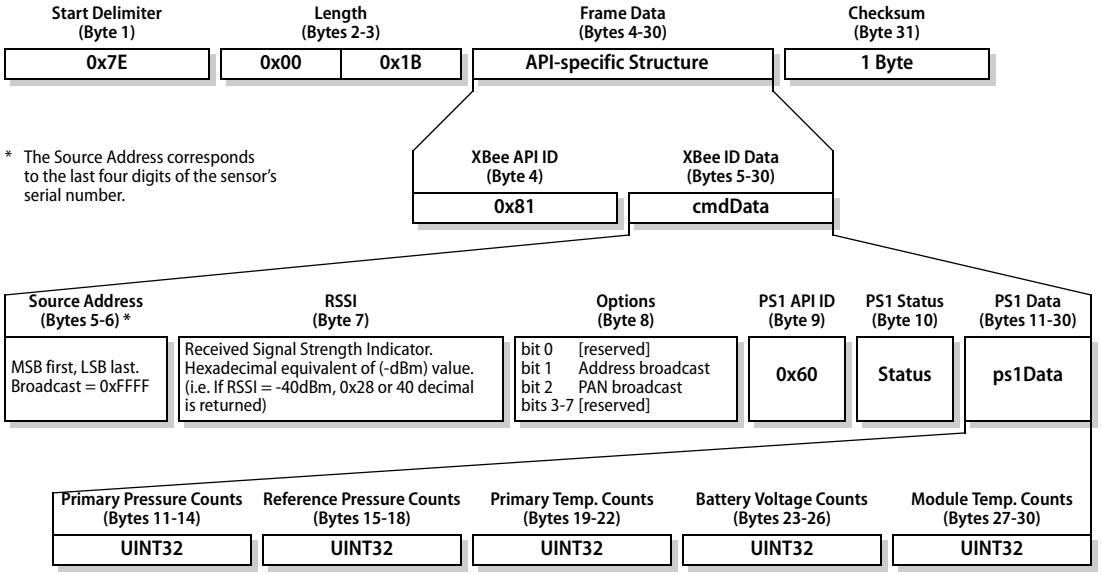

Figure 5-38: SCP-Read Reply Data Frame Structure

Byte Index	Data Type	Description
10	UINT8	0x00 - Successful command status.
		0x01 - Bad command error.
		0x02 - Bad argument.
11-14	UINT32	Counts for primary pressure sensing element strain ADC channel.
15-18	UINT32	Counts for reference pressure ADC channel.
19-22	UINT32	Counts for primary sensing element temperature ADC channel.
23-26	UINT32	Counts for battery voltage ADC channel.
27-30	UINT32	Counts for module temperature ADC channel.

Table 5-27: SCP-Read Reply Data Items

CAUTION

All calibration data is stored in RAM and will not persist if the battery is removed or if the sensor is reset as described in the topic "Sensor Reset (SR) Command - 0x22" on page 46. To save calibration data permanently, see the topic "Sensor Memory Save (SMS) Command - 0x27" on page 58

Name	Identifier	Data Type	Comments (* default)
Ambient Temperature	0x00	UINT8	Measures the primary pressure sensing element temperature during ambient temperature soak.
Reserved	0x01	UINT8	Reserved - do not use.
0% FS Pressure @ Ambient	0x02	UINT8	Measures the primary pressure sensing element strain at 0% full scale pressure during ambient temperature soak.
20% FS Pressure @ Ambient	0x03	UINT8	Measures the primary pressure sensing element strain at 20% full scale pressure during ambient temperature soak.
40% FS Pressure @ Ambient	0x04	UINT8	Measures the primary pressure sensing element strain at 40% full scale pressure during ambient temperature soak.
60% FS Pressure @ Ambient	0x05	UINT8	Measures the primary pressure sensing element strain at 60% full scale pressure during ambient temperature soak.
80% FS Pressure @ Ambient	0x06	UINT8	Measures the primary pressure sensing element strain at 80% full scale pressure during ambient temperature soak.
100% FS Pressure @ Ambient	0x07	UINT8	Measures the primary pressure sensing element strain at 100% full scale pressure during ambient temperature soak.
Reserved	0x08	UINT8	Reserved - do not use.
Cold Temperature	0x09	UINT8	Measures the primary pressure sensing element temperature during cold temperature soak.
0% FS Pressure @ Cold	0x0A	UINT8	Measures the primary pressure sensing element strain at 0% full scale pressure during cold temperature soak.
100% FS Pressure @ Cold	0x0B	UINT8	Measures the primary pressure sensing element strain at 100% full scale pressure during cold temperature soak.
Hot Temperature	0x0C	UINT8	Measures the primary pressure sensing element temperature during hot temperature soak.
0% FS Pressure @ Hot	0x0D	UINT8	Measures the primary pressure sensing element strain at 0% full scale pressure during hot temperature soak.

Table 5-28: Calibration Identifiers

Name	Identifier	Data Type	Comments (* default)
100% FS Pressure @ Hot	0x0E	UINT8	Measures the primary pressure sensing element strain at 100% full scale pressure during hot temperature soak.
Battery Voltage	0x0F	UINT8	Measures the battery voltage while being powered by 3.0V reference voltage.
Internal	0x10	UINT8	Performs an internal ADC calibration.

Table 5-28: Calibration Identifiers

CAUTION

The calibration process requires a suitable environment and NIST traceable pressure and temperature standards. Minimum accuracy requirements are specified in the ANSI Z540 standard. Sensor calibration requires a thorough understanding of the process and could invalidate the sensor's warranty if performed incorrectly.

Calibrate Sensor Offset (CSO) Command - 0x61

Trims the initial offset of the primary pressure sensing element.

CSO Command Data Frame

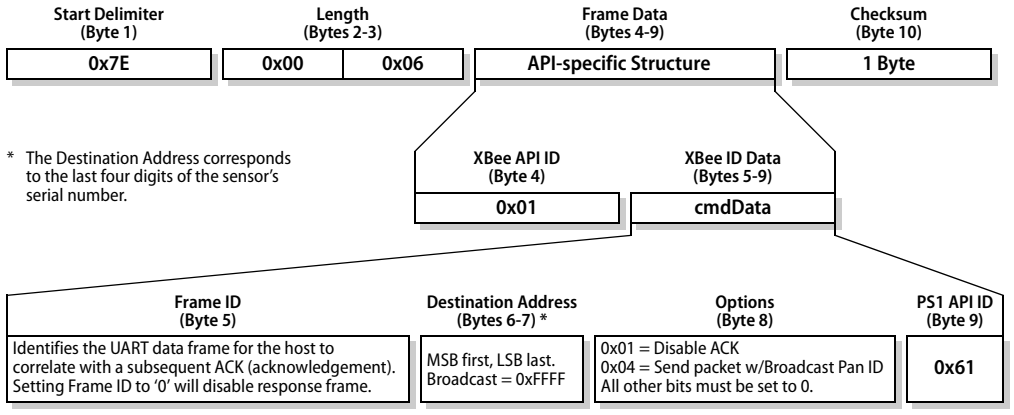
Start Delimiter (Byte 1)
Length (Bytes 2-3)
Frame Data (Bytes 4-9)
Checksum (Byte 10)
0x7E
0x00
0x06
API-specific Structure
1 Byte
* The Destination Address corresponds to the last four digits of the sensor's serial number.
XBee API ID (Byte 4)
XBee ID Data (Bytes 5-9)
0x01
cmdData
Frame ID (Byte 5)
Destination Address (Bytes 6-7) *
Options (Byte 8)
PS1 API ID (Byte 9)
Identifies the UART data frame for the host to correlate with a subsequent ACK (acknowledgement). Setting Frame ID to '0' will disable response frame.
MSB first, LSB last. Broadcast = 0xFFFF
0x01 = Disable ACK
0x04 = Send packet w/Broadcast Pan ID
All other bits must be set to 0.
0x61

Figure 5-39: CSO Command Data Frame Structure

After manufacturing, the primary pressure sensing element output must be initially offset to prepare for the full calibration process as described in the topic "Calibrate (CAL) Command - 0x60" on page 70. After the offset trim process successfully completes, the sensor can be calibrated.

CAUTION

The calibration process requires a suitable environment and NIST traceable pressure and temperature standards. Minimum accuracy requirements are specified in the ANSI Z540 standard. Sensor calibration requires a thorough understanding of the process and could invalidate the sensor's warranty if performed incorrectly.

NOTE

The sensor's factory lock protection system must be first unlocked before executing the CSO command. See the topic "Sensor Factory Unlock (SFU) Command - 0x28" on page 60 for a description on how to unlock the sensor control parameters.

CSO Reply Data Frame

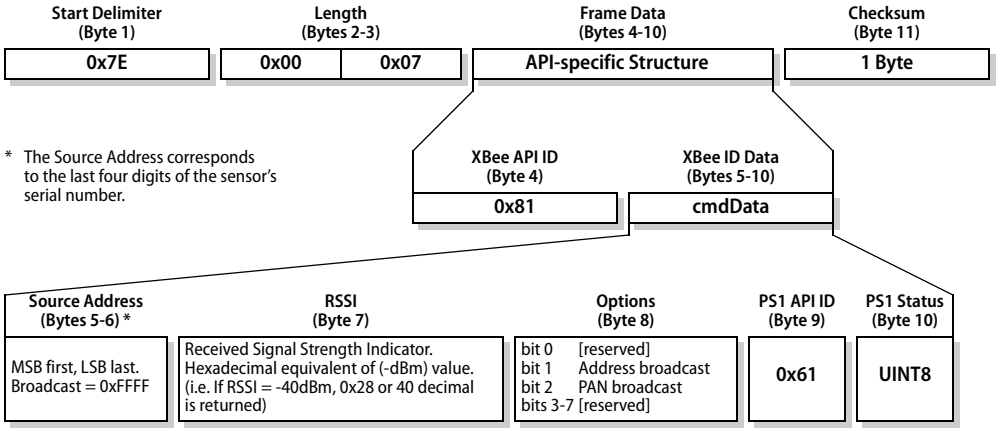
Start Delimiter (Byte 1)
0x7E
Length (Bytes 2-3)
0x00
0x07
Frame Data (Bytes 4-10)
API-specific Structure
Checksum (Byte 11)
1 Byte
* The Source Address corresponds to the last four digits of the sensor's serial number.
XBee API ID (Byte 4)
0x81
XBee ID Data (Bytes 5-10)
cmdData
Source Address (Bytes 5-6) *
MSB first, LSB last. Broadcast = 0xFFFF
RSSI (Byte 7)
Received Signal Strength Indicator. Hexadecimal equivalent of (-dBm) value. (i.e. If RSSI = -40dBm, 0x28 or 40 decimal is returned)
Options (Byte 8)
bit 0 [reserved]
bit 1 Address broadcast
bit 2 PAN broadcast
bits 3-7 [reserved]
PS1 API ID (Byte 9)
0x61
PS1 Status (Byte 10)
UINT8

Figure 5-40: CSO Reply Data Frame Structure

Byte Index	Data Type	Description
10	UINT8	0x00 - Successful command status.
		0x01 - Bad command error.
		0x03 - Factory settings locked.
		0x07 - Bad sensor.

Table 5-29: CSO Reply Data Items

CAUTION

All calibration data is stored in RAM and will not persist if the battery is removed or if the sensor is reset as described in the topic "Sensor Reset (SR) Command - 0x22" on page 46. To save calibration data permanently, see the topic "Sensor Memory Save (SMS) Command - 0x27" on page 58

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APPENDIX A
Product Specifications and Agency Certifications

This appendix contains the product performance specifications and agency certfication information.

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Product Specifications

Typical for 25°C unless otherwise specified.

Parameter	Specification
Pressure Ranges	100, 500, 1000, 1500, 3000, 5000, 7500 and 10000 PSI
Pressure Reference	User selectable absolute, sealed gage or true gage.
Zero Error	±0.5% of range; User-nullable.
Total Error (excluding zero)	±0.1% of range.
Analog-to-Digital Resolution	24-bits.

Table A-1: Performance Specifications

Parameter	Specification
Operating Temperature	-40°C to +85°C
Compensated Temperature	-40°C to +85°C
Thermal Zero Shift	±0.1% of range.
Thermal Span Shift	±0.1% of range.

Table A-2: Environmental Specifications

Parameter	Specification
Battery Type	PS1 - Lithium thionyl chloride (Li/SOCI2)
	PS2 - Alkaline
Battery Size	PS1 - 2/3AA X 1
	PS2 - C X 1
Battery Voltage	3.6V
	1.5V
Battery Life	Standard Range - 1 year
	Extended Range - 2 months
Insulation Resistance	>100 megohms @ 50VDC

Table A-3: Electrical Specifications

Parameter	Specification
Standard Range	Indoor/urban - 30 meters
	Outdoor LOS - 100 meters
Extended Range	Indoor/urban - 300 meters
	Outdoor LOS - 1000 meters
Operating Frequency	2.4 GHz

Table A-4: Wireless Specifications

Parameter	Specification
Media	Gas, liquid
Wetted Parts Material	15-5 PH, 316L stainless steel
Welds	Single electron beam.
Proof Pressure (sensor only)	2X range
Burst Pressure (sensor only)	Up to 500 PSI - 6X range
	Up to 6000 PSI - 5X range
	Up to 10000 PSI - 4X range
Pressure Port	PS1 - AS4395 E 04 (mates with AS5202-04)
	PS2 - 2" Fig 1502 Male Sub
Weight	PS1 - 500 g
	PS2 - 12 kg

Table A-5: Mechanical Specifications

Agency Certifications

FCC Certification

PS1 standard range contains FCC ID: OUR-XBEE
PS1 extended range contains FCC ID: OUR-XBEEPRO

The enclosed device complies with Part 15.247 of the FCC Rules. Operation is subject to the following two conditions:

1. This device may not cause harmful interference.
2. This device must accept any interference received, including interference that may cause undesired operation.

IC (Industry Canada) Certification

PS1 standard range contains Model XBee Radio, IC: 4214A XBEE
PS1 extended range contains Model XBee-PRO Radio, IC: 4214A XBEEPRO

European Certification (CE)

PS1 standard range conforms to ETSI.
PS1 extended range conforms to ETSI (10 mW TX output).

CE

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APPENDIX B
XBee™/XBee-PRO™ OEM RF Modules Product Manual

This chapter contains the complete product manual for the XBee and XBee-PRO modules from MaxStream, Inc. Since the wireless sensor products from IntelliSensing incorporate modular transceivers from MaxStream, and due to the need for accurate technical documentation, we include MaxStream's actual documentation for reference.

The IntelliSensing base station products provide a direct connection to the XBee-PRO module within the unit. As such, this chapter provides generic communication descriptions and must be used in conjunction with chapter "API Data Frame Specification" on page 21. An important consideration to remember when writing custom interface code for the base station products from IntelliSensing, is that API Operation Mode 1 (AP = 1) must always be used and the baudrate of the base station should be set to 57,600 bps. This baudrate is independant of the 250 Kbps data rate used for RF communication as specified in the IEEE 802.15.4 specification, however the PS1/PS2 sensor uses the same 57,600 bps baudrate during transfer of measurement data to it's transceiver, and it is advisable to maintain consistency throughout the system and avoid any contention.

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XBee™/XBee-PRO™ OEM RF Modules

XBee/XBee-PRO OEM RF Modules
RF Module Operation
RF Module Configuration
Appendices

Product Manual v1.xAx - 802.15.4 Protocol
For OEM RF Module Part Numbers: XB24-...-001, XBP24-...-001

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1. XBee/XBee-PRO OEM RF Modules

The XBee and XBee-PRO OEM RF Modules were engineered to meet IEEE 802.15.4 standards and support the unique needs of low-cost, low-power wireless sensor networks. The modules require minimal power and provide reliable delivery of data between devices.

The modules operate within the ISM 2.4 GHz frequency band and are pin-for-pin compatible with each other.

1.1. Key Features

Long Range Data Integrity

XBee

- Indoor/Urban: up to 100' (30 m)
- Outdoor line-of-sight: up to 300' (100 m)
- Transmit Power: 1 mW (0 dBm)
- Receiver Sensitivity: -92 dBm

XBee-PRO

- Indoor/Urban: up to 300' (100 m)
- Outdoor line-of-sight: up to 1 mile (1500 m)
- Transmit Power: 100 mW (20 dBm) EIRP
- Receiver Sensitivity: -100 dBm

RF Data Rate: 250,000 bps

Advanced Networking & Security

Retries and Acknowledgements

DSSS (Direct Sequence Spread Spectrum)

Each direct sequence channels has over 65,000 unique network addresses available

Source/Destination Addressing

Unicast & Broadcast Communications

Point-to-point, point-to-multipoint and peer-to-peer topologies supported

Coordinator/End Device operations

Low Power

XBee

- TX Current: 45 mA (@3.3 V)
- RX Current: 50 mA (@3.3 V)
- Power-down Current: < 10 µA

XBee-PRO

- TX Current: 215 mA (@3.3 V)
- RX Current: 55 mA (@3.3 V)
- Power-down Current: < 10 µA

ADC and I/O line support

Analog-to-digital conversion, Digital I/O

I/O Line Passing

Easy-to-Use

No configuration necessary for out-of box RF communications

Free X-CTU Software (Testing and configuration software)

AT and API Command Modes for configuring module parameters

Extensive command set

Small form factor

Free & Unlimited RF-XPert Support

1.1.1. Worldwide Acceptance

FCC Approval (USA) Refer to Appendix A [p59] for FCC Requirements. Systems that contain XBee/XBee-PRO RF Modules inherit MaxStream Certifications.

ISM (Industrial, Scientific & Medical) **2.4 GHz frequency band**

Manufactured under **ISO 9001:2000** registered standards

XBee/XBee-PRO RF Modules are optimized for use in the **United States**, **Canada**, **Australia, Israel and Europe**. Contact MaxStream for complete list of government agency approvals.

1.2. Specifications

Table 1-01. Specifications of the XBee/XBee-PRO OEM RF Modules

Specification	XBee	XBee-PRO
Performance		
Indoor/Urban Range	up to 100 ft. (30 m)	Up to 300' (100 m)
Outdoor RF line-of-sight Range	up to 300 ft. (100 m)	Up to 1 mile (1500 m)
Transmit Power Output (software selectable)	1mW (0 dBm)	60 mW (18 dBm) conducted, 100 mW (20 dBm) EIRP*
RF Data Rate	250,000 bps	250,000 bps
Serial Interface Data Rate (software selectable)	1200 - 115200 bps (non-standard baud rates also supported)	1200 - 115200 bps (non-standard baud rates also supported)
Receiver Sensitivity	-92 dBm (1% packet error rate)	-100 dBm (1% packet error rate)
Power Requirements		
Supply Voltage	2.8 – 3.4 V	2.8 – 3.4 V
Transmit Current (typical)	45mA (@ 3.3 V)	If PL=0 (10dBm): 137mA(@3.3V), 139mA(@3.0V) PL=1 (12dBm): 155mA (@3.3V), 153mA(@3.0V) PL=2 (14dBm): 170mA (@3.3V), 171mA(@3.0V) PL=3 (16dBm): 188mA (@3.3V), 195mA(@3.0V) PL=4 (18dBm): 215mA (@3.3V), 227mA(@3.0V)
Idle / Receive Current (typical)	50mA (@ 3.3 V)	55mA (@ 3.3 V)
Power-down Current	< 10 µA	< 10 µA
General		
Operating Frequency	ISM 2.4 GHz	ISM 2.4 GHz
Dimensions	0.960" x 1.087" (2.438cm x 2.761cm)	0.960" x 1.297" (2.438cm x 3.294cm)
Operating Temperature	-40 to 85º C (industrial)	-40 to 85º C (industrial)
Antenna Options	Integrated Whip, Chip or U.FL Connector	Integrated Whip, Chip or U.FL Connector
Networking & Security		
Supported Network Topologies	Point-to-point, Point-to-multipoint & Peer-to-peer	
Number of Channels (software selectable)	16 Direct Sequence Channels	12 Direct Sequence Channels
Addressing Options	PAN ID, Channel and Addresses	PAN ID, Channel and Addresses
Agency Approvals		
United States (FCC Part 15.247)	OUR-XBEE	OUR-XBEEPRO
Industry Canada (IC)	4214A XBEE	4214A XBEEPRO
Europe (CE)	ETSI	ETSI (Max. 10 dBm transmit power output)*
Japan	n/a	005NYCA0378 (Max. 10 dBm transmit power output)**

* When operating in Europe: XBee-PRO RF Modules must be configured to operate at a maximum transmit power output level of 10 dBm. The power output level is set using the PL command. The PL parameter must equal "0" (10 dBm).

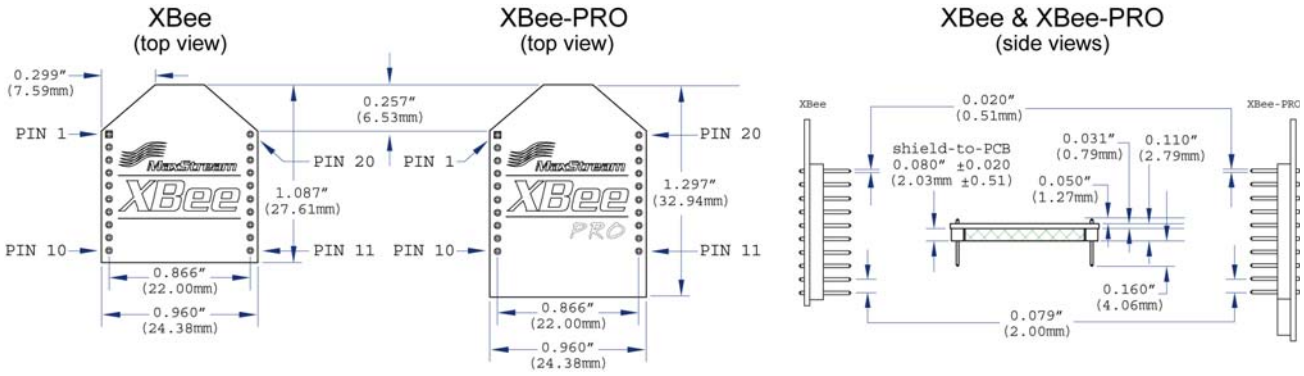
Additionally, European regulations stipulate an EIRP power maximum of 12.86 dBm (19 mW) for the XBee-PRO and 12.11 dBm for the XBee when integrating high-gain antennas.

** When operating in Japan: Transmit power output is limited to 10 dBm. A special part number is required when ordering modules approved for use in Japan. Contact MaxStream for more information [call 1-801-765-9885 or send e-mails to sales@maxstream.net].

Antenna Options: The ranges specified are typical when using the integrated Whip (1.5 dBi) and Dipole (2.1 dBi) antennas. The Chip antenna option provides advantages in its form factor; however, it typically yields shorter range than the Whip and Dipole antenna options when transmitting outdoors. For more information, refer to the "XBee Antenna" application note located on MaxStream's web site (http://www.maxstream.net/support/knowledgebase/article.php?kb=153).

1.3. Mechanical Drawings

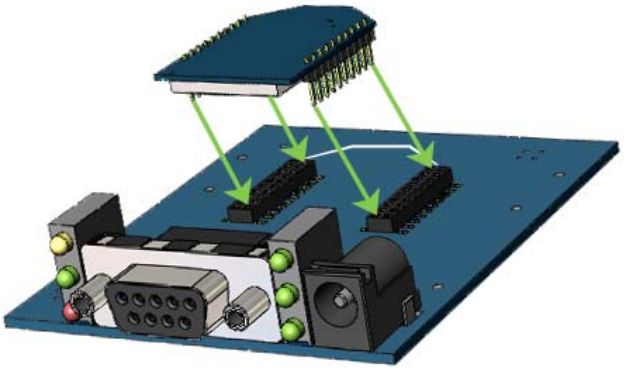
Figure 1-01. Mechanical drawings of the XBee/XBee-PRO OEM RF Modules (antenna options not shown)
The XBee and XBee-PRO RF Modules are pin-for-pin compatible.



1.4. Mounting Considerations

The XBee/XBee-PRO RF Module was designed to mount into a receptacle (socket) and therefore does not require any soldering when mounting it to a board. The XBee Development Kits contain RS-232 and USB interface boards which use two 20-pin receptacles to receive modules.

Figure 1-02. XBee Module Mounting to an RS-232 Interface Board.



The receptacles used on MaxStream development boards are manufactured by Century Interconnect. Several other manufacturers provide comparable mounting solutions; however, MaxStream currently uses the following receptacles:

- Through-hole single-row receptacles -
  Samtec P/N: MMS-110-01-L-SV (or equivalent)
- Surface-mount double-row receptacles -
  Century Interconnect P/N: CPRMSL20-D-0-1 (or equivalent)
- Surface-mount single-row receptacles -
  Samtec P/N: SMM-110-02-SM-S

MaxStream also recommends printing an outline of the module on the board to indicate the orientation the module should be mounted.

1.5. Pin Signals

Figure 1-03. XBee/XBee-PRO RF Module Pin Numbers
(top sides shown - shields on bottom)

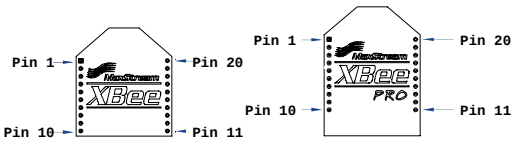


Table 1-02. Pin Assignments for the XBee and XBee-PRO Modules
(Low-asserted signals are distinguished with a horizontal line above signal name.)

Pin #	Name	Direction	Description
1	VCC	-	Power supply
2	DOUT	Output	UART Data Out
3	DIN / CONFIG	Input	UART Data In
4	DO8*	Output	Digital Output 8
5	RESET	Input	Module Reset (reset pulse must be at least 200 ns)
6	PWM0 / RSSI	Output	PWM Output 0 / RX Signal Strength Indicator
7	PWM1	Output	PWM Output 1
8	[reserved]	-	Do not connect
9	DTR / SLEEP_RQ / DI8	Input	Pin Sleep Control Line or Digital Input 8
10	GND	-	Ground
11	AD4 / DIO4	Either	Analog Input 4 or Digital I/O 4
12	CTS / DIO7	Either	Clear-to-Send Flow Control or Digital I/O 7
13	ON / SLEEP	Output	Module Status Indicator
14	VREF	Input	Voltage Reference for A/D Inputs
15	Associate / AD5 / DIO5	Either	Associated Indicator, Analog Input 5 or Digital I/O 5
16	RTS / AD6 / DIO6	Either	Request-to-Send Flow Control, Analog Input 6 or Digital I/O 6
17	AD3 / DIO3	Either	Analog Input 3 or Digital I/O 3
18	AD2 / DIO2	Either	Analog Input 2 or Digital I/O 2
19	AD1 / DIO1	Either	Analog Input 1 or Digital I/O 1
20	AD0 / DIO0	Either	Analog Input 0 or Digital I/O 0

* Function is not supported at the time of this release

Design Notes:

- Minimum connections: VCC, GND, DOUT & DIN
- Minimum connections for updating firmware: VCC, GND, DIN, DOUT, RTS & DTR
- Signal Direction is specified with respect to the module
- Module includes a 50k Ω pull-up resistor attached to RESET
- Several of the input pull-ups can be configured using the PR command
- Unused pins should be left disconnected

1.6. Electrical Characteristics

Table 1-03. DC Characteristics (VCC = 2.8 - 3.4 VDC)

Symbol	Characteristic	Condition	Min	Typical		Max	Unit
V_{IL}	Input Low Voltage	All Digital Inputs	-	-		0.35 * VCC	V
V_{IH}	Input High Voltage	All Digital Inputs	0.7 * VCC	-		-	V
V_{OL}	Output Low Voltage	I_{OL} = 2 mA, VCC >= 2.7 V	-	-		0.5	V
V_{OH}	Output High Voltage	I_{OH} = -2 mA, VCC >= 2.7 V	VCC - 0.5	-		-	V
II_{IN}	Input Leakage Current	V_{IN} = VCC or GND, all inputs, per pin	-	0.025		1	µA
II_{OZ}	High Impedance Leakage Current	V_{IN} = VCC or GND, all I/O High-Z, per pin	-	0.025		1	µA
TX	Transmit Current	VCC = 3.3 V	-	45 (XBee)	215 (PRO)	-	mA
RX	Receive Current	VCC = 3.3 V	-	50 (XBee)	55 (PRO)	-	mA
PWR-DWN	Power-down Current	SM parameter = 1	-	< 10		-	µA

Table 1-04. ADC Characteristics (Operating)

Symbol	Characteristic	Condition	Min	Typical	Max	Unit
V_{REFH}	VREF - Analog-to-Digital converter reference range		2.08	-	V_{DDAD}	V
I_{REF}	VREF - Reference Supply Current	Enabled	-	200	-	µA
		Disabled or Sleep Mode	-	< 0.01	0.02	µA
V_{INDC}	Analog Input Voltage[1]		V_{SSAD} - 0.3	-	V_{DDAD} + 0.3	V

1. Maximum electrical operating range, not valid conversion range.

Table 1-05. ADC Timing/Performance Characteristics[1]

Symbol	Characteristic	Condition	Min	Typical	Max	Unit
R_{AS}	Source Impedance at Input[2]		-	-	10	kΩ
V_{AIN}	Analog Input Voltage[3]		V_{REFL}		V_{REFH}	V
RES	Ideal Resolution (1 LSB)[4]	$2.08V \leq V_{DDAD} \leq 3.6V$	2.031	-	3.516	mV
DNL	Differential Non-linearity[5]		-	±0.5	±1.0	LSB
INL	Integral Non-linearity[6]		-	±0.5	±1.0	LSB
E_{ZS}	Zero-scale Error[7]		-	±0.4	±1.0	LSB
F_{FS}	Full-scale Error[8]		-	±0.4	±1.0	LSB
E_{IL}	Input Leakage Error[9]		-	±0.05	±5.0	LSB
E_{TU}	Total Unadjusted Error[10]		-	±1.1	±2.5	LSB

1. All ACCURACY numbers are based on processor and system being in WAIT state (very little activity and no IO switching) and that adequate low-pass filtering is present on analog input pins (filter with 0.01 µF to 0.1 µF capacitor between analog input and VREFL). Failure to observe these guidelines may result in system or microcontroller noise causing accuracy errors which will vary based on board layout and the type and magnitude of the activity.

Data transmission and reception during data conversion may cause some degradation of these specifications, depending on the number and timing of packets. It is advisable to test the ADCs in your installation if best accuracy is required.

2. R_{AS} is the real portion of the impedance of the network driving the analog input pin. Values greater than this amount may not fully charge the input circuitry of the ATD resulting in accuracy error.

3. Analog input must be between V_{REFL} and V_{REFH} for valid conversion. Values greater than V_{REFH} will convert to $3FF.

4. The resolution is the ideal step size or 1LSB = $(V_{REFH}–V_{REFL})/1024$

5. Differential non-linearity is the difference between the current code width and the ideal code width (1LSB). The current code width is the difference in the transition voltages to and from the current code.

6. Integral non-linearity is the difference between the transition voltage to the current code and the adjusted ideal transition voltage for the current code. The adjusted ideal transition voltage is $(Current\ Code–1/2)*(1/((V_{REFH}+E_{FS})–(V_{REFL}+E_{ZS})))$.

7. Zero-scale error is the difference between the transition to the first valid code and the ideal transition to that code. The Ideal transition voltage to a given code is $(Code–1/2)*(1/(V_{REFH}–V_{REFL}))$.

8. Full-scale error is the difference between the transition to the last valid code and the ideal transition to that code. The ideal transition voltage to a given code is $(Code–1/2)*(1/(V_{REFH}–V_{REFL}))$.

9. Input leakage error is error due to input leakage across the real portion of the impedance of the network driving the analog pin. Reducing the impedance of the network reduces this error.

10. Total unadjusted error is the difference between the transition voltage to the current code and the ideal straight-line transfer function. This measure of error includes inherent quantization error (1/2LSB) and circuit error (differential, integral, zero-scale, and full-scale) error. The specified value of E_{TU} assumes zero E_{IL} (no leakage or zero real source impedance).

2. RF Module Operation

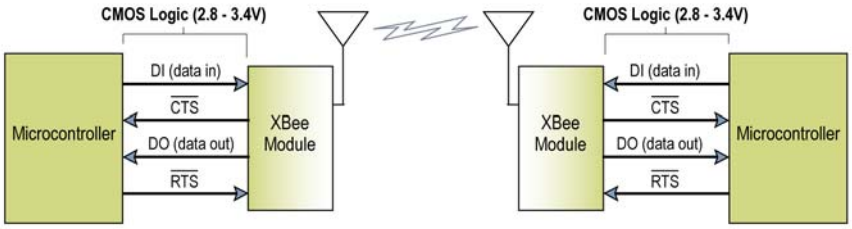
2.1. Serial Communications

The XBee/XBee-PRO OEM RF Modules interface to a host device through a logic-level asynchronous serial port. Through its serial port, the module can communicate with any logic and voltage compatible UART; or through a level translator to any serial device (For example: Through a MaxStream proprietary RS-232 or USB interface board).

2.1.1. UART Data Flow

Devices that have a UART interface can connect directly to the pins of the RF module as shown in the figure below.

Figure 2-01. System Data Flow Diagram in a UART-interfaced environment
(Low-asserted signals distinguished with horizontal line over signal name.)

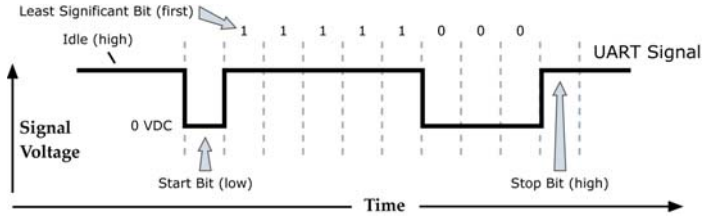


Serial Data

Data enters the module UART through the DI pin (pin 3) as an asynchronous serial signal. The signal should idle high when no data is being transmitted.

Each data byte consists of a start bit (low), 8 data bits (least significant bit first) and a stop bit (high). The following figure illustrates the serial bit pattern of data passing through the module.

Figure 2-02. UART data packet 0x1F (decimal number "31") as transmitted through the RF module
Example Data Format is 8-N-1 (bits - parity - # of stop bits)



The module UART performs tasks, such as timing and parity checking, that are needed for data communications. Serial communications depend on the two UARTs to be configured with compatible settings (baud rate, parity, start bits, stop bits, data bits).

2.1.2. Transparent Operation

By default, XBee/XBee-PRO RF Modules operate in Transparent Mode. When operating in this mode, the modules act as a serial line replacement - all UART data received through the DI pin is queued up for RF transmission. When RF data is received, the data is sent out the DO pin.

Serial-to-RF Packetization

Data is buffered in the DI buffer until one of the following causes the data to be packetized and transmitted:

1. No serial characters are received for the amount of time determined by the RO (Packetization Timeout) parameter. If RO = 0, packetization begins when a character is received.
2. The maximum number of characters that will fit in an RF packet (100) is received.
3. The Command Mode Sequence (GT + CC + GT) is received. Any character buffered in the DI buffer before the sequence is transmitted.

If the module cannot immediately transmit (for instance, if it is already receiving RF data), the serial data is stored in the DI Buffer. The data is packetized and sent at any RO timeout or when 100 bytes (maximum packet size) are received.

If the DI buffer becomes full, hardware or software flow control must be implemented in order to prevent overflow (loss of data between the host and module).

2.1.3. API Operation

API (Application Programming Interface) Operation is an alternative to the default Transparent Operation. The frame-based API extends the level to which a host application can interact with the networking capabilities of the module.

When in API mode, all data entering and leaving the module is contained in frames that define operations or events within the module.

Transmit Data Frames (received through the DI pin (pin 3)) include:

- RF Transmit Data Frame
- Command Frame (equivalent to AT commands)

Receive Data Frames (sent out the DO pin (pin 2)) include:

- RF-received data frame
- Command response
- Event notifications such as reset, associate, disassociate, etc.

The API provides alternative means of configuring modules and routing data at the host application layer. A host application can send data frames to the module that contain address and payload information instead of using command mode to modify addresses. The module will send data frames to the application containing status packets; as well as source, RSSI and payload information from received data packets.

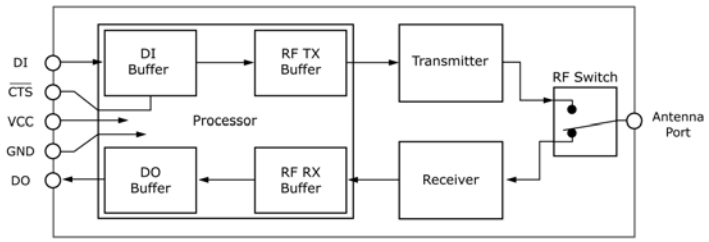
The API operation option facilitates many operations such as the examples cited below:

-> Transmitting data to multiple destinations without entering Command Mode
-> Receive success/failure status of each transmitted RF packet
-> Identify the source address of each received packet

To implement API operations, refer to API sections [p54].

2.1.4. Flow Control

Figure 2-03. Internal Data Flow Diagram



DI (Data In) Buffer

When serial data enters the RF module through the DI pin (pin 3), the data is stored in the DI Buffer until it can be processed.

Hardware Flow Control ($\overline{CTS}$). When the DI buffer is 17 bytes away from being full; by default, the module de-asserts $\overline{CTS}$ (high) to signal to the host device to stop sending data [refer to D7 (DIO7 Configuration) parameter]. $\overline{CTS}$ is re-asserted after the DI Buffer has 34 bytes of memory available.

How to eliminate the need for flow control:

1. Send messages that are smaller than the DI buffer size.
2. Interface at a lower baud rate [BD (Interface Data Rate) parameter] than the throughput data rate.

Case in which the DI Buffer may become full and possibly overflow:

If the module is receiving a continuous stream of RF data, any serial data that arrives on the DI pin is placed in the DI Buffer. The data in the DI buffer will be transmitted over-the-air when the module is no longer receiving RF data in the network.

Refer to the RO (Packetization Timeout), BD (Interface Data Rate) and D7 (DIO7 Configuration) command descriptions for more information.

DO (Data Out) Buffer

When RF data is received, the data enters the DO buffer and is sent out the serial port to a host device. Once the DO Buffer reaches capacity, any additional incoming RF data is lost.

Hardware Flow Control ($\overline{RTS}$). If $\overline{RTS}$ is enabled for flow control (D6 (DIO6 Configuration) Parameter = 1), data will not be sent out the DO Buffer as long as $\overline{RTS}$ (pin 16) is de-asserted.

Two cases in which the DO Buffer may become full and possibly overflow:

1. If the RF data rate is set higher than the interface data rate of the module, the module will receive data from the transmitting module faster than it can send the data to the host.
2. If the host does not allow the module to transmit data out from the DO buffer because of being held off by hardware or software flow control.

Refer to the D6 (DIO6 Configuration) command description for more information.

2.2. ADC and Digital I/O Line Support

The XBee/XBee-PRO RF Modules support ADC (Analog-to-digital conversion) and digital I/O line passing. The following pins support multiple functions:

Table 2-01. Pin functions and their associated pin numbers and commands
AD = Analog-to-Digital Converter, DIO = Digital Input/Output
Pin functions not applicable to this section are denoted within (parenthesis).

Pin Function	Pin#	AT Command
AD0 / DIO0	20	D0
AD1 / DIO1	19	D1
AD2 / DIO2	18	D2
AD3 / DIO3 / (COORD_SEL)	17	D3
AD4 / DIO4	11	D4
AD5 / DIO5 / (ASSOCIATE)	15	D5
DIO6 / (RTS)	16	D6
DIO7 / (CTS)	12	D7
DI8 / (DTR) / (Sleep_RQ)	9	D8

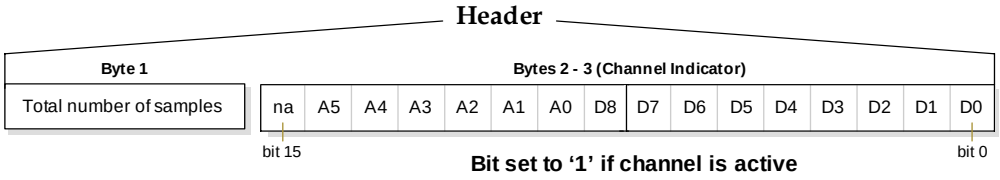
To enable ADC and DIO pin functions:

For ADC Support:	Set ATDn = 2
For Digital Input support:	Set ATDn = 3
For Digital Output Low support:	Set ATDn = 4
For Digital Output High support:	Set ATDn = 5

2.2.1. I/O Data Format

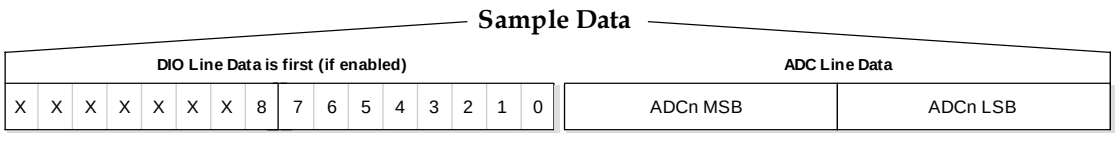
I/O data begins with a header. The first byte of the header defines the number of samples forthcoming. A sample is comprised of input data and the inputs can contain either DIO or ADC. The last 2 bytes of the header (Channel Indicator) define which inputs are active. Each bit represents either a DIO line or ADC channel.

Figure 2-04. Header


Header
Byte 1
Bytes 2 - 3 (Channel Indicator)
Total number of samples
na A5 A4 A3 A2 A1 A0 D8 D7 D6 D5 D4 D3 D2 D1 D0
bit 15
bit 0
Bit set to '1' if channel is active

Sample data follows the header and the channel indicator frame is used to determine how to read the sample data. If any of the DIO lines are enabled, the first 2 bytes are the DIO data and the ADC data follows. ADC channel data is stored as an unsigned 10-bit value right-justified on a 16-bit boundary.

Figure 2-05. Sample Data



2.2.2. API Support

I/O data is sent out the UART using an API frame. All other data can be sent and received using Transparent Operation [refer to p10] or API framing if API mode is enabled (AP > 0).

API Operations support two RX (Receive) frame identifiers for I/O data:

- 0x82 for RX (Receive) Packet: 64-bit address I/O
- 0x83 for RX (Receive) Packet: 16-bit address I/O

The API command header is the same as shown in the "RX (Receive) Packet: 64-bit Address" and "RX (Receive) Packet: 64-bit Address" API types [refer to p58]. RX data follows the format described in the I/O Data Format section [p12].

Applicable Commands: AP (API Enable)

2.2.3. Sleep Support

When an RF module wakes, it will always do a sample based on any active ADC or DIO lines. This allows sampling based on the sleep cycle whether it be Cyclic Sleep (SM parameter = 4 or 5) or Pin Sleep (SM = 1 or 2). To gather more samples when awake, set the IR (Sample Rate) parameter.

For Cyclic Sleep modes: If the IR parameter is set, the module will stay awake until the IT (Samples before TX) parameter is met. The module will stay awake for ST (Time before Sleep) time.

Applicable Commands: IR (Sample Rate), IT (Samples before TX), SM (Sleep Mode), IC (DIO Change Detect)

2.2.4. DIO Pin Change Detect

When "DIO Change Detect" is enabled (using the IC command), DIO lines 0-7 are monitored. When a change is detected on a DIO line, the following will occur:

1. An RF packet is sent with the updated DIO pin levels. This packet will not contain any ADC samples.
2. Any queued samples are transmitted before the change detect data. This may result in receiving a packet with less than IT (Samples before TX) samples.

Note: Change detect will not affect Pin Sleep wake-up. The D8 pin (DTR/Sleep_RQ/DI8) is the only line that will wake a module from Pin Sleep. If not all samples are collected, the module will still enter Sleep Mode after a change detect packet is sent.

Applicable Commands: IC (DIO Change Detect), IT (Samples before TX)

NOTE: Change detect is only supported when the Dx (DIOx Configuration) parameter equals 3,4 or 5.

2.2.5. Sample Rate (Interval)

The Sample Rate (Interval) feature allows enabled ADC and DIO pins to be read periodically on modules that are not configured to operate in Sleep Mode. When one of the Sleep Modes is enabled and the IR (Sample Rate) parameter set, the module will stay awake until IT (Samples before TX) samples have been collected.

Once a particular pin is enabled, the appropriate sample rate must be chosen. The maximum sample rate that can be achieved while using one A/D line is 1 sample/ms or 1 KHz (Note that the modem will not be able to keep up with transmission when IR & IT are equal to "1").

Applicable Commands: IR (Sample Rate), IT (Samples before TX), SM (Sleep Mode)

2.2.6. I/O Line Passing

Virtual wires can be set up between XBee/XBee-PRO Modules. When an RF data packet is received that contains I/O data, the receiving module can be setup to update any enabled outputs (PWM and DIO) based on the data it receives.

Note that I/O lines are mapped in pairs. For example: AD0 can only update PWM0 and DI5 can only update DO5). The default setup is for outputs not to be updated, which results in the I/O data being sent out the UART (refer to the IU (Enable I/O Output) command). To enable the outputs to be updated, the IA (I/O Input Address) parameter must be setup with the address of the module that has the appropriate inputs enabled. This effectively binds the outputs to a particular module's input. This does not affect the ability of the module to receive I/O line data from other modules - only its ability to update enabled outputs. The IA parameter can also be setup to accept I/O data for output changes from any module by setting the IA parameter to 0xFFFF.

When outputs are changed from their non-active state, the module can be setup to return the output level to it non-active state. The timers are set using the Tn (Dn Output Timer) and PT (PWM Output Timeout) commands. The timers are reset every time a valid I/O packet (passed IA check) is received. The IC (Change Detect) and IR (Sample Rate) parameters can be setup to keep the output set to their active output if the system needs more time than the timers can handle.

Note: DI8 can not be used for I/O line passing.

Applicable Commands: IA (I/O Input Address), Tn (Dn Output Timeout), P0 (PWM0 Configuration), P1 (PWM1 Configuration), M0 (PWM0 Output Level), M1 (PWM1 Output Level), PT (PWM Output Timeout), RP (RSSSI PWM Timer)

2.2.7. Configuration Example

As an example for a simple A/D link, a pair of RF modules could be set as follows:

Remote Configuration	Base Configuration
DL = 0x1234	DL = 0x5678
MY = 0x5678	MY = 0x1234
D0 = 2	P0 = 2
D1 = 2	P1 = 2
IR = 0x14	IU = 1
IT = 5	IA = 0x5678 (or 0xFFFF)

These settings configure the remote module to sample AD0 and AD1 once each every 20 ms. It then buffers 5 samples each before sending them back to the base module. The base should then receive a 32-Byte transmission (20 Bytes data and 12 Bytes framing) every 100 ms.

2.3. XBee/XBee-PRO Networks

The following IEEE 802.15.4 network types are supported by the XBee/XBee-PRO RF modules:

- NonBeacon
- NonBeacon (w/ Coordinator)

The following terms will be used to explicate the network operations:

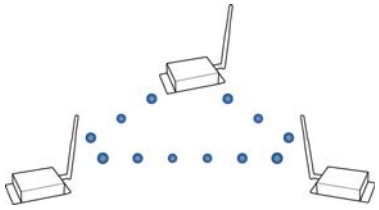
Table 2-02. Terms and definitions

Term	Definition
PAN	Personal Area Network - A data communication network that includes one or more End Devices and optionally a Coordinator.
Coordinator	A Full-function device (FFD) that provides network synchronization by polling nodes [NonBeacon (w/ Coordinator) networks only]
End Device	*When in the same network as a Coordinator* - RF modules that rely on a Coordinator for synchronization and can be put into states of sleep for low-power applications.
Association	The establishment of membership between End Devices and a Coordinator. Association is only applicable in NonBeacon (w/Coordinator) networks.

2.3.1. NonBeacon

By default, XBee/XBee-PRO RF Modules are configured to support NonBeacon communications. NonBeacon systems operate within a Peer-to-Peer network topology and therefore are not dependent upon Master/Slave relationships. This means that modules remain synchronized without use of master/server configurations and each module in the network shares both roles of master and slave. MaxStream's peer-to-peer architecture features fast synchronization times and fast cold start times. This default configuration accommodates a wide range of RF data applications.

Figure 2-06. NonBeacon Peer-to-Peer Architecture



A peer-to-peer network can be established by configuring each module to operate as an End Device (CE = 0), disabling End Device Association on all modules (A1 = 0) and setting ID and CH parameters to be identical across the network.

2.3.2. NonBeacon (w/ Coordinator)

A device is configured as a Coordinator by setting the CE (Coordinator Enable) parameter to “1”. Coordinator power-up is governed by the A2 (Coordinator Association) parameter.

In a NonBeacon (w/ Coordinator) system, the Coordinator can be configured to use direct or indirect transmissions. If the SP (Cyclic Sleep Period) parameter is set to “0”, the Coordinator will send data immediately. Otherwise, the SP parameter determines the length of time the Coordinator will retain the data before discarding it. Generally, SP (Cyclic Sleep Period) and ST (Time before Sleep) parameters should be set to match the SP and ST settings of the End Devices.

Association plays a critical role in the implementation of a NonBeacon (w/ Coordinator) system. Refer to the Association section [next page] for more information.

2.3.3. Association

Association is the establishment of membership between End Devices and a Coordinator and is only applicable in NonBeacon (w/ Coordinator) networks. The establishment of membership is useful in scenarios that require a central unit (Coordinator) to relay messages to or gather data from several remote units (End Devices), assign channels or assign PAN IDs.

An RF data network that consists of one Coordinator and one or more End Devices forms a PAN (Personal Area Network). Each device in a PAN has a PAN Identifier [ID (PAN ID) parameter]. PAN IDs must be unique to prevent miscommunication between PANs. The Coordinator PAN ID is set using the ID (PAN ID) and A2 (Coordinator Association) commands.

An End Device can associate to a Coordinator without knowing the address, PAN ID or channel of the Coordinator. The A1 (End Device Association) parameter bit fields determine the flexibility of an End Device during association. The A1 parameter can be used for an End Device to dynamically set its destination address, PAN ID and/or channel.

For example: If the PAN ID of a Coordinator is known, but the operating channel is not; the A1 command on the End Device should be set to enable the 'Auto_Associate' and 'Reassign_Channel' bits. Additionally, the ID parameter should be set to match the PAN ID of the associated Coordinator.

Coordinator / End Device Setup and Operation

To configure a module to operate as a Coordinator, set the CE (Coordinator Enable) parameter to '1'. Set the CE parameter of End Devices to '0' (default). Coordinator and End Devices should contain matching firmware versions.

NonBeacon (w/ Coordinator) Systems

In a NonBeacon (w/ Coordinator) system, the Coordinator can be configured to use direct or indirect transmissions. If the SP (Cyclic Sleep Period) parameter is set to '0', the Coordinator will send data immediately. Otherwise, the SP parameter determines the length of time the Coordinator will retain the data before discarding it. Generally, SP (Cyclic Sleep Period) and ST (Time before Sleep) parameters should be set to match the SP and ST settings of the End Devices.

Coordinator Power-up

Coordinator power-up is governed by the A2 (Coordinator Association) command. On power-up, the Coordinator undergoes the following sequence of events:

1. **Check A2 parameter- Reassign_PANID Flag**

   Set (bit 0 = 1) - The Coordinator issues an Active Scan. The Active Scan selects one channel and transmits a BeaconRequest command to the broadcast address (0xFFFF) and broadcast PAN ID (0xFFFF). It then listens on that channel for beacons from any Coordinator operating on that channel. The listen time on each channel is determined by the SD (Scan Duration) parameter value.

   Once the time expires on that channel, the Active Scan selects another channel and again transmits the BeaconRequest as before. This process continues until all channels have been scanned, or until 5 PANs have been discovered. When the Active Scan is complete, the results include a list of PAN IDs and Channels that are being used by other PANs. This list is used to assign an unique PAN ID to the new Coordinator. The ID parameter will be retained if it is not found in the Active Scan results. Otherwise, the ID (PAN ID) parameter setting will be updated to a PAN ID that was not detected.

   Not Set (bit 0 = 0) - The Coordinator retains its ID setting. No Active Scan is performed.

2. Check A2 parameter - Reassign_Channel Flag (bit 1)

Set (bit 1 = 1) - The Coordinator issues an Energy Scan. The Energy Scan selects one channel and scans for energy on that channel. The duration of the scan is specified by the SD (Scan Duration) parameter. Once the scan is completed on a channel, the Energy Scan selects the next channel and begins a new scan on that channel. This process continues until all channels have been scanned.

When the Energy Scan is complete, the results include the maximal energy values detected on each channel. This list is used to determine a channel where the least energy was detected. If an Active Scan was performed (Reassign_PANID Flag set), the channels used by the detected PANs are eliminated as possible channels. Thus, the results of the Energy Scan and the Active Scan (if performed) are used to find the best channel (channel with the least energy that is not used by any detected PAN). Once the best channel has been selected, the CH (Channel) parameter value is updated to that channel.

Not Set (bit 1 = 0) - The Coordinator retains its CH setting. An Energy Scan is not performed.

3. Start Coordinator

The Coordinator starts on the specified channel (CH parameter) and PAN ID (ID parameter). Note, these may be selected in steps 1 and/or 2 above. The Coordinator will only allow End Devices to associate to it if the A2 parameter “AllowAssociation” flag is set. Once the Coordinator has successfully started, the Associate LED will blink 1 time per second. (The LED is solid if the Coordinator has not started.)

4. Coordinator Modifications

Once a Coordinator has started:
Modifying the A2 (Reassign_Channel or Reassign_PANID bits), ID, CH or MY parameters will cause the Coordinator’s MAC to reset (The Coordinator RF module (including volatile RAM) is not reset). Changing the A2 AllowAssociation bit will not reset the Coordinator’s MAC. In a non-beaconing system, End Devices that associated to the Coordinator prior to a MAC reset will have knowledge of the new settings on the Coordinator. Thus, if the Coordinator were to change its ID, CH or MY settings, the End Devices would no longer be able to communicate with the non-beacon Coordinator. Once a Coordinator has started, the ID, CH, MY or A2 (Reassign_Channel or Reassign_PANID bits) should not be changed.

End Device Power-up

End Device power-up is governed by the A1 (End Device Association) command. On power-up, the End Device undergoes the following sequence of events:

1. Check A1 parameter - AutoAssociate Bit

Set (bit 2 = 1) - End Device will attempt to associate to a Coordinator. (refer to steps 2-3).

Not Set (bit 2 = 0) - End Device will not attempt to associate to a Coordinator. The End Device will operate as specified by its ID, CH and MY parameters. Association is considered complete and the Associate LED will blink quickly (5 times per second). When the AutoAssociate bit is not set, the remaining steps (2-3) do not apply.

2. Discover Coordinator (if Auto-Associate Bit Set)

The End Device issues an Active Scan. The Active Scan selects one channel and transmits a BeaconRequest command to the broadcast address (0xFFFF) and broadcast PAN ID (0xFFFF). It then listens on that channel for beacons from any Coordinator operating on that channel. The listen time on each channel is determined by the SD parameter.

Once the time expires on that channel, the Active Scan selects another channel and again transmits the BeaconRequest command as before. This process continues until all channels have been scanned, or until 5 PANs have been discovered. When the Active Scan is complete, the results include a list of PAN IDs and Channels that are being used by detected PANs.

The End Device selects a Coordinator to associate with according to the A1 parameter "Reassign_PANID" and "Reassign_Channel" flags:

Reassign_PANID Bit Set (bit 0 = 1)- End Device can associate with a PAN with any ID value.

Reassign_PANID Bit Not Set (bit 0 = 0) - End Device will only associate with a PAN whose ID setting matches the ID setting of the End Device.

Reassign_Channel Bit Set (bit 1 = 1) - End Device can associate with a PAN with any CH value.

Reassign_Channel Bit Not Set (bit 1 = 0)- End Device will only associate with a PAN whose CH setting matches the CH setting of the End Device.

After applying these filters to the discovered Coordinators, if multiple candidate PANs exist, the End Device will select the PAN whose transmission link quality is the strongest. If no valid Coordinator is found, the End Device will either go to sleep (as dictated by its SM (Sleep Mode) parameter) or retry Association.

Note - An End Device will also disqualify Coordinators if they are not allowing association (A2 - AllowAssociation bit); or, if the Coordinator is not using the same NonBeacon scheme as the End Device. (They must both be programmed with NonBeacon code.)

3. Associate to Valid Coordinator

Once a valid Coordinator is found (step 2), the End Device sends an AssociationRequest message to the Coordinator. It then waits for an AssociationConfirmation to be sent from the Coordinator. Once the Confirmation is received, the End Device is Associated and the Associate LED will blink rapidly (2 times per second). The LED is solid if the End Device has not associated.

4. End Device Changes once an End Device has associated

Changing A1, ID or CH parameters will cause the End Device to disassociate and restart the Association procedure.

If the End Device fails to associate, the AI command can give some indication of the failure.

2.4. XBee / XBee-PRO Addressing

Every RF data packet sent over-the-air contains a Source Address and Destination Address field in its header. The RF module conforms to the 802.15.4 specification and supports both short 16-bit addresses and long 64-bit addresses. A unique 64-bit IEEE source address is assigned at the factory and can be read with the SL (Serial Number Low) and SH (Serial Number High) commands. Short addressing must be configured manually. A module will use its unique 64-bit address as its Source Address if its MY (16-bit Source Address) value is “0xFFFF” or “0xFFFE”.

To send a packet to a specific module using 64-bit addressing: Set Destination Address (DL + DH) to match the Source Address (SL + SH) of the intended destination module.

To send a packet to a specific module using 16-bit addressing: Set DL (Destination Address Low) parameter to equal the MY parameter and set the DH (Destination Address High) parameter to ‘0’.

2.4.1. Unicast Mode

By default, the RF module operates in Unicast Mode. Unicast Mode is the only mode that supports retries. While in this mode, receiving modules send an ACK (acknowledgement) of RF packet reception to the transmitter. If the transmitting module does not receive the ACK, it will re-send the packet up to three times or until the ACK is received.

Short 16-bit addresses. The module can be configured to use short 16-bit addresses as the Source Address by setting (MY < 0xFFFE). Setting the DH parameter (DH = 0) will configure the Destination Address to be a short 16-bit address (if DL < 0xFFFE). For two modules to communicate using short addressing, the Destination Address of the transmitter module must match the MY parameter of the receiver.

The following table shows a sample network configuration that would enable Unicast Mode communications using short 16-bit addresses.

Table 2-03. Sample Unicast Network Configuration (using 16-bit addressing)

Parameter	RF Module 1	RF Module 2
MY (Source Address)	0x01	0x02
DH (Destination Address High)	0	0
DL (Destination Address Low)	0x02	0x01

Long 64-bit addresses. The RF module’s serial number (SL parameter concatenated to the SH parameter) can be used as a 64-bit source address when the MY (16-bit Source Address) parameter is disabled. When the MY parameter is disabled (set MY = 0xFFFF or 0xFFFE), the module’s source address is set to the 64-bit IEEE address stored in the SH and SL parameters.

When an End Device associates to a Coordinator, its MY parameter is set to 0xFFFE to enable 64-bit addressing. The 64-bit address of the module is stored as SH and SL parameters. To send a packet to a specific module, the Destination Address (DL + DH) on one module must match the Source Address (SL + SH) of the other.

2.4.2. Broadcast Mode

Any RF module within range will accept a packet that contains a broadcast address. When configured to operate in Broadcast Mode, receiving modules do not send ACKs (Acknowledgements) and transmitting modules do not automatically re-send packets as is the case in Unicast Mode.

To send a broadcast packet to all modules regardless of 16-bit or 64-bit addressing, set the destination addresses of all the modules as shown below.

Sample Network Configuration (All modules in the network):

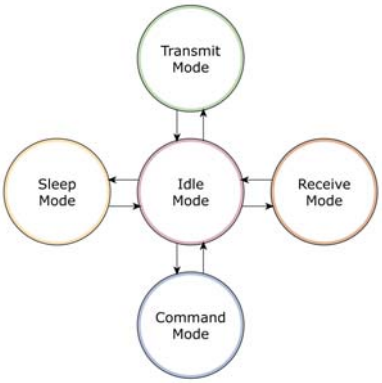
- DL (Destination Low Address) = 0x0000FFFF
- DH (Destination High Address) = 0x00000000 (default value)

NOTE: When programming the module, parameters are entered in hexadecimal notation (without the “0x” prefix). Leading zeros may be omitted.

2.5. Modes of Operation

XBee/XBee-PRO RF Modules operate in five modes.

Figure 2-07. Modes of Operation



2.5.1. Idle Mode

When not receiving or transmitting data, the RF module is in Idle Mode. The module shifts into the other modes of operation under the following conditions:

- Transmit Mode (Serial data is received in the DI Buffer)
- Receive Mode (Valid RF data is received through the antenna)
- Sleep Mode (Sleep Mode condition is met)
- Command Mode (Command Mode Sequence is issued)

2.5.2. Transmit/Receive Modes

RF Data Packets

Each transmitted data packet contains a Source Address and Destination Address field. The Source Address matches the address of the transmitting module as specified by the MY (Source Address) parameter (if MY >= 0xFFFE), the SH (Serial Number High) parameter or the SL (Serial Number Low) parameter. The <Destination Address> field is created from the DH (Destination Address High) and DL (Destination Address Low) parameter values. The Source Address and/or Destination Address fields will either contain a 16-bit short or long 64-bit long address.

The RF data packet structure follows the 802.15.4 specification.

[Refer to the XBee/XBee-PRO Addressing section for more information]

Direct and Indirect Transmission

There are two methods to transmit data:

- Direct Transmission - data is transmitted immediately to the Destination Address
- Indirect Transmission - A packet is retained for a period of time and is only transmitted after the destination module (Source Address = Destination Address) requests the data.

Indirect Transmissions can only occur on a Coordinator. Thus, if all nodes in a network are End Devices, only Direct Transmissions will occur. Indirect Transmissions are useful to ensure packet delivery to a sleeping node. The Coordinator currently is able to retain up to 2 indirect messages.

Direct Transmission

A NonBeaconing Coordinator can be configured to use only Direct Transmission by setting the SP (Cyclic Sleep Period) parameter to "0". Also, a NonBeaconing Coordinator using indirect transmissions will revert to direct transmission if it knows the destination module is awake.

To enable this behavior, the ST (Time before Sleep) value of the Coordinator must be set to match the ST value of the End Device. Once the End Device either transmits data to the Coordinator or polls the Coordinator for data, the Coordinator will use direct transmission for all subsequent data transmissions to that module address until ST time (or number of beacons) occurs with no activity (at which point it will revert to using indirect transmissions for that module address). "No activity" means no transmission or reception of messages with a specific address. Global messages will not reset the ST timer.

Indirect Transmission

To configure Indirect Transmissions in a PAN (Personal Area Network), the SP (Cyclic Sleep Period) parameter value on the Coordinator must be set to match the longest sleep value of any End Device. The SP parameter represents time in NonBeacon systems and beacons in Beacon-enabled systems. The sleep period value on the Coordinator determines how long (time or number of beacons) the Coordinator will retain an indirect message before discarding it.

In NonBeacon networks, an End Device must poll the Coordinator once it wakes from Sleep to determine if the Coordinator has an indirect message for it. For Cyclic Sleep Modes, this is done automatically every time the module wakes (after SP time). For Pin Sleep Modes, the A1 (End Device Association) parameter value must be set to enable Coordinator polling on pin wake-up. Alternatively, an End Device can use the FP (Force Poll) command to poll the Coordinator as needed.

CCA (Clear Channel Assessment)

Prior to transmitting a packet, a CCA (Clear Channel Assessment) is performed on the channel to determine if the channel is available for transmission. The detected energy on the channel is compared with the CA (Clear Channel Assessment) parameter value. If the detected energy exceeds the CA parameter value, the packet is not transmitted.

Also, a delay is inserted before a transmission takes place. This delay is settable using the RN (Backoff Exponent) parameter. If RN is set to "0", then there is no delay before the first CCA is performed. The RN parameter value is the equivalent of the "minBE" parameter in the 802.15.4 specification. The transmit sequence follows the 802.15.4 specification.

By default, the MM (MAC Mode) parameter = 0. On a CCA failure, the module will attempt to resend the packet up to two additional times.

When in Unicast packets with RR (Retries) = 0, the module will execute two CCA retries. Broadcast packets always get two CCA retries.

Acknowledgement

If the transmission is not a broadcast message, the module will expect to receive an acknowledgement from the destination node. If an acknowledgement is not received, the packet will be resent up to 3 more times. If the acknowledgement is not received after all transmissions, an ACK failure is recorded.

2.5.3. Sleep Mode

Sleep Modes enable the RF module to enter states of low-power consumption when not in use. In order to enter Sleep Mode, one of the following conditions must be met (in addition to the module having a non-zero SM parameter value):

- Sleep_RQ (pin 9) is asserted.
- The module is idle (no data transmission or reception) for the amount of time defined by the ST (Time before Sleep) parameter. [NOTE: ST is only active when SM = 4-5.]

Table 2-04. Sleep Mode Configurations

Sleep Mode Setting	Transition into Sleep Mode	Transition out of Sleep Mode (wake)	Characteristics	Related Commands	Power Consumption
Pin Hibernate (SM = 1)	Assert (high) Sleep_RQ (pin 9)	De-assert (low) Sleep_RQ	Pin/Host-controlled / NonBeacon systems only / Lowest Power	(SM)	< 10 µA (@3.0 VCC)
Pin Doze (SM = 2)	Assert (high) Sleep_RQ (pin 9)	De-assert (low) Sleep_RQ	Pin/Host-controlled / NonBeacon systems only / Fastest wake-up	(SM)	< 50 µA
Cyclic Sleep (SM = 4 - 5)	Automatic transition to Sleep Mode as defined by the SM (Sleep Mode) and ST (Time before Sleep) parameters.	Transition occurs after the cyclic sleep time interval elapses. The time interval is defined by the SP (Cyclic Sleep Period) parameter.	RF module wakes in pre-determined time intervals to detect if RF data is present / When SM = 5, NonBeacon systems only	(SM), SP, ST	< 50 µA when sleeping

The SM command is central to setting Sleep Mode configurations. By default, Sleep Modes are disabled (SM = 0) and the module remains in Idle/Receive Mode. When in this state, the module is constantly ready to respond to serial or RF activity.

Higher Voltages. Sleep Mode current consumption is highly sensitive to voltage. Voltages above 3.0V will cause much higher current consumption.

Table 2-05. Sample Sleep Mode Currents

	XBee			XBee-PRO		
Vcc (V)	SM=1	SM=2	SM=4,5	SM=1	SM=2	SM=4,5
2.8–3.0	<3 µA	<35uA	<34uA	<4uA	<34uA	<34uA
3.1	8uA	37mA	36uA	12uA	39uA	37uA
3.2	32uA	48uA	49uA	45uA	60uA	55uA
3.3	101uA	83uA	100uA	130uA	115uA	120uA
3.4	255uA	170uA	240uA	310uA	260uA	290uA

Pin / Host-controlled Sleep Modes

The transient current when waking from pin sleep (SM = 1 or 2) does not exceed the idle current of the module. The current ramps up exponentially to its idle current.

Pin Hibernate (SM = 1)

- Pin/Host-controlled
- Typical power-down current: < 10 µA (@3.0 VCC)
- Wake-up time: 13.2 msec

Pin Hibernate Mode minimizes quiescent power (power consumed when in a state of rest or inactivity). This mode is voltage level-activated; when Sleep_RQ is asserted, the module will finish any transmit, receive or association activities, enter Idle Mode and then enter a state of sleep. The module will not respond to either serial or RF activity while in pin sleep.

To wake a sleeping module operating in Pin Hibernate Mode, de-assert Sleep_RQ (pin 9). The module will wake when Sleep_RQ is de-asserted and is ready to transmit or receive when the $\overline{\text{CTS}}$ line is low. When waking the module, the pin must be de-asserted at least two 'byte times' after $\overline{\text{CTS}}$ goes low. This assures that there is time for the data to enter the DI buffer.

Pin Doze (SM = 2)

- Pin/Host-controlled
- Typical power-down current: < 50 µA
- Wake-up time: 2 msec

Pin Doze Mode functions as does Pin Hibernate Mode; however, Pin Doze features faster wake-up time and higher power consumption.

To wake a sleeping module operating in Pin Doze Mode, de-assert Sleep_RQ (pin 9). The module will wake when Sleep_RQ is de-asserted and is ready to transmit or receive when the $\overline{\text{CTS}}$ line is low. When waking the module, the pin must be de-asserted at least two 'byte times' after $\overline{\text{CTS}}$ goes low. This assures that there is time for the data to enter the DI buffer.

Cyclic Sleep Modes

Cyclic Sleep Remote (SM = 4)

- Typical Power-down Current: < 50 µA (when asleep)
- Wake-up time: 2 msec

The Cyclic Sleep Modes allow modules to periodically check for RF data. When the SM parameter is set to '4', the module is configured to sleep, then wakes once a cycle to check for data from a module configured as a Cyclic Sleep Coordinator (SM = 0, CE = 1). The Cyclic Sleep Remote sends a poll request to the coordinator at a specific interval set by the SP (Cyclic Sleep Period) parameter. The coordinator will transmit any queued data addressed to that specific remote upon receiving the poll request.

If no data is queued for the remote, the coordinator will not transmit and the remote will return to sleep for another cycle. If queued data is transmitted back to the remote, it will stay awake to allow for back and forth communication until the ST (Time before Sleep) timer expires.

Also note that $\overline{\text{CTS}}$ will go low each time the remote wakes, allowing for communication initiated by the remote host if desired.

Cyclic Sleep Remote with Pin Wake-up (SM = 5)

Use this mode to wake a sleeping remote module through either the RF interface or by the de-assertion of Sleep_RQ for event-driven communications. The cyclic sleep mode works as described above (Cyclic Sleep Remote) with the addition of a pin-controlled wake-up at the remote module. The Sleep_RQ pin is edge-triggered, not level-triggered. The module will wake when a low is detected then set $\overline{\text{CTS}}$ low as soon as it is ready to transmit or receive.

Any activity will reset the ST (Time before Sleep) timer so the module will go back to sleep only after there is no activity for the duration of the timer. Once the module wakes (pin-controlled), further pin activity is ignored. The module transitions back into sleep according to the ST time regardless of the state of the pin.

[Cyclic Sleep Coordinator (SM = 6)]

- Typical current = Receive current
- Always awake

NOTE: The SM=6 parameter value exists solely for backwards compatibility with firmware version 1.x60. If backwards compatibility with the older firmware version is not required, always use the CE (Coordinator Enable) command to configure a module as a Coordinator.

This mode configures a module to wake cyclic sleeping remotes through RF interfacing. The Coordinator will accept a message addressed to a specific remote 16 or 64-bit address and hold it in a buffer until the remote wakes and sends a poll request. Messages not sent directly (buffered and requested) are called "Indirect messages". The Coordinator only queues one indirect message at a time. The Coordinator will hold the indirect message for a period 2.5 times the sleeping period indicated by the SP (Cyclic Sleep Period) parameter. The Coordinator's SP parameter should be set to match the value used by the remotes.

2.5.4. Command Mode

To modify or read RF Module parameters, the module must first enter into Command Mode - a state in which incoming characters are interpreted as commands. Two Command Mode options are supported: AT Command Mode [refer to section below] and API Command Mode [p54].

AT Command Mode

To Enter AT Command Mode:

Send the 3-character command sequence "+++" and observe guard times before and after the command characters. [Refer to the "Default AT Command Mode Sequence" below.]

Default AT Command Mode Sequence (for transition to Command Mode):

- No characters sent for one second [GT (Guard Times) parameter = 0x3E8]
- Input three plus characters ("+++") within one second [CC (Command Sequence Character) parameter = 0x2B.]
- No characters sent for one second [GT (Guard Times) parameter = 0x3E8]

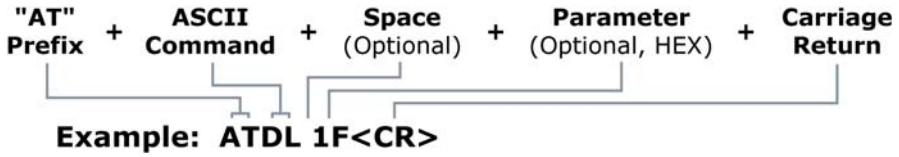
All of the parameter values in the sequence can be modified to reflect user preferences.

NOTE: Failure to enter AT Command Mode is most commonly due to baud rate mismatch. Ensure the 'Baud' setting on the "PC Settings" tab matches the interface data rate of the RF module. By default, the BD parameter = 3 (9600 bps).

To Send AT Commands:

Send AT commands and parameters using the syntax shown below.

Figure 2-08. Syntax for sending AT Commands



To read a parameter value stored in the RF module's register, omit the parameter field.

The preceding example would change the RF module Destination Address (Low) to "0x1F". To store the new value to non-volatile (long term) memory, subsequently send the WR (Write) command.

For modified parameter values to persist in the module's registry after a reset, changes must be saved to non-volatile memory using the WR (Write) Command. Otherwise, parameters are restored to previously saved values after the module is reset.

System Response. When a command is sent to the module, the module will parse and execute the command. Upon successful execution of a command, the module returns an "OK" message. If execution of a command results in an error, the module returns an "ERROR" message.

To Exit AT Command Mode:

1. Send the ATCN (Exit Command Mode) command (followed by a carriage return).

   [OR]

2. If no valid AT Commands are received within the time specified by CT (Command Mode Timeout) Command, the RF module automatically returns to Idle Mode.

For an example of programming the RF module using AT Commands and descriptions of each configurable parameter, refer to the RF Module Configuration chapter [p25].

3. RF Module Configuration

3.1. Programming the RF Module

Refer to the Command Mode section [p24] for more information about entering Command Mode, sending AT commands and exiting Command Mode. For information regarding module programming using API Mode, refer to the API Operation sections [p54].

3.1.1. Programming Examples

Refer to the 'X-CTU' section of the Development Guide [Appendix B] for more information regarding the X-CTU configuration software.

Setup

The programming examples in this section require the installation of MaxStream's X-CTU Software and a serial connection to a PC. (MaxStream stocks RS-232 and USB boards to facilitate interfacing with a PC.)

1. Install MaxStream's X-CTU Software to a PC by double-clicking the "setup_X-CTU.exe" file. (The file is located on the MaxStream CD and under the 'Software' section of the following web page: www.maxstream.net/support/downloads.php)
2. Mount the RF module to an interface board, then connect the module assembly to a PC.
3. Launch the X-CTU Software and select the 'PC Settings' tab. Verify the baud and parity settings of the Com Port match those of the RF module.

NOTE: Failure to enter AT Command Mode is most commonly due to baud rate mismatch. Ensure the 'Baud' setting on the 'PC Settings' tab matches the interface data rate of the RF module. By default, the BD parameter = 3 (which corresponds to 9600 bps).

Sample Configuration: Modify RF Module Destination Address

Example: Utilize the X-CTU "Terminal" tab to change the RF module's DL (Destination Address Low) parameter and save the new address to non-volatile memory.

After establishing a serial connection between the RF module and a PC [refer to the 'Setup' section above], select the "Terminal" tab of the X-CTU Software and enter the following command lines ('CR' stands for carriage return):

Method 1 (One line per command)

Send AT Command	System Response
+++	OK <CR> (Enter into Command Mode)
ATDL <Enter>	{current value} <CR> (Read Destination Address Low)
ATDL1A0D <Enter>	OK <CR> (Modify Destination Address Low)
ATWR <Enter>	OK <CR> (Write to non-volatile memory)
ATCN <Enter>	OK <CR> (Exit Command Mode)

Method 2 (Multiple commands on one line)

Send AT Command	System Response
+++	OK <CR> (Enter into Command Mode)
ATDL <Enter>	{current value} <CR> (Read Destination Address Low)
ATDL1A0D,WR,CN <Enter>	OK<CR> OK<CR> OK<CR>

Sample Configuration: Restore RF Module Defaults

Example: Utilize the X-CTU "Modem Configuration" tab to restore default parameter values.

After establishing a connection between the module and a PC [refer to the 'Setup' section above], select the "Modem Configuration" tab of the X-CTU Software.

1. Select the 'Read' button.
2. Select the 'Restore' button.

3.2. Command Reference Tables

XBee/XBee-PRO RF Modules expect numerical values in hexadecimal. Hexadecimal values are designated by a "0x" prefix. Decimal equivalents are designated by a "d" suffix. Commands are contained within the following command categories (listed in the order that their tables appear):

- Special
- Networking & Security
- RF Interfacing
- Sleep (Low Power)
- Serial Interfacing
- I/O Settings
- Diagnostics
- AT Command Options

All modules within a PAN should operate using the same firmware version.

Special

Table 3-01. XBee-PRO Commands - Special

AT Command	Command Category	Name and Description	Parameter Range	Default
WR	Special	Write. Write parameter values to non-volatile memory so that parameter modifications persist through subsequent power-up or reset. Note: Once WR is issued, no additional characters should be sent to the module until after the response "OK\r" is received.	-	-
RE	Special	Restore Defaults. Restore module parameters to factory defaults.	-	-
FR (v1.x80*)	Special	Software Reset. Responds immediately with an OK then performs a hard reset ~100ms later.	-	-

* Firmware version in which the command was first introduced (firmware versions are numbered in hexadecimal notation.)

Networking & Security

Table 3-02. XBee/XBee-PRO Commands - Networking & Security (Sub-categories designated within {brackets})

AT Command	Command Category	Name and Description	Parameter Range	Default
CH	Networking {Addressing}	Channel. Set/Read the channel number used for transmitting and receiving data between RF modules (uses 802.15.4 protocol channel numbers).	0x0B - 0x1A (XBee) 0x0C - 0x17 (XBee-PRO)	0x0C (12d)
ID	Networking {Addressing}	PAN ID. Set/Read the PAN (Personal Area Network) ID. Use 0xFFFF to broadcast messages to all PANs.	0 - 0xFFFF	0x3332 (13106d)
DH	Networking {Addressing}	Destination Address High. Set/Read the upper 32 bits of the 64-bit destination address. When combined with DL, it defines the destination address used for transmission. To transmit using a 16-bit address, set DH parameter to zero and DL less than 0xFFFF. 0x000000000000FFFF is the broadcast address for the PAN.	0 - 0xFFFFFFFF	0
DL	Networking {Addressing}	Destination Address Low. Set/Read the lower 32 bits of the 64-bit destination address. When combined with DH, DL defines the destination address used for transmission. To transmit using a 16-bit address, set DH parameter to zero and DL less than 0xFFFF. 0x000000000000FFFF is the broadcast address for the PAN.	0 - 0xFFFFFFFF	0
MY	Networking {Addressing}	16-bit Source Address. Set/Read the RF module 16-bit source address. Set MY = 0xFFFF to disable reception of packets with 16-bit addresses. 64-bit source address (serial number) and broadcast address (0x000000000000FFFF) is always enabled.	0 - 0xFFFF	0
SH	Networking {Addressing}	Serial Number High. Read high 32 bits of the RF module's unique IEEE 64-bit address. 64-bit source address is always enabled.	0 - 0xFFFFFFFF [read-only]	Factory-set
SL	Networking {Addressing}	Serial Number Low. Read low 32 bits of the RF module's unique IEEE 64-bit address. 64-bit source address is always enabled.	0 - 0xFFFFFFFF [read-only]	Factory-set
RR (v1.xA0*)	Networking {Addressing}	XBee Retries. Set/Read the maximum number of retries the module will execute in addition to the 3 retries provided by the 802.15.4 MAC. For each XBee retry, the 802.15.4 MAC can execute up to 3 retries.	0 - 6	0
RN	Networking {Addressing}	Random Delay Slots. Set/Read the minimum value of the back-off exponent in the CSMA-CA algorithm that is used for collision avoidance. If RN = 0, collision avoidance is disabled during the first iteration of the algorithm (802.15.4 - macMinBE).	0 - 3 [exponent]	0
MM (v1.x80*)	Networking {Addressing}	MAC Mode. Set/Read MAC Mode value. MAC Mode enables/disables the use of a MaxStream header in the 802.15.4 RF packet. When Mode 0 is enabled (MM=0), duplicate packet detection is enabled as well as certain AT commands. Modes 1 and 2 are strict 802.15.4 modes.	0 - 2 0 = MaxStream Mode 1 = 802.15.4 (no ACKs) 2 = 802.15.4 (with ACKs)	0

Table 3-02. XBee/XBee-PRO Commands - Networking & Security (Sub-categories designated within {brackets})

AT Command	Command Category	Name and Description	Parameter Range	Default
NI (v1.x80*)	Networking {Identification}	Node Identifier. Stores a string identifier. The register only accepts printable ASCII data. A string can not start with a space. Carriage return ends command. Command will automatically end when maximum bytes for the string have been entered. This string is returned as part of the ND (Node Discover) command. This identifier is also used with the DN (Destination Node) command.	20-character ASCII string	-
ND (v1.x80*)	Networking {Identification}	Node Discover. Discovers and reports all RF modules found. The following information is reported for each module discovered (the example cites use of Transparent operation (AT command format) - refer to the long ND command description regarding differences between Transparent and API operation). MY<CR> SH<CR> SL<CR> DB<CR> NI<CR><CR> The amount of time the module allows for responses is determined by the NT parameter. In Transparent operation, command completion is designated by a <CR> (carriage return). ND also accepts a Node Identifier as a parameter. In this case, only a module matching the supplied identifier will respond.	optional 20-character NI value	
NT (v1.xA0*)	Networking {Identification}	Node Discover Time. Set/Read the amount of time a node will wait for responses from other nodes when using the ND (Node Discover) command.	0x01 - 0xFC	0x19
DN (v1.x80*)	Networking {Identification}	Destination Node. Resolves an NI (Node Identifier) string to a physical address. The following events occur upon successful command execution: 1. DL and DH are set to the address of the module with the matching Node Identifier. 2. "OK" is returned. 3. RF module automatically exits AT Command Mode If there is no response from a module within 200 msec or a parameter is not specified (left blank), the command is terminated and an "ERROR" message is returned.	20-character ASCII string	-
CE (v1.x80*)	Networking {Association}	Coordinator Enable. Set/Read the coordinator setting.	0 - 1 0 = End Device 1 = Coordinator	0
SC (v1.x80*)	Networking {Association}	Scan Channels. Set/Read list of channels to scan for all Active and Energy Scans as a bitfield. This affects scans initiated in command mode (AS, ED) and during End Device Association and Coordinator startup: bit 0 - 0x0B bit 4 - 0x0F bit 8 - 0x13 bit12 - 0x17 bit 1 - 0x0C bit 5 - 0x10 bit 9 - 0x14 bit13 - 0x18 bit 2 - 0x0D bit 6 - 0x11 bit 10 - 0x15 bit14 - 0x19 bit 3 - 0x0E bit 7 - 0x12 bit 11 - 0x16 bit 15 - 0x1A	0 - 0xFFFF [bitfield] (bits 0, 14, 15 not allowed on the XBee-PRO)	0x1FFE (all XBee-PRO Channels)
SD (v1.x80*)	Networking {Association}	Scan Duration. Set/Read the scan duration exponent. *End Device* - Duration of Active Scan during Association. On beacon system, set SD = BE of coordinator. SD must be set at least to the highest BE parameter of any Beaconing Coordinator with which an End Device or Coordinator wish to discover. *Coordinator* - If 'ReassignPANID' option is set on Coordinator [refer to A2 parameter], SD determines the length of time the Coordinator will scan channels to locate existing PANs. If 'ReassignChannel' option is set, SD determines how long the Coordinator will perform an Energy Scan to determine which channel it will operate on. 'Scan Time' is measured as (# of channels to scan] * (2 ^ SD) * 15.36ms). The number of channels to scan is set by the SC command. The XBee can scan up to 16 channels (SC = 0xFFFF). The XBee PRO can scan up to 13 channels (SC = 0x3FFE). Example: The values below show results for a 13 channel scan: If SD = 0, time = 0.18 sec SD = 8, time = 47.19 sec SD = 2, time = 0.74 sec SD = 10, time = 3.15 min SD = 4, time = 2.95 sec SD = 12, time = 12.58 min SD = 6, time = 11.80 sec SD = 14, time = 50.33 min	0-0x0F [exponent]	4
A1 (v1.x80*)	Networking {Association}	End Device Association. Set/Read End Device association options. bit 0 - ReassignPanID 0 - Will only associate with Coordinator operating on PAN ID that matches module ID 1 - May associate with Coordinator operating on any PAN ID bit 1 - ReassignChannel 0 - Will only associate with Coordinator operating on matching CH Channel setting 1 - May associate with Coordinator operating on any Channel bit 2 - AutoAssociate 0 - Device will not attempt Association 1 - Device attempts Association until success Note: This bit is used only for Non-Beacon systems. End Devices in Beacon-enabled system must always associate to a Coordinator bit 3 - PollCoordOnPinWake 0 - Pin Wake will not poll the Coordinator for indirect (pending) data 1 - Pin Wake will send Poll Request to Coordinator to extract any pending data bits 4 - 7 are reserved	0 - 0x0F [bitfield]	0

Table 3-02. XBee/XBee-PRO Commands - Networking & Security (Sub-categories designated within {brackets})

AT Command	Command Category	Name and Description	Parameter Range	Default
A2 (v1.x80*)	Networking {Association}	Coordinator Association. Set/Read Coordinator association options. bit 0 - ReassignPanID 0 - Coordinator will not perform Active Scan to locate available PAN ID. It will operate on ID (PAN ID). 1 - Coordinator will perform Active Scan to determine an available ID (PAN ID). If a PAN ID conflict is found, the ID parameter will change. bit 1 - ReassignChannel - 0 - Coordinator will not perform Energy Scan to determine free channel. It will operate on the channel determined by the CH parameter. 1 - Coordinator will perform Energy Scan to find a free channel, then operate on that channel. bit 2 - AllowAssociation - 0 - Coordinator will not allow any devices to associate to it. 1 - Coordinator will allow devices to associate to it. bits 3 - 7 are reserved	0 - 7 [bitfield]	0
AI (v1.x80*)	Networking {Association}	Association Indication. Read errors with the last association request: 0x00 - Successful Completion - Coordinator successfully started or End Device association complete 0x01 - Active Scan Timeout 0x02 - Active Scan found no PANs 0x03 - Active Scan found PAN, but the CoordinatorAllowAssociation bit is not set 0x04 - Active Scan found PAN, but Coordinator and End Device are not configured to support beacons 0x05 - Active Scan found PAN, but the Coordinator ID parameter does not match the ID parameter of the End Device 0x06 - Active Scan found PAN, but the Coordinator CH parameter does not match the CH parameter of the End Device 0x07 - Energy Scan Timeout 0x08 - Coordinator start request failed 0x09 - Coordinator could not start due to invalid parameter 0x0A - Coordinator Realignment is in progress 0x0B - Association Request not sent 0x0C - Association Request timed out - no reply was received 0x0D - Association Request had an Invalid Parameter 0x0E - Association Request Channel Access Failure. Request was not transmitted - CCA failure 0x0F - Remote Coordinator did not send an ACK after Association Request was sent 0x10 - Remote Coordinator did not reply to the Association Request, but an ACK was received after sending the request 0x11 - [reserved] 0x12 - Sync-Loss - Lost synchronization with a Beaconing Coordinator 0x13 - Disassociated - No longer associated to Coordinator	0 - 0x13 [read-only]	-
DA (v1.x80*)	Networking {Association}	Force Disassociation. End Device will immediately disassociate from a Coordinator (if associated) and reattempt to associate.	-	-
FP (v1.x80*)	Networking {Association}	Force Poll. Request indirect messages being held by a coordinator.	-	-

Table 3-02. XBee/XBee-PRO Commands - Networking & Security (Sub-categories designated within {brackets})

AT Command	Command Category	Name and Description	Parameter Range	Default
AS (v1.x80*)	Networking {Association}	Active Scan. Send Beacon Request to Broadcast Address (0xFFFF) and Broadcast PAN (0xFFFF) on every channel. The parameter determines the time the radio will listen for Beacons on each channel. A PanDescriptor is created and returned for every Beacon received from the scan. Each PanDescriptor contains the following information: CoordAddress (SH, SL)<CR> CoordPanID (ID)<CR> CoordAddrMode <CR> 0x02 = 16-bit Short Address 0x03 = 64-bit Long Address Channel (CH parameter) <CR> SecurityUse<CR> ACLEntry<CR> SecurityFailure<CR> SuperFrameSpec<CR> (2 bytes): bit 15 - Association Permitted (MSB) bit 14 - PAN Coordinator bit 13 - Reserved bit 12 - Battery Life Extension bits 8-11 - Final CAP Slot bits 4-7 - Superframe Order bits 0-3 - Beacon Order GtsPermit<CR> RSSI<CR> (RSSI is returned as -dBm) TimeStamp<CR> (3 bytes) <CR> A carriage return <CR> is sent at the end of the AS command. The Active Scan is capable of returning up to 5 PanDescriptors in a scan. The actual scan time on each channel is measured as Time = [(2 ^SD PARAM) * 15.36] ms. Note the total scan time is this time multiplied by the number of channels to be scanned (16 for the XBee and 13 for the XBee-PRO). Also refer to SD command description.	0 - 6	-
ED (v1.x80*)	Networking {Association}	Energy Scan. Send an Energy Detect Scan. This parameter determines the length of scan on each channel. The maximal energy on each channel is returned & each value is followed by a carriage return. An additional carriage return is sent at the end of the command. The values returned represent the detected energy level in units of -dBm. The actual scan time on each channel is measured as Time = [(2 ^ED) * 15.36] ms. Note the total scan time is this time multiplied by the number of channels to be scanned (refer to SD parameter).	0 - 6	-
EE (v1.xA0*)	Networking {Security}	AES Encryption Enable. Disable/Enable 128-bit AES encryption support. Use in conjunction with the KY command.	0 - 1	0 (disabled)
KY (v1.xA0*)	Networking {Security}	AES Encryption Key. Set the 128-bit AES (Advanced Encryption Standard) key for encrypting/decrypting data. The KY register cannot be read.	0 - (any 16-Byte value)	-

* Firmware version in which the command was first introduced (firmware versions are numbered in hexadecimal notation.)

RF Interfacing

Table 3-03. XBee/XBee-PRO Commands - RF Interfacing

AT Command	Command Category	Name and Description	Parameter Range	Default
PL	RF Interfacing	Power Level. Select/Read the power level at which the RF module transmits conducted power. *NOTE: XBee-PRO RF Modules optimized for use in Japan contain firmware that limits transmit power output to 10 dBm. If PL=4 (default), the maximum power output level is fixed at 10 dBm.*	0 - 4 (XBee / XBee-PRO) 0 = -10 / 10 dBm 1 = -6 / 12 dBm 2 = -4 / 14 dBm 3 = -2 / 16 dBm 4 = 0 / 18 dBm	4
CA (v1.x80*)	RF Interfacing	CCA Threshold. Set/read the CCA (Clear Channel Assessment) threshold. Prior to transmitting a packet, a CCA is performed to detect energy on the channel. If the detected energy is above the CCA Threshold, the module will not transmit the packet.	0 - 0x50 [-dBm]	0x2C (-44d dBm)

* Firmware version in which the command was first introduced (firmware versions are numbered in hexadecimal notation.)

Sleep (Low Power)

Table 3-04. XBee/XBee-PRO Commands - Sleep (Low Power)

AT Command	Command Category	Name and Description	Parameter Range	Default
SM	Sleep (Low Power)	Sleep Mode. <NonBeacon firmware> Set/Read Sleep Mode configurations.	0 - 5 0 = No Sleep 1 = Pin Hibernate 2 = Pin Doze 3 = Reserved 4 = Cyclic sleep remote 5 = Cyclic sleep remote w/ pin wake-up 6 = [Sleep Coordinator] for backwards compatibility w/ v1.x6 only; otherwise, use CE command.	0
ST	Sleep (Low Power)	Time before Sleep. <NonBeacon firmware> Set/Read time period of inactivity (no serial or RF data is sent or received) before activating Sleep Mode. ST parameter is only valid with Cyclic Sleep settings (SM = 4 - 5). Coordinator and End Device ST values must be equal. Also note, the GT parameter value must always be less than the ST value. (If GT > ST, the configuration will render the module unable to enter into command mode.) If the ST parameter is modified, also modify the GT parameter accordingly.	1 - 0xFFFF [x 1 ms]	0x1388 (5000d)
SP	Sleep (Low Power)	Cyclic Sleep Period. <NonBeacon firmware> Set/Read sleep period for cyclic sleeping remotes. Coordinator and End Device SP values should always be equal. To send Direct Messages, set SP = 0. *End Device* - SP determines the sleep period for cyclic sleeping remotes. Maximum sleep period is 268 seconds (0x68B0). *Coordinator* - If non-zero, SP determines the time to hold an indirect message before discarding it. A Coordinator will discard indirect messages after a period of (2.5 * SP).	0 - 0x68B0 [x 10 ms]	0
DP (1.x80*)	Sleep (Low Power)	Disassociated Cyclic Sleep Period. <NonBeacon firmware> *End Device* - Set/Read time period of sleep for cyclic sleeping remotes that are configured for Association but are not associated to a Coordinator. (i.e. If a device is configured to associate, configured as a Cyclic Sleep remote, but does not find a Coordinator, it will sleep for DP time before reattempting association.) Maximum sleep period is 268 seconds (0x68B0). DP should be > 0 for NonBeacon systems.	1 - 0x68B0 [x 10 ms]	0x3E8 (1000d)

* Firmware version in which the command was first introduced (firmware versions are numbered in hexadecimal notation.)

Serial Interfacing

Table 3-05. XBee-PRO Commands - Serial Interfacing

AT Command	Command Category	Name and Description	Parameter Range	Default
BD	Serial Interfacing	Interface Data Rate. Set/Read the serial interface data rate for communications between the RF module serial port and host. Request non-standard baud rates with values above 0x80 using a terminal window. Read the BD register to find actual baud rate achieved.	0 - 7 (standard baud rates) 0 = 1200 bps 1 = 2400 2 = 4800 3 = 9600 4 = 19200 5 = 38400 6 = 57600 7 = 115200 0x80 - 0x1C200 (non-standard baud rates)	3
RO	Serial Interfacing	Packetization Timeout. Set/Read number of character times of inter-character delay required before transmission. Set to zero to transmit characters as they arrive instead of buffering them into one RF packet.	0 - 0xFF [x character times]	3
AP (v1.x80*)	Serial Interfacing	API Enable. Disable/Enable API Mode.	0 - 2 0 = Disabled 1 = API enabled 2 = API enabled (w/escaped control characters)	0
NB	Serial Interfacing	Parity. Set/Read parity settings.	0 - 4 0 = 8-bit (no parity or 7-bit (any parity) 1 = 8-bit even 2 = 8-bit odd 3 = 8-bit mark 4 = 8-bit space	0

Table 3-05. XBee-PRO Commands - Serial Interfacing

AT Command	Command Category	Name and Description	Parameter Range	Default
PR (v1.x80*)	Serial Interfacing	Pull-up Resistor Enable. Set/Read bitfield to configure internal pull-up resistor status for I/O lines Bitfield Map: bit 0 - AD4/DIO4 (pin11) bit 1 - AD3 / DIO3 (pin17) bit 2 - AD2/DIO2 (pin18) bit 3 - AD1/DIO1 (pin19) bit 4 - AD0 / DIO0 (pin20) bit 5 - RTS / AD6 / DIO6 (pin16) bit 6 - DTR / SLEEP_RQ / DI8 (pin9) bit 7 - DIN/CONFIG (pin3) Bit set to "1" specifies pull-up enabled; "0" specifies no pull-up	0 - 0xFF	0xFF

* Firmware version in which the command was first introduced (firmware versions are numbered in hexadecimal notation.)

I/O Settings

Table 3-06. XBee-PRO Commands - I/O Settings (sub-category designated within {brackets})

AT Command	Command Category	Name and Description	Parameter Range	Default
D8	I/O Settings	DI8 Configuration. Select/Read options for the DI8 line (pin 9) of the RF module.	0 - 1 0 = Disabled 3 = DI (1,2,4 & 5 n/a)	0
D7 (v1.x80*)	I/O Settings	DIO7 Configuration. Select/Read settings for the DIO7 line (pin 12) of the RF module. Options include CTS flow control and I/O line settings.	0 - 1 0 = Disabled 1 = CTS Flow Control 2 = (n/a) 3 = DI 4 = DO low 5 = DO high	1
D6 (v1.x80*)	I/O Settings	DIO6 Configuration. Select/Read settings for the DIO6 line (pin 16) of the RF module. Options include RTS flow control and I/O line settings.	0 - 1 0 = Disabled 1 = RTS flow control 2 = (n/a) 3 = DI 4 = DO low 5 = DO high	0
D5 (v1.x80*)	I/O Settings	DIO5 Configuration. Configure settings for the DIO5 line (pin 15) of the RF module. Options include Associated LED indicator (blinks when associated) and I/O line settings.	0 - 1 0 = Disabled 1 = Associated indicator 2 = ADC 3 = DI 4 = DO low 5 = DO high	1
D0 - D4 (v1.xA0*)	I/O Settings	(DIO4 -DIO4) Configuration. Select/Read settings for the following lines: AD0/DIO0 (pin 20), AD1/DIO1 (pin 19), AD2/DIO2 (pin 18), AD3/DIO3 (pin 17), AD4/DIO4 (pin 11). Options include: Analog-to-digital converter, Digital Input and Digital Output.	0 - 1 0 = Disabled 1 = (n/a) 2 = ADC 3 = DI 4 = DO low 5 = DO high	0
IU (v1.xA0*)	I/O Settings	I/O Output Enable. Disables/Enables I/O data received to be sent out UART. The data is sent using an API frame regardless of the current AP parameter value.	0 - 1 0 = Disabled 1 = Enabled	1
IT (v1.xA0*)	I/O Settings	Samples before TX. Set/Read the number of samples to collect before transmitting data. Maximum number of samples is dependent upon the number of enabled inputs.	1 - 0xFF	1
IS (v1.xA0*)	I/O Settings	Force Sample. Force a read of all enabled inputs (DI or ADC). Data is returned through the UART. If no inputs are defined (DI or ADC), this command will return error.	8-bit bitmap (each bit represents the level of an I/O line setup as an output)	-
IO (v1.xA0*)	I/O Settings	Digital Output Level. Set digital output level to allow DIO lines that are setup as outputs to be changed through Command Mode.	-	-
IC (v1.xA0*)	I/O Settings	DIO Change Detect. Set/Read bitfield values for change detect monitoring. Each bit enables monitoring of DIO0 - DIO7 for changes. If detected, data is transmitted with DIO data only. Any samples queued waiting for transmission will be sent first.	0 - 0xFF [bitfield]	0 (disabled)
IR (v1.xA0*)	I/O Settings	Sample Rate. Set/Read sample rate. When set, this parameter causes the module to sample all enabled inputs at a specified interval.	0 - 0xFFFF [x 1 msec]	0
AV (v1.xA0*)	I/O Settings	ADC Voltage Reference. <XBee-PRO only> Set/Read ADC reference voltage switch.	0 - 1 0 = VREF pin 1 = Internal	0

Table 3-06. XBee-PRO Commands - I/O Settings (sub-category designated within {brackets})

AT Command	Command Category	Name and Description	Parameter Range	Default
IA (v1.xA0*)	I/O Settings {I/O Line Passing}	I/O Input Address. Set/Read addresses of module to which outputs are bound. Setting all bytes to 0xFF will not allow any received I/O packet to change outputs. Setting address to 0xFFFF will allow any received I/O packet to change outputs.	0 - 0xFFFFFFFFFFFFFFFF	0xFFFFFFFF FFFFFFFF
T0 - T7 (v1.xA0*)	I/O Settings {I/O Line Passing}	(D0 - D7) Output Timeout. Set/Read Output timeout values for lines that correspond with the D0 - D7 parameters. When output is set (due to I/O line passing) to a non-default level, a timer is started which when expired will set the output to it default level. The timer is reset when a valid I/O packet is received.	0 - 0xFF [x 100 ms]	0xFF
P0	I/O Settings {I/O Line Passing}	PWM0 Configuration. Select/Read function for PWM0 pin.	0 - 2 0 = Disabled 1 = RSSI 2 = PWM Output	1
P1 (v1.xA0*)	I/O Settings {I/O Line Passing}	PWM1 Configuration. Select/Read function for PWM1 pin.	0 - 2 0 = Disabled 1 = RSSI 2 = PWM Output	0
M0 (v1.xA0*)	I/O Settings {I/O Line Passing}	PWM0 Output Level. Set/Read the PWM0 output level.	0 - 0x03FF	-
M1 (v1.xA0*)	I/O Settings {I/O Line Passing}	PWM1 Output Level. Set/Read the PWM0 output level.	0 - 0x03FF	-
PT (v1.xA0*)	I/O Settings {I/O Line Passing}	PWM Output Timeout. Set/Read output timeout value for both PWM outputs. When PWM is set to a non-zero value: Due to I/O line passing, a time is started which when expired will set the PWM output to zero. The timer is reset when a valid I/O packet is received.]	0 - 0xFF [x 100 ms]	0xFF
RP	I/O Settings {I/O Line Passing}	RSSI PWM Timer. Set/Read PWM timer register. Set the duration of PWM (pulse width modulation) signal output on the RSSI pin. The signal duty cycle is updated with each received packet and is shut off when the timer expires.]	0 - 0xFF [x 100 ms]	0x28 (40d)

* Firmware version in which the command was first introduced (firmware versions are numbered in hexadecimal notation.)

Diagnostics

Table 3-07. XBee/XBee-PRO Commands - Diagnostics

AT Command	Command Category	Name and Description	Parameter Range	Default
VR	Diagnostics	Firmware Version. Read firmware version of the RF module.	0 - 0xFFFF [read-only]	Factory-set
VL (v1.x80*)	Diagnostics	Firmware Version - Verbose. Read detailed version information (including application build date, MAC, PHY and bootloader versions).	-	-
HV (v1.x80*)	Diagnostics	Hardware Version. Read hardware version of the RF module.	0 - 0xFFFF [read-only]	Factory-set
DB	Diagnostics	Received Signal Strength. Read signal level [in dB] of last good packet received (RSSI). Absolute value is reported. (For example: 0x58 = -88 dBm) Reported value is accurate between -40 dBm and RX sensitivity.	0x17-0x5C (XBee) 0x24-0x64 (XBee-PRO) [read-only]	-
EC (v1.x80*)	Diagnostics	CCA Failures. Reset/Read count of CCA (Clear Channel Assessment) failures. This parameter value increments when the module does not transmit a packet because it detected energy above the CCA threshold level set with CA command. This count saturates at its maximum value. Set count to “0” to reset count.	0 - 0xFFFF	-
EA (v1.x80*)	Diagnostics	ACK Failures. Reset/Read count of acknowledgment failures. This parameter value increments when the module expires its transmission retries without receiving an ACK on a packet transmission. This count saturates at its maximum value. Set the parameter to “0” to reset count.	0 - 0xFFFF	-
ED (v1.x80*)	Diagnostics	Energy Scan. Send ‘Energy Detect Scan’. ED parameter determines the length of scan on each channel. The maximal energy on each channel is returned and each value is followed by a carriage return. Values returned represent detected energy levels in units of -dBm. Actual scan time on each channel is measured as Time = [(2 ^ SD) * 15.36] ms. Total scan time is this time multiplied by the number of channels to be scanned.	0 - 6	-

* Firmware version in which the command was first introduced (firmware versions are numbered in hexadecimal notation.)

AT Command Options

Table 3-08. XBee/XBee-PRO Commands - AT Command Options

AT Command	Command Category	Name and Description	Parameter Range	Default
CT	AT Command Mode Options	Command Mode Timeout. Set/Read the period of inactivity (no valid commands received) after which the RF module automatically exits AT Command Mode and returns to Idle Mode.	2 - 0xFFFF [x 100 ms]	0x64 (100d)
CN	AT Command Mode Options	Exit Command Mode. Explicitly exit the module from AT Command Mode.	--	--
AC (v1.xA0*)	AT Command Mode Options	Apply Changes. Explicitly apply changes to queued parameter value(s) and re-initialize module.	--	--
GT	AT Command Mode Options	Guard Times. Set required period of silence before and after the Command Sequence Characters of the AT Command Mode Sequence (GT+ CC + GT). The period of silence is used to prevent inadvertent entrance into AT Command Mode.	2 - 0x0CE4 [x 1 ms]	0x3E8 (1000d)
CC	AT Command Mode Options	Command Sequence Character. Set/Read the ASCII character value to be used between Guard Times of the AT Command Mode Sequence (GT+CC+GT). The AT Command Mode Sequence enters the RF module into AT Command Mode.	0 - 0xFF	0x2B ('+' ASCII)

* Firmware version in which the command was first introduced (firmware versions are numbered in hexadecimal notation.)

3.3. Command Descriptions

Command descriptions in this section are listed alphabetically. Command categories are designated within "< >" symbols that follow each command title. XBee/XBee-PRO RF Modules expect parameter values in hexadecimal (designated by the "0x" prefix).

All modules operating within the same network should contain the same firmware version.

A1 (End Device Association) Command

<Networking {Association}> The A1 command is used to set and read association options for an End Device.

Use the table below to determine End Device behavior in relation to the A1 parameter.

AT Command: ATA1

Parameter Range: 0 – 0x0F [bitfield]

Default Parameter Value: 0

Related Commands: ID (PAN ID), NI (Node Identifier), CH (Channel), CE (Coordinator Enable), A2 (Coordinator Association)

Minimum Firmware Version Required: v1.x80

Bit number	End Device Association Option
0 - ReassignPanID	0 - Will only associate with Coordinator operating on PAN ID that matches Node Identifier
	1 - May associate with Coordinator operating on any PAN ID
1 - ReassignChannel	0 - Will only associate with Coordinator operating on Channel that matches CH setting
	1 - May associate with Coordinator operating on any Channel
2 - AutoAssociate	0 - Device will not attempt Association
	1 - Device attempts Association until success Note: This bit is used only for Non-Beacon systems. End Devices in a Beaconing system must always associate to a Coordinator
3 - PollCoordOnPinWake	0 - Pin Wake will not poll the Coordinator for pending (indirect) Data
	1 - Pin Wake will send Poll Request to Coordinator to extract any pending data
4 - 7	[reserved]

A2 (Coordinator Association) Command

<Networking {Association}> The A2 command is used to set and read association options of the Coordinator.

Use the table below to determine Coordinator behavior in relation to the A2 parameter.

AT Command: ATA2

Parameter Range: 0 – 7 [bitfield]

Default Parameter Value: 0

Related Commands: ID (PAN ID), NI (Node Identifier), CH (Channel), CE (Coordinator Enable), A1 (End Device Association), AS Active Scan), ED (Energy Scan)

Minimum Firmware Version Required: v1.x80

Bit number	End Device Association Option
0 - ReassignPanID	0 - Coordinator will not perform Active Scan to locate available PAN ID. It will operate on ID (PAN ID).
	1 - Coordinator will perform Active Scan to determine an available ID (PAN ID). If a PAN ID conflict is found, the ID parameter will change.
1 - ReassignChannel	0 - Coordinator will not perform Energy Scan to determine free channel. It will operate on the channel determined by the CH parameter.
	1 - Coordinator will perform Energy Scan to find a free channel, then operate on that channel.
2 - AllowAssociate	0 - Coordinator will not allow any devices to associate to it.
	1 - Coordinator will allow devices to associate to it.
3 - 7	[reserved]

The binary equivalent of the default value (0x06) is 00000110. 'Bit 0' is the last digit of the sequence.

AC (Apply Changes) Command

AT Command: ATAC

Minimum Firmware Version Required: v1.xA0

<AT Command Mode Options> The AC command is used to explicitly apply changes to module parameter values. 'Applying changes' means that the module is re-initialized based on changes made to its parameter values. Once changes are applied, the module immediately operates according to the new parameter values.

This behavior is in contrast to issuing the WR (Write) command. The WR command saves parameter values to non-volatile memory, but the module still operates according to previously saved values until the module is re-booted or the CN (Exit AT Command Mode) command is issued.

Refer to the "AT Command – Queue Parameter Value" API type for more information.

AI (Association Indication) Command

AT Command: ATAI

Parameter Range: 0 – 0x13 [read-only]

Related Commands: AS (Active Scan), ID (PAN ID), CH (Channel), ED (Energy Scan), A1 (End Device Association), A2 (Coordinator Association), CE (Coordinator Enable)

Minimum Firmware Version Required: v1.x80

<Networking {Association}> The AI command is used to indicate occurrences of errors during the last association request.

Use the table below to determine meaning of the returned values.

Returned Value (Hex)	Association Indication
0x00	Successful Completion - Coordinator successfully started or End Device association complete
0x01	Active Scan Timeout
0x02	Active Scan found no PANs
0x03	Active Scan found PAN, but the Coordinator Allow Association bit is not set
0x04	Active Scan found PAN, but Coordinator and End Device are not configured to support beacons
0x05	Active Scan found PAN, but Coordinator ID (PAN ID) value does not match the ID of the End Device
0x06	Active Scan found PAN, but Coordinator CH (Channel) value does not match the CH of the End Device
0x07	Energy Scan Timeout
0x08	Coordinator start request failed
0x09	Coordinator could not start due to Invalid Parameter
0x0A	Coordinator Realignment is in progress
0x0B	Association Request not sent
0x0C	Association Request timed out - no reply was received
0x0D	Association Request had an Invalid Parameter
0x0E	Association Request Channel Access Failure - Request was not transmitted - CCA failure
0x0F	Remote Coordinator did not send an ACK after Association Request was sent
0x10	Remote Coordinator did not reply to the Association Request, but an ACK was received after sending the request
0x11	[reserved]
0x12	Sync-Loss - Lost synchronization with a Beaconing Coordinator
0x13	Disassociated - No longer associated to Coordinator
0xFF	RF Module is attempting to associate

AP (API Enable) Command

<Serial Interfacing> The AP command is used to enable the RF module to operate using a frame-based API instead of using the default Transparent (UART) mode.

AT Command: ATAP

Parameter Range:0 – 2

Parameter	Configuration
0	Disabled (Transparent operation)
1	API enabled
2	API enabled (with escaped characters)

Default Parameter Value:0

Minimum Firmware Version Required: v1.x80

Refer to the API Operation section when API operation is enabled (AP = 1 or 2).

AS (Active Scan) Command

<AT Command Mode Options> The AS command is used to send a Beacon Request to a Broadcast (0xFFFF) and Broadcast PAN (0xFFFF) on every channel. The parameter determines the amount of time the RF module will listen for Beacons on each channel. A 'PanDescriptor' is created and returned for every Beacon received from the scan. Each PanDescriptor contains the following information:

AT Command: ATAS

Parameter Range: 0 – 6

Related Command: SD (Scan Duration), DL (Destination Low Address), DH (Destination High Address), ID (PAN ID), CH (Channel)

Minimum Firmware Version Required: v1.x80

CoordAddress (SH + SL parameters)<CR> (NOTE: If MY on the coordinator is set less than 0xFFFF, the MY value is displayed)
CoordPanID (ID parameter)<CR>
CoordAddrMode <CR>
  0x02 = 16-bit Short Address
  0x03 = 64-bit Long Address
Channel (CH parameter) <CR>
SecurityUse<CR>
ACLEntry<CR>
SecurityFailure<CR>
SuperFrameSpec<CR> (2 bytes):
  bit 15 - Association Permitted (MSB)
  bit 14 - PAN Coordinator
  bit 13 - Reserved
  bit 12 - Battery Life Extension
  bits 8-11 - Final CAP Slot
  bits 4-7 - Superframe Order
  bits 0-3 - Beacon Order
GtsPermit<CR>
RSSI<CR> (- RSSI is returned as -dBm)
TimeStamp<CR> (3 bytes)
<CR> (A carriage return <CR> is sent at the end of the AS command.

The Active Scan is capable of returning up to 5 PanDescriptors in a scan. The actual scan time on each channel is measured as Time = [(2 ^ (SD Parameter)) * 15.36] ms. Total scan time is this time multiplied by the number of channels to be scanned (16 for the XBee, 12 for the XBee-PRO).

NOTE: Refer the scan table in the SD description to determine scan times. If using API Mode, no <CR>'s are returned in the response. Refer to the API Mode Operation section.

AV (ADC Voltage Reference) Command

<Serial Interfacing> The AV command is used to set/read the ADC reference voltage switch. The XBee-PRO has an ADC voltage reference switch which allows the module to select between an on-board voltage reference or to use the VREF pin on the connector.

This command only applies to XBee-PRO RF Modules and will return error on an XBee RF Module.

AT Command: ATAV

Parameter Range:0 – 1

Parameter	Configuration
0	VREF Pin
1	Internal (on-board reference – VCC)

Default Parameter Value:0

Minimum Firmware Version Required: v1.xA0

BD (Interface Data Rate) Command

<Serial Interfacing> The BD command is used to set and read the serial interface data rate used between the RF module and host. This parameter determines the rate at which serial data is sent to the module from the host. Modified interface data rates do not take effect until the CN (Exit AT Command Mode) command is issued and the system returns the 'OK' response.

When parameters 0-7 are sent to the module, the respective interface data rates are used (as shown in the table on the right).

The RF data rate is not affected by the BD parameter. If the interface data rate is set higher than the RF data rate, a flow control configuration may need to be implemented.

AT Command: ATBD

Parameter Range:0 – 7 (standard rates)
0x80–0x1C200 (non-stndard rates)

Parameter	Configuration (bps)
0	1200
1	2400
2	4800
3	9600
4	19200
5	38400
6	57600
7	115200

Default Parameter Value:3

Non-standard Interface Data Rates:
Any value above 0x07 will be interpreted as an actual baud rate. When a value above 0x07 is sent, the closest interface data rate represented by the number is stored in the BD register. For example, a rate of 19200 bps can be set by sending the following command line "ATBD4B00". NOTE: When using MaxStream's X-CTU Software, non-standard interface data rates can only be set and read using the X-CTU 'Terminal' tab. Non-standard rates are not accessible through the 'Modem Configuration' tab.

When the BD command is sent with a non-standard interface data rate, the UART will adjust to accommodate the requested interface rate. In most cases, the clock resolution will cause the stored BD parameter to vary from the parameter that was sent (refer to the table below). Reading the BD command (send "ATBD" command without an associated parameter value) will return the value actually stored in the module's BD register.

Parameters Sent Versus Parameters Stored

BD Parameter Sent (HEX)	Interface Data Rate (bps)	BD Parameter Stored (HEX)
0	1200	0
4	19,200	4
7	115,200	7
12C	300	12B
1C200	115,200	1B207

CA (CCA Threshold) Command

<RF Interfacing> CA command is used to set and read CCA (Clear Channel Assessment) thresholds.

Prior to transmitting a packet, a CCA is performed to detect energy on the transmit channel. If the detected energy is above the CCA Threshold, the RF module will not transmit the packet.

AT Command: ATCA

Parameter Range: 0 – 0x50 [–dBm]

Default Parameter Value: 0x2C
(–44 decimal dBm)

Minimum Firmware Version Required: v1.x80

CC (Command Sequence Character) Command

<AT Command Mode Options> The CC command is used to set and read the ASCII character used between guard times of the AT Command Mode Sequence (GT + CC + GT). This sequence enters the RF module into AT Command Mode so that data entering the module from the host is recognized as commands instead of payload.

AT Command: ATCC

Parameter Range: 0 – 0xFF

Default Parameter Value: 0x2B (ASCII "+")

Related Command: GT (Guard Times)

The AT Command Sequence is explained further in the AT Command Mode section.

CE (Coordinator Enable) Command

<Serial Interfacing> The CE command is used to set and read the behavior (End Device vs. Coordinator) of the RF module.

AT Command: ATCE

Parameter Range:0 – 1

Parameter	Configuration
0	End Device
1	Coordinator

Default Parameter Value:0

Minimum Firmware Version Required: v1.x80

CH (Channel) Command

<Networking {Addressing}> The CH command is used to set/read the operating channel on which RF connections are made between RF modules. The channel is one of three addressing options available to the module. The other options are the PAN ID (ID command) and destination addresses (DL & DH commands).

AT Command: ATCH

Parameter Range: 0x0B – 0x1A (XBee)
0x0C – 0x17 (XBee-PRO)

Default Parameter Value: 0x0C (12 decimal)

Related Commands: ID (PAN ID), DL (Destination Address Low, DH (Destination Address High)

In order for modules to communicate with each other, the modules must share the same channel number. Different channels can be used to prevent modules in one network from listening to transmissions of another. Adjacent channel rejection is 23 dB.

The module uses channel numbers of the 802.15.4 standard.
Center Frequency = 2.405 + (CH - 11d) * 5 MHz (d = decimal)

Refer to the XBee/XBee-PRO Addressing section for more information.

CN (Exit Command Mode) Command

<AT Command Mode Options> The CN command is used to explicitly exit the RF module from AT Command Mode.

AT Command: ATCN

CT (Command Mode Timeout) Command

<AT Command Mode Options> The CT command is used to set and read the amount of inactive time that elapses before the RF module automatically exits from AT Command Mode and returns to Idle Mode.

Use the CN (Exit Command Mode) command to exit AT Command Mode manually.

AT Command: ATCT

Parameter Range:2 – 0xFFFF
[x 100 milliseconds]

Default Parameter Value: 0x64 (100 decimal (which equals 10 decimal seconds))

Number of bytes returned: 2

Related Command: CN (Exit Command Mode)

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D0 - D4 (DIOn Configuration) Commands

<I/O Settings> The D0, D1, D2, D3 and D4 commands are used to select/read the behavior of their respective AD/DIO lines (pins 20, 19, 18, 17 and 11 respectively).

Options include:

- Analog-to-digital converter
- Digital input
- Digital output

AT Commands:
ATD0, ATD1, ATD2, ATD3, ATD4

Parameter Range:0 – 5

Parameter	Configuration
0	Disabled
1	n/a
2	ADC
3	DI
4	DO low
5	DO high

Default Parameter Value:0

Minimum Firmware Version Required: 1.x.A0

D5 (DIO5 Configuration) Command

<I/O Settings> The D5 command is used to select/read the behavior of the DIO5 line (pin 15).

Options include:

- Associated Indicator (LED blinks when the module is associated)
- Analog-to-digital converter
- Digital input
- Digital output

AT Command: ATD5

Parameter Range:0 – 5

Parameter	Configuration
0	Disabled
1	Associated Indicator
2	ADC
3	DI
4	DO low
5	DO high

Default Parameter Value:1

Parameters 2–5 supported as of firmware version 1.xA0

D6 (DIO6 Configuration) Command

<I/O Settings> The D6 command is used to select/read the behavior of the DIO6 line (pin 16). Options include:

- RTS flow control
- Analog-to-digital converter
- Digital input
- Digital output

AT Command: ATD6

Parameter Range:0 – 5

Parameter	Configuration
0	Disabled
1	RTS Flow Control
2	n/a
3	DI
4	DO low
5	DO high

Default Parameter Value:0

Parameters 3–5 supported as of firmware version 1.xA0

D7 (DIO7 Configuration) Command

<I/O Settings> The D7 command is used to select/read the behavior of the DIO7 line (pin 12). Options include:

- CTS flow control
- Analog-to-digital converter
- Digital input
- Digital output

AT Command: ATD7

Parameter Range:0 – 5

Parameter	Configuration
0	Disabled
1	CTS Flow Control
2	n/a
3	DI
4	DO low
5	DO high

Default Parameter Value:1

Parameters 3–5 supported as of firmware version 1.x.A0

D8 (DI8 Configuration) Command

<I/O Settings> The D8 command is used to select/read the behavior of the DI8 line (pin 9). This command enables configuring the pin to function as a digital input. This line is also used with Pin Sleep.

AT Command: ATD8

Parameter Range:0 – 5
(1, 2, 4 & 5 n/a)

Parameter	Configuration
0	Disabled
3	DI

Default Parameter Value:0

Minimum Firmware Version Required: 1.xA0

DA (Force Disassociation) Command

<(Special)> The DA command is used to immediately disassociate an End Device from a Coordinator and reattempt to associate.

AT Command: ATDA

Minimum Firmware Version Required: v1.x80

DB (Received Signal Strength) Command

<Diagnostics> DB parameter is used to read the received signal strength (in dBm) of the last RF packet received. Reported values are accurate between -40 dBm and the RF module's receiver sensitivity.

AT Command: ATDB

Parameter Range [read-only]: 0x17–0x5C (XBee), 0x24–0x64 (XBee-PRO)

Absolute values are reported. For example: 0x58 = -88 dBm (decimal). If no packets have been received (since last reset, power cycle or sleep event), “0” will be reported.

DH (Destination Address High) Command

<Networking {Addressing}> The DH command is used to set and read the upper 32 bits of the RF module's 64-bit destination address. When combined with the DL (Destination Address Low) parameter, it defines the destination address used for transmission.

An module will only communicate with other modules having the same channel (CH parameter), PAN ID (ID parameter) and destination address (DH + DL parameters).

AT Command: ATDH

Parameter Range: 0 – 0xFFFFFFFF

Default Parameter Value: 0

Related Commands: DL (Destination Address Low), CH (Channel), ID (PAN VID), MY (Source Address)

To transmit using a 16-bit address, set the DH parameter to zero and the DL parameter less than 0xFFFF. 0x000000000000FFFF (DL concatenated to DH) is the broadcast address for the PAN.

Refer to the XBee/XBee-PRO Addressing section for more information.

DL (Destination Address Low) Command

<Networking {Addressing}> The DL command is used to set and read the lower 32 bits of the RF module's 64-bit destination address. When combined with the DH (Destination Address High) parameter, it defines the destination address used for transmission.

AT Command: ATDL
Parameter Range: 0 - 0xFFFFFFFF
Default Parameter Value: 0
Related Commands: DH (Destination Address High), CH (Channel), ID (PAN VID), MY (Source Address)

A module will only communicate with other modules having the same channel (CH parameter), PAN ID (ID parameter) and destination address (DH + DL parameters).

To transmit using a 16-bit address, set the DH parameter to zero and the DL parameter less than 0xFFFF. 0x000000000000FFFF (DL concatenated to DH) is the broadcast address for the PAN.

Refer to the XBee/XBee-PRO Addressing section for more information.

DN (Destination Node) Command

<Networking {Identification}> The DN command is used to resolve a NI (Node Identifier) string to a physical address. The following events occur upon successful command execution:

AT Command: ATDN
Parameter Range: 20-character ASCII String
Minimum Firmware Version Required: v1.x80

1. DL and DH are set to the address of the module with the matching NI (Node Identifier).
2. 'OK' is returned.
3. RF module automatically exits AT Command Mode.

If there is no response from a modem within 200 msec or a parameter is not specified (left blank), the command is terminated and an 'ERROR' message is returned.

DP (Disassociation Cyclic Sleep Period) Command

<Sleep Mode (Low Power)>

AT Command: ATDP
Parameter Range: 1 – 0x68B0 [x 10 milliseconds]
Default Parameter Value:0x3E8 (1000 decimal)
Related Commands: SM (Sleep Mode), SP (Cyclic Sleep Period), ST (Time before Sleep)
Minimum Firmware Version Required: v1.x80

NonBeacon Firmware

End Device - The DP command is used to set and read the time period of sleep for cyclic sleeping remotes that are configured for Association but are not associated to a Coordinator. (i.e. If a device is configured to associate, configured as a Cyclic Sleep remote, but does not find a Coordinator; it will sleep for DP time before reattempting association.) Maximum sleep period is 268 seconds (0x68B0). DP should be > 0 for NonBeacon systems.

EA (ACK Failures) Command

<Diagnostics> The EA command is used to reset and read the count of ACK (acknowledgement) failures. This parameter value increments when the module expires its transmission retries without receiving an ACK on a packet transmission. This count saturates at its maximum value.

AT Command: ATEA
Parameter Range:0 – 0xFFFF
Minimum Firmware Version Required: v1.x80

Set the parameter to "0" to reset count.

EC (CCA Failures) Command

<Diagnostics> The EC command is used to read and reset the count of CCA (Clear Channel Assessment) failures. This parameter value increments when the RF module does not transmit a packet due to the detection of energy that is above the CCA threshold level (set with CA command). This count saturates at its maximum value.

Set the EC parameter to "0" to reset count.

AT Command: ATEC

Parameter Range:0 – 0xFFFF

Related Command: CA (CCA Threshold)

Minimum Firmware Version Required: v1.x80

ED (Energy Scan) Command

<Networking {Association}> The ED command is used to send an "Energy Detect Scan". This parameter determines the length of scan on each channel. The maximal energy on each channel is returned and each value is followed by a carriage return. An additional carriage return is sent at the end of the command.

AT Command: ATED

Parameter Range:0 – 6

Related Command: SD (Scan Duration), SC (Scan Channel)

Minimum Firmware Version Required: v1.x80

The values returned represent the detected energy level in units of -dBm. The actual scan time on each channel is measured as Time = [(2 ^ ED PARAM) * 15.36] ms.

Note: Total scan time is this time multiplied by the number of channels to be scanned. Also refer to the SD (Scan Duration) table. Use the SC (Scan Channel) command to choose which channels to scan.

EE (AES Encryption Enable) Command

<Networking {Security}> The EE command is used to set/read the parameter that disables/enables 128-bit AES encryption.

The XBee/XBee-PRO firmware uses the 802.15.4 Default Security protocol and uses AES encryption with a 128-bit key. AES encryption dictates that all modules in the network use the same key and the maximum RF packet size is 95 Bytes.

When encryption is enabled, the module will always use its 64-bit long address as the source address for RF packets. This does not affect how the MY (Source Address), DH (Destination Address High) and DL (Destination Address Low) parameters work

AT Command: ATEE

Parameter Range:0 – 1

Parameter	Configuration
0	Disabled
1	Enabled

Default Parameter Value:0

Related Commands: KY (Encryption Key), AP (API Enable), MM (MAC Mode)

Minimum Firmware Version Required: v1.xA0

If MM (MAC Mode) > 0 and AP (API Enable) parameter > 0:
With encryption enabled and a 16-bit short address set, receiving modules will only be able to issue RX (Receive) 64-bit indicators. This is not an issue when MM = 0.

If a module with a non-matching key detects RF data, but has an incorrect key: When encryption is enabled, non-encrypted RF packets received will be rejected and will not be sent out the UART.

Transparent Operation --> All RF packets are sent encrypted if the key is set.

API Operation --> Receive frames use an option bit to indicate that the packet was encrypted.

FP (Force Poll) Command

<Networking (Association)> The FP command is used to request indirect messages being held by a Coordinator.

AT Command: ATFP

Minimum Firmware Version Required: v1.x80

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FR (Software Reset) Command

<Special> The FR command is used to force a software reset on the RF module. The reset simulates powering off and then on again the module.

AT Command: ATFR

Minimum Firmware Version Required: v1.x80

GT (Guard Times) Command

<AT Command Mode Options> GT Command is used to set the DI (data in from host) time-of-silence that surrounds the AT command sequence character (CC Command) of the AT Command Mode sequence (GT + CC + GT).

The DI time-of-silence is used to prevent inadvertent entrance into AT Command Mode.

Refer to the Command Mode section for more information regarding the AT Command Mode Sequence.

AT Command: ATGT

Parameter Range:2 – 0x0CE4 [x 1 millisecond]

Default Parameter Value:0x3E8 (1000 decimal)

Related Command: CC (Command Sequence Character)

HV (Hardware Version) Command

<Diagnostics> The HV command is used to read the hardware version of the RF module.

AT Command: ATHV

Parameter Range:0 – 0xFFFF [Read-only]

Minimum Firmware Version Required: v1.x80

IA (I/O Input Address) Command

<I/O Settings {I/O Line Passing}> The IA command is used to bind a module output to a specific address. Outputs will only change if received from this address. The IA command can be used to set/read both 16 and 64-bit addresses.

Setting all bytes to 0xFF will not allow the reception of any I/O packet to change outputs. Setting the IA address to 0xFFFF will cause the module to accept all I/O packets.

AT Command: ATIA

Parameter Range:0 – 0xFFFFFFFFFFFFFFFF

Default Parameter Value:0xFFFFFFFFFFFFFFFF (will not allow any received I/O packet to change outputs)

Minimum Firmware Version Required: v1.xA0

IC (DIO Change Detect) Command

<I/O Settings> Set/Read bitfield values for change detect monitoring. Each bit enables monitoring of DIO0 - DIO7 for changes.

If detected, data is transmitted with DIO data only. Any samples queued waiting for transmission will be sent first.

Refer to the “ADC and Digital I/O Line Support” sections of the “RF Module Operations” chapter for more information.

AT Command: ATIC

Parameter Range:0 – 0xFF [bitfield]

Default Parameter Value:0 (disabled)

Minimum Firmware Version Required: 1.xA0

ID (Pan ID) Command

<Networking {Addressing}> The ID command is used to set and read the PAN (Personal Area Network) ID of the RF module. Only modules with matching PAN IDs can communicate with each other. Unique PAN IDs enable control of which RF packets are received by a module.

Setting the ID parameter to 0xFFFF indicates a global transmission for all PANs. It does not indicate a global receive.

AT Command: ATID

Parameter Range: 0 – 0xFFFF

Default Parameter Value:0x3332 (13106 decimal)

IO (Digital Output Level) Command

<I/O Settings> The IO command is used to set digital output levels. This allows DIO lines setup as outputs to be changed through Command Mode.

AT Command: ATIO

Parameter Range: 8-bit bitmap (where each bit represents the level of an I/O line that is setup as an output.)

Minimum Firmware Version Required: v1.xA0

IR (Sample Rate) Command

<I/O Settings> The IR command is used to set/read the sample rate. When set, the module will sample all enabled DIO/ADC lines at a specified interval. This command allows periodic reads of the ADC and DIO lines in a non-Sleep Mode setup.

Example: When IR = 0x0A, the sample rate is 10 ms (or 100 Hz).

AT Command: ATIR

Parameter Range: 0 - 0xFFFF [x 1 msec] (cannot guarantee 1 ms timing when IT=1)

Default Parameter Value:0

Related Command: IT (Samples before TX)

Minimum Firmware Version Required: v1.xA0

IS (Force Sample) Command

<I/O Settings> The IS command is used to force a read of all enabled DIO/ADC lines. The data is returned through the UART.

When operating in Transparent Mode (AP=0), the data is retuned in the following format:

AT Command: ATIS

Parameter Range: 1 - 0xFF

Default Parameter Value:1

Minimum Firmware Version Required: v1.xA0

All bytes are converted to ASCII:
number of samples<CR>
channel mask<CR>
DIO data<CR> (If DIO lines are enabled<CR>
ADC channel Data<cr> <-This will repeat for every enabled ADC channel<CR>
<CR> (end of data noted by extra <CR>)

When operating in API mode (AP > 0), the command will immediately return an 'OK' response. The data will follow in the normal API format for DIO data.

IT (Samples before TX) Command

<I/O Settings> The IT command is used to set/read the number of DIO and ADC samples to collect before transmitting data.

One ADC sample is considered complete when all enabled ADC channels have been read. The module can buffer up to 93 Bytes of sample data. Since the module uses a 10-bit A/D converter, each sample uses two Bytes. This leads to a maximum buffer size of 46 samples or IT=0x2E.

AT Command: ATIT

Parameter Range: 1 - 0xFF

Default Parameter Value:1

Minimum Firmware Version Required: v1.xA0

When Sleep Modes are enabled and IR (Sample Rate) is set, the module will remain awake until IT samples have been collected.

IU (I/O Output Enable) Command

<I/O Settings> The IU command is used to disable/enable I/O UART output. When enabled (IU = 1), received I/O line data packets are sent out the UART. The data is sent using an API frame regardless of the current AP parameter value.

AT Command: ATIU

Parameter Range:0 – 1

Parameter	Configuration
0	Disabled – Received I/O line data packets will NOT sent out UART.
1	Enabled – Received I/O line data will be sent out UART

Default Parameter Value:1

Minimum Firmware Version Required: 1.xA0

KY (AES Encryption Key) Command

<Networking {Security}> The KY command is used to set the 128-bit AES (Advanced Encryption Standard) key for encrypting/decrypting data. Once set, the key cannot be read out of the module by any means.

AT Command: ATKY

Parameter Range:0 – (any 16–Byte value)

Default Parameter Value:0

Related Command: EE (Encryption Enable)

Minimum Firmware Version Required: v1.xA0

The entire payload of the packet is encrypted using the key and the CRC is computed across the ciphertext. When encryption is enabled, each packet carries an additional 16 Bytes to convey the random CBC Initialization Vector (IV) to the receiver(s). The KY value may be “0” or any 128-bit value. Any other value, including entering KY by itself with no parameters, is invalid. All ATKY entries (valid or not) are received with a returned 'OK'.

A module with the wrong key (or no key) will receive encrypted data, but the data driven out the serial port will be meaningless. A module with a key and encryption enabled will receive data sent from a module without a key and the correct unencrypted data output will be sent out the serial port. Because CBC mode is utilized, repetitive data appears differently in different transmissions due to the randomly-generated IV.

When queried, the system will return an ‘OK’ message and the value of the key will not be returned.

M0 (PWM0 Output Level) Command

<I/O Settings> The M0 command is used to set/read the output level of the PWM0 line (pin 6).

Before setting the line as an output:

1. Enable PWM0 output (P0 = 2)
2. Apply settings (use CN or AC)

The PWM period is 64 µsec and there are 0x03FF (1023 decimal) steps within this period. When M0 = 0 (0% PWM), 0x01FF (50% PWM), 0x03FF (100% PWM), etc.

AT Command: ATM0

Parameter Range:0 – 0x03FF [steps]

Default Parameter Value:0

Related Commands: P0 (PWM0 Enable), AC (Apply Changes), CN (Exit Command Mode)

Minimum Firmware Version Required: v1.xA0

M1 (PWM1 Output Level) Command

<I/O Settings> The M1 command is used to set/read the output level of the PWM1 line (pin 7).

Before setting the line as an output:

1. Enable PWM1 output (P1 = 2)
2. Apply settings (use CN or AC)

AT Command: ATM1

Parameter Range:0 – 0x03FF

Default Parameter Value:0

Related Commands: P1 (PWM1 Enable), AC (Apply Changes), CN (Exit Command Mode)

Minimum Firmware Version Required: v1.xA0

MM (MAC Mode) Command

<Networking {Addressing}> The MM command is used to set and read the MAC Mode value. The MM command disables/enables the use of a MaxStream header contained in the 802.15.4 RF packet. By default (MM = 0), MaxStream Mode is enabled and the module adds an extra header to the data portion of the 802.15.4 packet. This enables the following features:

- ND and DN command support
- Duplicate packet detection when using ACKs

The MM command allows users to turn off the use of the extra header. Modes 1 and 2 are strict 802.15.4 modes. If the MaxStream header is disabled, ND and DN parameters are also disabled.

Note: When MM > 0, application and CCA failure retries are not supported.

AT Command: ATMM

Parameter Range:0 – 2

Parameter	Configuration
0	MaxStream Mode (802.15.4 + MaxStream header)
1	802.15.4 (no ACKs)
2	802.15.4 (with ACKs)

Default Parameter Value:0

Related Commands: ND (Node Discover), DN (Destination Node)

Minimum Firmware Version Required: v1.x80

MY (16-bit Source Address) Command

<Networking {Addressing}> The MY command is used to set and read the 16-bit source address of the RF module.

By setting MY to 0xFFFF, the reception of RF packets having a 16-bit address is disabled. The 64-bit address is the module's serial number and is always enabled.

AT Command: ATMY

Parameter Range: 0 – 0xFFFF

Default Parameter Value: 0

Related Commands: DH (Destination Address High), DL (Destination Address Low), CH (Channel), ID (PAN ID)

NB (Parity) Command

<Serial Interfacing> The NB command is used to select/read the parity settings of the RF module for UART communications.

AT Command: ATNB

Parameter Range: 0 – 4

Parameter	Configuration
0	8-bit (no parity or 7-bit (any parity)
1	8-bit even
2	8-bit odd
3	8-bit mark
4	8-bit space

Default Parameter Value: 0

Number of bytes returned: 1

ND (Node Discover) Command

<Networking {Identification}> The ND command is used to discover and report all modules on its current operating channel (CH parameter) and PAN ID (ID parameter). ND also accepts an NI (Node Identifier) value as a parameter. In this case, only a module matching the supplied identifier will respond.

AT Command: ATND
Range: optional 20-character NI value
Related Commands: CH (Channel), ID (Pan ID), MY (Source Address), SH (Serial Number High), SL (Serial Number Low), NI (Node Identifier), NT (Node Discover Time)
Minimum Firmware Version Required: v1.x80

ND uses a 64-bit long address when sending and responding to an ND request. The ND command causes a module to transmit a globally addressed ND command packet. The amount of time allowed for responses is determined by the NT (Node Discover Time) parameter.

In AT Command mode, command completion is designated by a carriage return (0x0D). Since two carriage returns end a command response, the application will receive three carriage returns at the end of the command. If no responses are received, the application should only receive one carriage return. When in API mode, the application should receive a frame (with no data) and status (set to 'OK') at the end of the command. When the ND command packet is received, the remote sets up a random time delay (up to 2.2 sec) before replying as follows:

Node Discover Response (AT command mode format - Transparent operation):
MY (Source Address) value<CR>
SH (Serial Number High) value<CR>
SL (Serial Number Low) value<CR>
DB (Received Signal Strength) value<CR>
NI (Node Identifier) value<CR>
<CR> (This is part of the response and not the end of command indicator.)

Node Discover Response (API format - data is binary (except for NI)):
2 bytes for MY (Source Address) value
4 bytes for SH (Serial Number High) value
4 bytes for SL (Serial Number Low) value
1 byte for DB (Received Signal Strength) value
NULL-terminated string for NI (Node Identifier) value (max 20 bytes w/out NULL terminator)

NI (Node Identifier) Command

<Networking {Identification}> The NI command is used to set and read a string for identifying a particular node.

AT Command: ATNI
Parameter Range: 20-character ASCII string
Related Commands: ND (Node Discover), DN (Destination Node)
Minimum Firmware Version Required: v1.x80

Rules:

- Register only accepts printable ASCII data.
- A string can not start with a space.
- A carriage return ends command
- Command will automatically end when maximum bytes for the string have been entered.

This string is returned as part of the ND (Node Discover) command. This identifier is also used with the DN (Destination Node) command.

NT (Node Discover Time) Command

<Networking {Identification}> The NT command is used to set the amount of time a base node will wait for responses from other nodes when using the ND (Node Discover) command. The NT value is transmitted with the ND command.

AT Command: ATNT
Parameter Range: 0x01 - 0xFC [x 100 msec]
Default: 0x19 (2.5 decimal seconds)
Related Commands: ND (Node Discover)
Minimum Firmware Version Required: 1.xA0

Remote nodes will set up a random hold-off time based on this time. The remotes will adjust this time down by 250 ms to give each node the ability to respond before the base ends the command. Once the ND command has ended, any response received on the base would be discarded.

P0 (PWM0 Configuration) Command

<I/O Setting {I/O Line Passing}> The P0 command is used to select/read the function for PWM0 (Pulse Width Modulation output 0). This command enables the option of translating incoming data to a PWM so that the output can be translated back into analog form.

With the IA (I/O Input Address) parameter correctly set, AD0 values can automatically be passed to PWM0.

AT Command: ATP0
The second character in the command is the number zero ("0"), not the letter "O".

Parameter Range: 0 – 2

Parameter	Configuration
0	Disabled
1	RSSI
2	PWM0 Output

Default Parameter Value: 1

P1 (PWM1 Configuration) Command

<I/O Setting {I/O Line Passing}> The P1 command is used to select/read the function for PWM1 (Pulse Width Modulation output 1). This command enables the option of translating incoming data to a PWM so that the output can be translated back into analog form.

With the IA (I/O Input Address) parameter correctly set, AD1 values can automatically be passed to PWM1.

AT Command: ATP1

Parameter Range: 0 – 2

Parameter	Configuration
0	Disabled
1	RSSI
2	PWM1 Output

Default Parameter Value: 0

Minimum Firmware Version Required: v1.xA0

PL (Power Level) Command

<RF Interfacing> The PL command is used to select and read the power level at which the RF module transmits conducted power.

WHEN OPERATING IN EUROPE:
XBee-PRO RF Modules must be configured to operate at a maximum transmit power output level of 10 dBm. The PL parameter must equal "0" (10 dBm).

Additionally, European regulations stipulate an EIRP power maximum of 12.86 dBm (19 mW) for the XBee-PRO and 12.11 dBm for the XBee when integrating high-gain antennas.

AT Command: ATPL

Parameter Range: 0 – 4

Parameter	XBee	XBee-PRO
0	-10 dBm	10 dBm
1	-6 dBm	12 dBm
2	-4 dBm	14 dBm
3	-2 dBm	16 dBm
4	0 dBm	18 dBm

Default Parameter Value: 4

WHEN OPERATING IN JAPAN:
XBee-PRO RF Modules optimized for use in Japan contain firmware that limits transmit power output to 10 dBm. If PL=4 (default), the maximum power output level is 10 dBm. For a list of module part numbers approved for use in Japan, contact MaxStream [call 1-801-765-9885 or send e-mail to sales@maxstream.net].

PR (Pull-up Resistor Enable) Command

<Serial Interfacing> The PR command is used to set and read the bit field that is used to configure internal the pull-up resistor status for I/O lines. "1" specifies the pull-up resistor is enabled. "0" specifies no pull up.

bit 0 - AD4/DIO4 (pin 11)
bit 1 - AD3/DIO3 (pin 17)
bit 2 - AD2/DIO2 (pin 18)
bit 3 - AD1/DIO1 (pin 19)
bit 4 - AD0/DIO0 (pin 20)
bit 5 - AD6/DIO6 (pin 16)
bit 6 - DI8 (pin 9)
bit 7 - DIN/CONFIG (pin 3)

AT Command: ATPR
Parameter Range: 0 – 0xFF
Default Parameter Value: 0xFF (all pull–up resistors are enabled)
Minimum Firmware Version Required: v1.x80

For example: Sending the command "ATPR 6F" will turn bits 0, 1, 2, 3, 5 and 6 ON; and bits 4 & 7 will be turned OFF. (The binary equivalent of "0x6F" is "01101111". Note that 'bit 0' is the last digit in the bitfield.

PT (PWM Output Timeout) Command

<I/O Settings {I/O Line Passing}> The PT command is used to set/read the output timeout value for both PWM outputs.

When PWM is set to a non-zero value: Due to I/O line passing, a time is started which when expired will set the PWM output to zero. The timer is reset when a valid I/O packet is received.

AT Command: ATPT
Parameter Range: 0 – 0xFF [x 100 msec]
Default Parameter Value: 0xFF
Minimum Firmware Version Required: 1.xA0

RE (Restore Defaults) Command

<(Special)> The RE command is used to restore all configurable parameters to their factory default settings. The RE command does not write restored values to non-volatile (persistent) memory. Issue the WR (Write) command subsequent to issuing the RE command to save restored parameter values to non-volatile memory.

AT Command: ATRE

RN (Random Delay Slots) Command

<Networking & Security> The RN command is used to set and read the minimum value of the back-off exponent in the CSMA-CA algorithm. The CSMA-CA algorithm was engineered for collision avoidance (random delays are inserted to prevent data loss caused by data collisions).

AT Command: ATRN
Parameter Range: 0 – 3 [exponent]
Default Parameter Value: 0

If RN = 0, collision avoidance is disabled during the first iteration of the algorithm (802.15.4 - macMinBE).

CSMA-CA stands for "Carrier Sense Multiple Access - Collision Avoidance". Unlike CSMA-CD (reacts to network transmissions after collisions have been detected), CSMA-CA acts to prevent data collisions before they occur. As soon as a module receives a packet that is to be transmitted, it checks if the channel is clear (no other module is transmitting). If the channel is clear, the packet is sent over-the-air. If the channel is not clear, the module waits for a randomly selected period of time, then checks again to see if the channel is clear. After a time, the process ends and the data is lost.

RO (Packetization Timeout) Command

<Serial Interfacing> RO command is used to set and read the number of character times of inter-character delay required before transmission.

RF transmission commences when data is detected in the DI (data in from host) buffer and RO character times of silence are detected on the UART receive lines (after receiving at least 1 byte).

AT Command: ATRO
Parameter Range:0 – 0xFF [x character times]
Default Parameter Value: 3

RF transmission will also commence after 100 Bytes (maximum packet size) are received in the DI buffer.

Set the RO parameter to '0' to transmit characters as they arrive instead of buffering them into one RF packet.

RP (RSSI PWM Timer) Command

<I/O Settings {I/O Line Passing}> The RP command is used to enable PWM (Pulse Width Modulation) output on the RF module. The output is calibrated to show the level a received RF signal is above the sensitivity level of the module. The PWM pulses vary from 24 to 100%. Zero percent means PWM output is inactive. One to 24% percent means the received RF signal is at or below the published sensitivity level of the module. The following table shows levels above sensitivity and PWM values.

AT Command: ATRP
Parameter Range:0 – 0xFF [x 100 msec]
Default Parameter Value: 0x28 (40 decimal)

The total period of the PWM output is 64 µs. Because there are 445 steps in the PWM output, the minimum step size is 144 ns.

PWM Percentages

dB above Sensitivity	PWM percentage (high period / total period)
10	41%
20	58%
30	75%

A non-zero value defines the time that the PWM output will be active with the RSSI value of the last received RF packet. After the set time when no RF packets are received, the PWM output will be set low (0 percent PWM) until another RF packet is received. The PWM output will also be set low at power-up until the first RF packet is received. A parameter value of 0xFF permanently enables the PWM output and it will always reflect the value of the last received RF packet.

RR (XBee Retries) Command

<Networking {Addressing}> The RR command is used set/read the maximum number of retries the module will execute in addition to the 3 retries provided by the 802.15.4 MAC. For each XBee retry, the 802.15.4 MAC can execute up to 3 retries.

AT Command: ATRR
Parameter Range: 0 – 6
Default: 0
Minimum Firmware Version Required: 1.xA0

This values does not need to be set on all modules for retries to work. If retries are enabled, the transmitting module will set a bit in the Maxstream RF Packet header which requests the receiving module to send an ACK (acknowledgement). If the transmitting module does not receive an ACK within 200 msec, it will re-send the packet within a random period up to 48 msec. Each XBee retry can potentially result in the MAC sending the packet 4 times (1 try plus 3 retries). Note that retries are not attempted for packets that are purged when transmitting with a Cyclic Sleep Coordinator.

SC (Scan Channels) Command

<Networking {Association}> The SC command is used to set and read the list of channels to scan for all Active and Energy Scans as a bit field.

This affects scans initiated in command mode [AS (Active Scan) and ED (Energy Scan) commands] and during End Device Association and Coordinator startup.

AT Command: ATSC

Parameter Range: 0 – 0xFFFF [Bitfield] (bits 0, 14, 15 are not allowed when using the XBee-PRO)

Default Parameter Value: 0x1FFE (all XBee-PRO channels)

Related Commands: ED (Energy Scan), SD (Scan Duration)

Minimum Firmware Version Required: v1.x80

bit 0 - 0x0B	bit 4 - 0x0F	bit 8 - 0x13	bit 12 - 0x17
bit 1 - 0x0C	bit 5 - 0x10	bit 9 - 0x14	bit 13 - 0x18
bit 2 - 0x0D	bit 6 - 0x11	bit 10 - 0x15	bit 14 - 0x19
bit 3 - 0x0E	bit 7 - 0x12	bit 11 - 0x16	bit 15 - 0x1A

SD (Scan Duration) Command

<Networking {Association}> The SD command is used to set and read the exponent value that determines the duration (in time) of a scan.

AT Command: ATSD

Parameter Range: 0 – 0x0F

Default Parameter Value: 4

Related Commands: ED (Energy Scan), SC (Scan Channel)

Minimum Firmware Version Required: v1.x80

End Device (Duration of Active Scan during Association) - In a Beacon system, set SD = BE of the Coordinator. SD must be set at least to the highest BE parameter of any Beaconing Coordinator with which an End Device or Coordinator wish to discover.

Coordinator - If the 'ReassignPANID' option is set on the Coordinator [refer to A2 parameter], the SD parameter determines the length of time the Coordinator will scan channels to locate existing PANs. If the 'ReassignChannel' option is set, SD determines how long the Coordinator will perform an Energy Scan to determine which channel it will operate on.

Scan Time is measured as ((# of Channels to Scan) * (2 ^ SD) * 15.36ms). The number of channels to scan is set by the SC command. The XBee RF Module can scan up to 16 channels (SC = 0xFFFF). The XBee PRO RF Module can scan up to 12 channels (SC = 0x1FFE).

Examples: Values below show results for a 12-channel scan

If SD = 0, time = 0.18 sec	SD = 8, time = 47.19 sec
SD = 2, time = 0.74 sec	SD = 10, time = 3.15 min
SD = 4, time = 2.95 sec	SD = 12, time = 12.58 min
SD = 6, time = 11.80 sec	SD = 14, time = 50.33 min

SH (Serial Number High) Command

<Diagnostics> The SH command is used to read the high 32 bits of the RF module's unique IEEE 64-bit address.

The module serial number is set at the factory and is read-only.

AT Command: ATSH

Parameter Range: 0 – 0xFFFFFFFF [read-only]

Related Commands: SL (Serial Number Low), MY (Source Address)

SL (Serial Number Low) Command

<Diagnostics> The SL command is used to read the low 32 bits of the RF module's unique IEEE 64-bit address.

The module serial number is set at the factory and is read-only.

AT Command: ATSL

Parameter Range: 0 – 0xFFFFFFFF [read-only]

Related Commands: SH (Serial Number High), MY (Source Address)

SM (Sleep Mode) Command

<Sleep Mode (Low Power)> The SM command is used to set and read Sleep Mode settings. By default, Sleep Modes are disabled (SM = 0) and the RF module remains in Idle/Receive Mode. When in this state, the module is constantly ready to respond to either serial or RF activity.

SM command options vary according to the networking system type. By default, the module is configured to operate in a NonBeacon system.

* The Sleep Coordinator option (SM=6) only exists for backwards compatibility with firmware version 1.x06 only. In all other cases, use the CE command to enable a Coordinator.

AT Command: ATSM

Parameter Range: 0 – 6

Parameter	Configuration
0	Disabled
1	Pin Hibernate
2	Pin Doze
3	(reserved)
4	Cyclic Sleep Remote
5	Cyclic Sleep Remote (with Pin Wake-up)
6	Sleep Coordinator*

Default Parameter Value: 0

Related Commands: SP (Cyclic Sleep Period), ST (Time before Sleep)

SP (Cyclic Sleep Period) Command

<Sleep Mode (Low Power)> The SP command is used to set and read the duration of time in which a remote RF module sleeps. After the cyclic sleep period is over, the module wakes and checks for data. If data is not present, the module goes back to sleep. The maximum sleep period is 268 seconds (SP = 0x68B0).

The SP parameter is only valid if the module is configured to operate in Cyclic Sleep (SM = 4-6). Coordinator and End Device SP values should always be equal.

To send Direct Messages, set SP = 0.

AT Command: ATSP

Parameter Range:	NonBeacon Firmware: 1 – 0x68B0 [x 10 milliseconds]
Default Parameter Value:	NonBeacon Firmware: 0

Related Commands: SM (Sleep Mode), ST (Time before Sleep), DP (Disassociation Cyclic Sleep Period, BE (Beacon Order)

NonBeacon Firmware

End Device - SP determines the sleep period for cyclic sleeping remotes. Maximum sleep period is 268 seconds (0x68B0).

Coordinator - If non-zero, SP determines the time to hold an indirect message before discarding it. A Coordinator will discard indirect messages after a period of (2.5 * SP).

ST (Time before Sleep) Command

<Sleep Mode (Low Power)> The ST command is used to set and read the period of inactivity (no serial or RF data is sent or received) before activating Sleep Mode.

NonBeacon Firmware

Set/Read time period of inactivity (no serial or RF data is sent or received) before activating Sleep Mode. ST parameter is only valid with Cyclic Sleep settings (SM = 4 - 5).

Coordinator and End Device ST values must be equal.

AT Command: ATST

Parameter Range:	NonBeacon Firmware: 1 – 0xFFFF [x 1 millisecond]
Default Parameter Value:	NonBeacon Firmware: 0x1388 (5000 decimal)

Related Commands: SM (Sleep Mode), ST (Time before Sleep)

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T0 - T7 ((D0-D7) Output Timeout) Command

AT Commands: ATT0 – ATT7
Parameter Range:0 – 0xFF [x 100 msec]
Default Parameter Value:0xFF
Minimum Firmware Version Required: v1.xA0

<I/O Settings {I/O Line Passing}> The T0, T1, T2, T3, T4, T5, T6 and T7 commands are used to set/read output timeout values for the lines that correspond with the D0 - D7 parameters. When output is set (due to I/O line passing) to a non-default level, a timer is started which when expired, will set the output to its default level. The timer is reset when a valid I/O packet is received. The Tn parameter defines the permissible amount of time to stay in a non-default (active) state. If Tn = 0, Output Timeout is disabled (output levels are held indefinitely).

VL (Firmware Version - Verbose)

AT Command: ATVL
Parameter Range:0 – 0xFF [x 100 milliseconds]
Default Parameter Value: 0x28 (40 decimal)
Minimum Firmware Version Required: v1.x80

<Diagnostics> The VL command is used to read detailed version information about the RF module. The information includes:
application build date; MAC, PHY and bootloader versions; and build dates.

VR (Firmware Version) Command

AT Command: ATVR
Parameter Range: 0 – 0xFFFF [read only]

<Diagnostics> The VR command is used to read which firmware version is stored in the module.

XBee version numbers will have four significant digits. The reported number will show three or four numbers and is stated in hexadecimal notation. A version can be reported as "ABC" or "ABCD". Digits ABC are the main release number and D is the revision number from the main release. "D" is not required and if it is not present, a zero is assumed for D. "B" is a variant designator. The following variants exist:

- "0" = Non-Beacon Enabled 802.15.4 Code
- "1" = Beacon Enabled 802.15.4 Code

WR (Write) Command

AT Command: ATWR

<(Special)> The WR command is used to write configurable parameters to the RF module's non-volatile memory. Parameter values remain in the module's memory until overwritten by subsequent use of the WR Command.

If changes are made without writing them to non-volatile memory, the module reverts back to previously saved parameters the next time the module is powered-on.

NOTE: Once the WR command is sent to the module, no additional characters should be sent until after the “OK/r” response is received.

3.4. API Operation

By default, XBee/XBee-PRO RF Modules act as a serial line replacement (Transparent Operation) - all UART data received through the DI pin is queued up for RF transmission. When the module receives an RF packet, the data is sent out the DO pin with no additional information.

Inherent to Transparent Operation are the following behaviors:

- If module parameter registers are to be set or queried, a special operation is required for transitioning the module into Command Mode.
- In point-to-multipoint systems, the application must send extra information so that the receiving module(s) can distinguish between data coming from different remotes.

As an alternative to the default Transparent Operation, API (Application Programming Interface) Operations are available. API operation requires that communication with the module be done through a structured interface (data is communicated in frames in a defined order). The API specifies how commands, command responses and module status messages are sent and received from the module using a UART Data Frame.

3.4.1. API Frame Specifications

Two API modes are supported and both can be enabled using the AP (API Enable) command. Use the following AP parameter values to configure the module to operate in a particular mode:

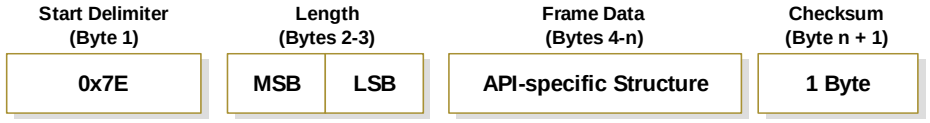
- AP = 0 (default): Transparent Operation (UART Serial line replacement)
  API modes are disabled.
- AP = 1: API Operation
- AP = 2: API Operation (with escaped characters)

Any data received prior to the start delimiter is silently discarded. If the frame is not received correctly or if the checksum fails, the data is silently discarded.

API Operation (AP parameter = 1)

When this API mode is enabled (AP = 1), the UART data frame structure is defined as follows:

Figure 3-01. UART Data Frame Structure:

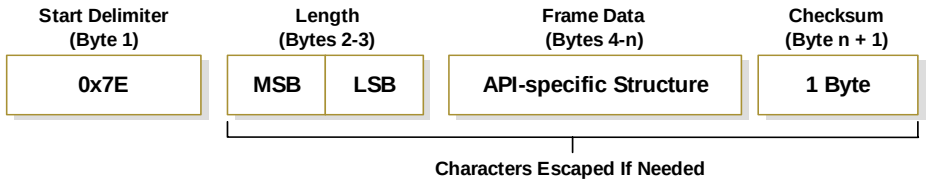


MSB = Most Significant Byte, LSB = Least Significant Byte

API Operation - with Escape Characters (AP parameter = 2)

When this API mode is enabled (AP = 2), the UART data frame structure is defined as follows:

Figure 3-02. UART Data Frame Structure - with escape control characters:



MSB = Most Significant Byte, LSB = Least Significant Byte

Escape characters. When sending or receiving a UART data frame, specific data values must be escaped (flagged) so they do not interfere with the UART or UART data frame operation. To escape an interfering data byte, insert 0x7D and follow it with the byte to be escaped XOR'd with 0x20.

Data bytes that need to be escaped:

- 0x7E – Frame Delimiter
- 0x7D – Escape
- 0x11 – XON
- 0x13 – XOFF

Example - Raw UART Data Frame (before escaping interfering bytes):
0x7E 0x00 0x02 0x23 0x11 0xCB

0x11 needs to be escaped which results in the following frame:
0x7E 0x00 0x02 0x23 0x7D 0x31 0xCB

Note: In the above example, the length of the raw data (excluding the checksum) is 0x0002 and the checksum of the non-escaped data (excluding frame delimiter and length) is calculated as: 0xFF - (0x23 + 0x11) = (0xFF - 0x34) = 0xCB.

Checksum

To test data integrity, a checksum is calculated and verified on non-escaped data.

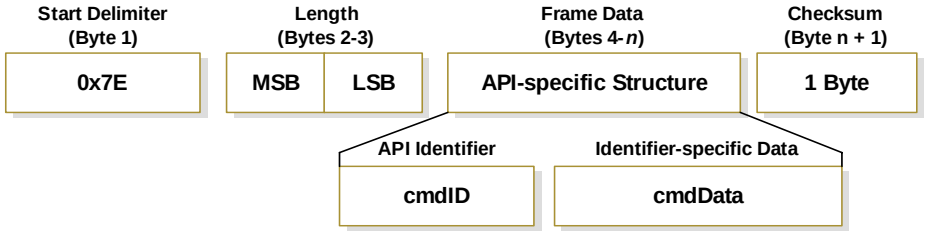
To calculate: Not including frame delimiters and length, add all bytes keeping only the lowest 8 bits of the result and subtract from 0xFF.

To verify: Add all bytes (include checksum, but not the delimiter and length). If the checksum is correct, the sum will equal 0xFF.

3.4.2. API Types

Frame data of the UART data frame forms an API-specific structure as follows:

Figure 3-03. UART Data Frame & API-specific Structure:

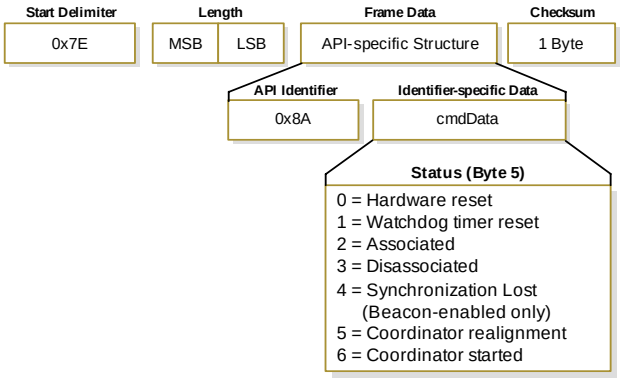


The cmdID frame (API-identifier) indicates which API messages will be contained in the cmdData frame (Identifier-specific data). Refer to the sections that follow for more information regarding the supported API types. Note that multi-byte values are sent big endian.

Modem Status

API Identifier: 0x8A
RF module status messages are sent from the module in response to specific conditions.

Figure 3-04. Modem Status Frames



AT Command

API Identifier Value: 0x08

The "AT Command" API type allows for module parameters to be queried or set. When using this command ID, new parameter values are applied immediately. This includes any register set with the "AT Command - Queue Parameter Value" (0x09) API type.

Figure 3-05. AT Command Frames

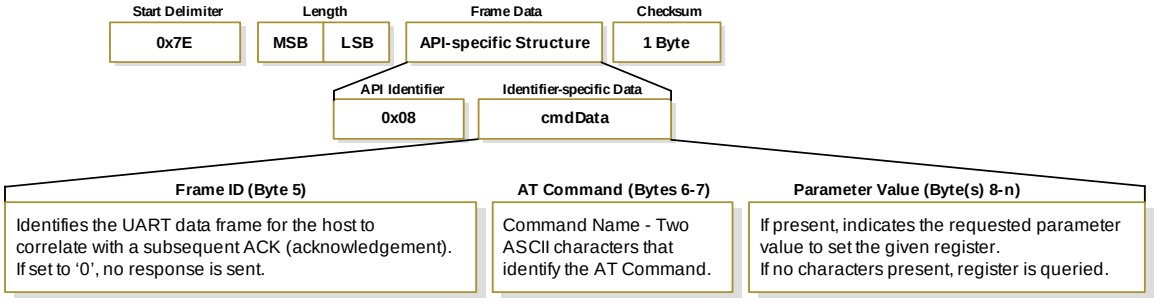
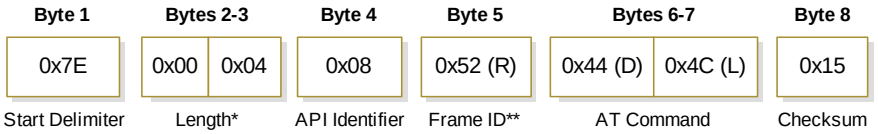

Start Delimiter
0x7E
Length
MSB
LSB
Frame Data
API-specific Structure
Checksum
1 Byte
API Identifier
0x08
Identifier-specific Data
cmdData
Frame ID (Byte 5)
Identifies the UART data frame for the host to correlate with a subsequent ACK (acknowledgement). If set to '0', no response is sent.
AT Command (Bytes 6-7)
Command Name - Two ASCII characters that identify the AT Command.
Parameter Value (Byte(s) 8-n)
If present, indicates the requested parameter value to set the given register. If no characters present, register is queried.

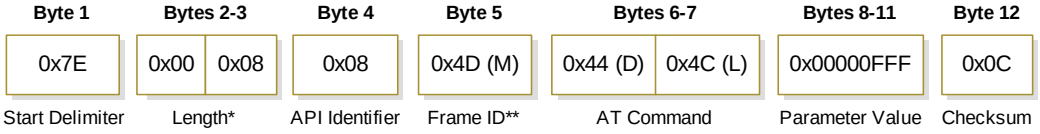
Figure 3-06. Example: API frames when reading the DL parameter value of the module.



** Length [Bytes] = API Identifier + Frame ID + AT Command*

*** "R" value was arbitrarily selected.*

Figure 3-07. Example: API frames when modifying the DL parameter value of the module.



** Length [Bytes] = API Identifier + Frame ID + AT Command + Parameter Value*

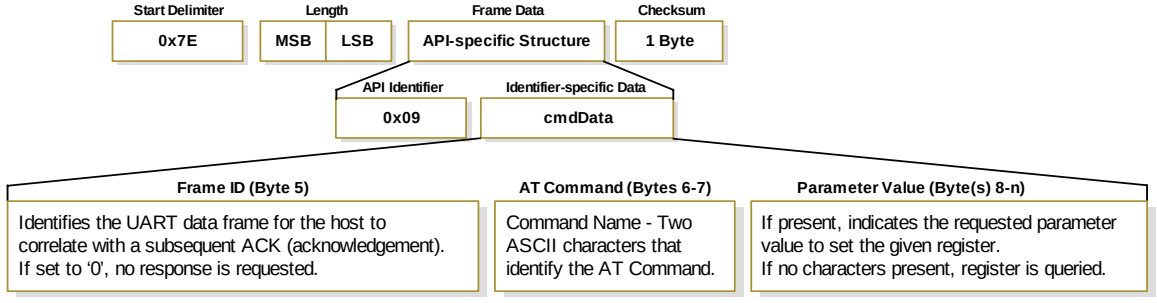
*** "M" value was arbitrarily selected.*

AT Command - Queue Parameter Value

API Identifier Value: 0x09

This API type allows module parameters to be queried or set. In contrast to the "AT Command" API type, new parameter values are queued and not applied until either the "AT Command" (0x08) API type or the AC (Apply Changes) command is issued. Register queries (reading parameter values) are returned immediately.

Figure 3-08. AT Command Frames
(Note that frames are identical to the "AT Command" API type except for the API identifier.)

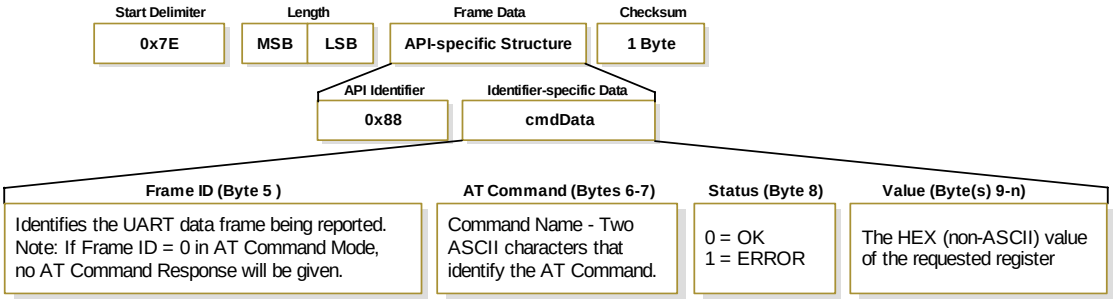

Start Delimiter
0x7E
Length
MSB
LSB
Frame Data
API-specific Structure
Checksum
1 Byte
API Identifier
0x09
Identifier-specific Data
cmdData
Frame ID (Byte 5)
Identifies the UART data frame for the host to correlate with a subsequent ACK (acknowledgement). If set to '0', no response is requested.
AT Command (Bytes 6-7)
Command Name - Two ASCII characters that identify the AT Command.
Parameter Value (Byte(s) 8-n)
If present, indicates the requested parameter value to set the given register. If no characters present, register is queried.

AT Command Response

API Identifier Value: 0x88
Response to previous command.

In response to an AT Command message, the module will send an AT Command Response message. Some commands will send back multiple frames (for example, the ND (Node Discover) and AS (Active Scan) commands). These commands will end by sending a frame with a status of ATCMD_OK and no cmdData.

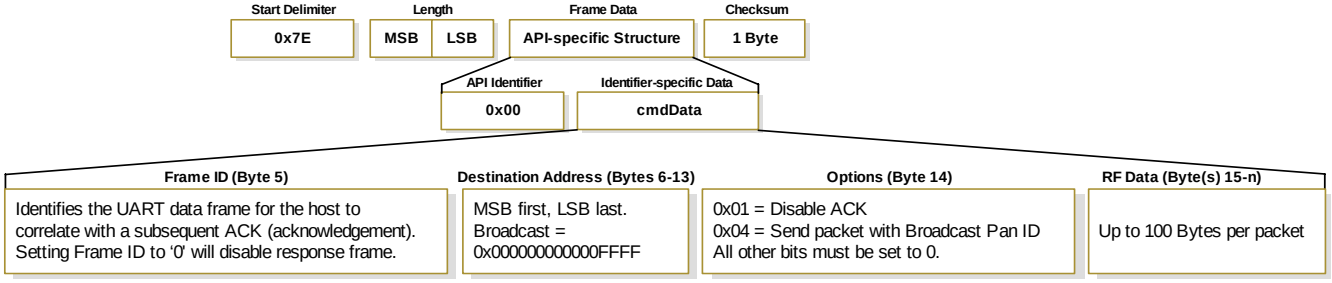
Figure 3-09. AT Command Response Frames.



TX (Transmit) Request: 64-bit address

API Identifier Value: 0x00
A TX Request message will cause the module to send RF Data as an RF Packet.

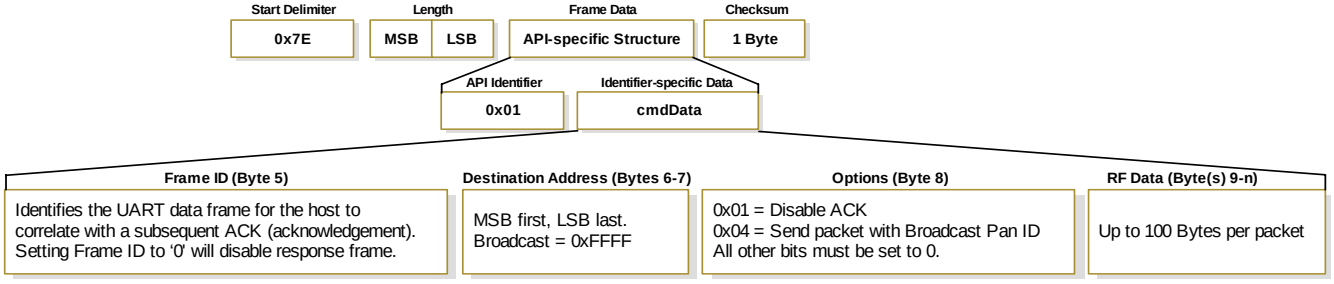
Figure 3-10. TX Packet (64-bit address) Frames



TX (Transmit) Request: 16-bit address

API Identifier Value: 0x01
A TX Request message will cause the module to send RF Data as an RF Packet.

Figure 3-11. TX Packet (16-bit address) Frames

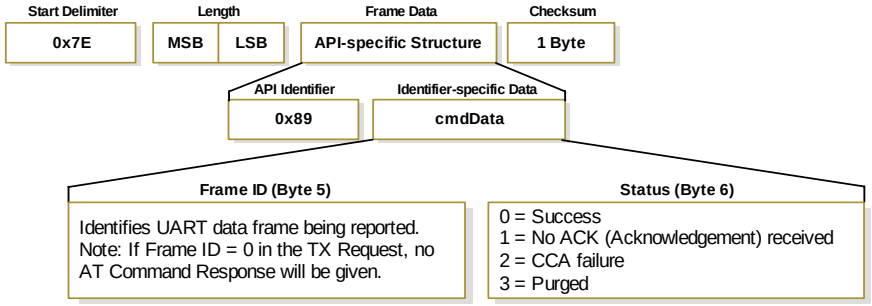


TX (Transmit) Status

API Identifier Value: 0x89

When a TX Request is completed, the module sends a TX Status message. This message will indicate if the packet was transmitted successfully or if there was a failure.

Figure 3-12. TX Status Frames



NOTES:

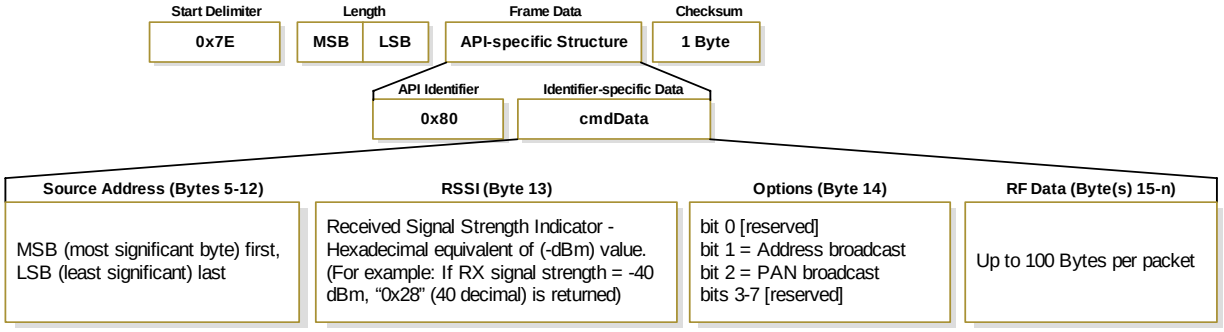
- "STATUS = 1" occurs when all retries are expired and no ACK is received.
- If transmitter broadcasts (destination address = 0x000000000000FFFF), only "STATUS = 0 or 2" will be returned.
- "STATUS = 3" occurs when Coordinator times out of an indirect transmission. Timeout is defined as (2.5 x SP (Cyclic Sleep Period) parameter value).

RX (Receive) Packet: 64-bit Address

API Identifier Value: 0x80

When the module receives an RF packet, it is sent out the UART using this message type.

Figure 3-13. RX Packet (64-bit address) Frames

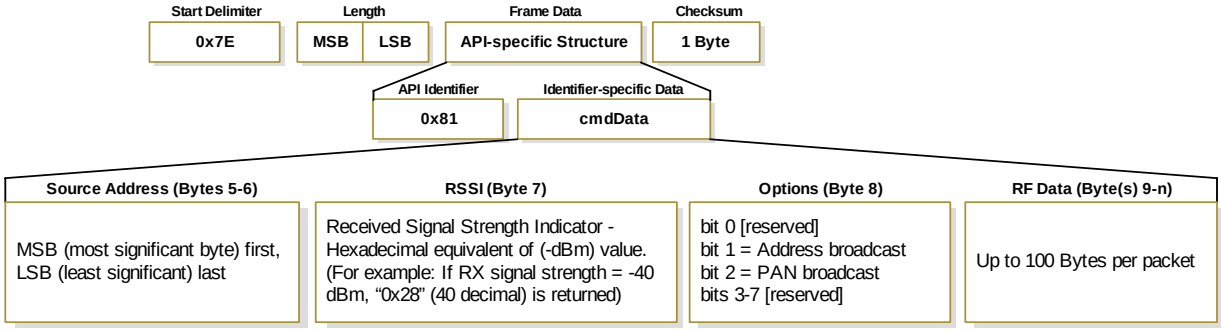


RX (Receive) Packet: 16-bit Address

API Identifier Value: 0x81

When the module receives an RF packet, it is sent out the UART using this message type.

Figure 3-14. RX Packet (16-bit address) Frames



Appendix A: Agency Certifications

United States (FCC)

XBee/XBee-PRO RF Modules comply with Part 15 of the FCC rules and regulations. Compliance with the labeling requirements, FCC notices and antenna usage guidelines is required.

To fulfill FCC Certification requirements, the OEM must comply with the following regulations:

1. The system integrator must ensure that the text on the external label provided with this device is placed on the outside of the final product [Figure A-01].
2. XBee/XBee-PRO RF Modules may only be used with antennas that have been tested and approved for use with this module [refer to the antenna tables in this section].

OEM Labeling Requirements

WARNING: The Original Equipment Manufacturer (OEM) must ensure that FCC labeling requirements are met. This includes a clearly visible label on the outside of the final product enclosure that displays the contents shown in the figure below.

Figure A-01. Required FCC Label for OEM products containing the XBee/XBee-PRO RF Module

Contains FCC ID: OUR-XBEE/OUR-XBEEPRO*

The enclosed device complies with Part 15 of the FCC Rules. Operation is subject to the following two conditions: (*i.*) this device may not cause harmful interference and (*ii.*) this device must accept any interference received, including interference that may cause undesired operation.

* The FCC ID for the XBee is "OUR-XBEE". The FCC ID for the XBee-PRO is "OUR-XBEEPRO".

FCC Notices

IMPORTANT: The XBee/XBee-PRO OEM RF Module has been certified by the FCC for use with other products without any further certification (as per FCC section 2.1091). Modifications not expressly approved by MaxStream could void the user's authority to operate the equipment.

IMPORTANT: OEMs must test final product to comply with unintentional radiators (FCC section 15.107 & 15.109) before declaring compliance of their final product to Part 15 of the FCC Rules.

IMPORTANT: The RF module has been certified for remote and base radio applications. If the module will be used for portable applications, the device must undergo SAR testing.

This equipment has been tested and found to comply with the limits for a Class B digital device, pursuant to Part 15 of the FCC Rules. These limits are designed to provide reasonable protection against harmful interference in a residential installation. This equipment generates, uses and can radiate radio frequency energy and, if not installed and used in accordance with the instructions, may cause harmful interference to radio communications. However, there is no guarantee that interference will not occur in a particular installation.

If this equipment does cause harmful interference to radio or television reception, which can be determined by turning the equipment off and on, the user is encouraged to try to correct the interference by one or more of the following measures: Re-orient or relocate the receiving antenna, Increase the separation between the equipment and receiver, Connect equipment and receiver to outlets on different circuits, or Consult the dealer or an experienced radio/TV technician for help.

FCC-Approved Antennas (2.4 GHz)

XBee/XBee-PRO RF Modules can be installed using antennas and cables constructed with standard connectors (Type-N, SMA, TNC, etc.) if the installation is performed professionally and according to FCC guidelines. For installations not performed by a professional, non-standard connectors (RPSMA, RPTNC, etc) must be used.

The modules are FCC-approved for fixed base station and mobile applications on channels 0x0B - 0x1A (XBee) and 0x0C - 0x17 (XBee-PRO). If the antenna is mounted at least 20cm (8 in.) from nearby persons, the application is considered a mobile application. Antennas not listed in the table must be tested to comply with FCC Section 15.203 (Unique Antenna Connectors) and Section 15.247 (Emissions).

XBee OEM RF Modules (1 mW): XBee Modules have been tested and approved for use with all of the antennas listed in the tables below (Cable-loss IS NOT required).

XBee-PRO OEM RF Modules (60 mW): XBee-PRO Modules have been tested and approved for use with the antennas listed in the tables below (Cable-loss IS required when using antennas listed in Table A-02).

Table A-01. Antennas approved for use with the XBee/XBee-PRO RF Modules (Cable-loss is not required.)

Part Number	Type (Description)	Gain	Application*	Min. Separation
A24-HSM-450	Dipole (Half-wave articulated RPSMA - 4.5")	2.1 dBi	Fixed/Mobile	20 cm
A24-HABSM	Dipole (Articulated RPSMA)	2.1 dBi	Fixed	20 cm
A24-HABUF-P5I	Dipole (Half-wave articulated bulkhead mount U.FL. w/ 5" pigtail)	2.1 dBi	Fixed	20 cm
A24-QI	Monopole (Integrated whip)	1.5 dBi	Fixed	20 cm

Table A-02. Antennas approved for use with the XBee/XBee-PRO RF Modules (Cable-loss is required)

Part Number	Type (Description)	Gain	Application*	Min. Separation	Required Cable-loss
A24-C1	Surface Mount	-1.5 dBi	Fixed/Mobile	20 cm	-
A24-Y4NF	Yagi (4-element)	6.0 dBi	Fixed	2 m	8.1 dB
A24-Y6NF	Yagi (6-element)	8.8 dBi	Fixed	2 m	10.9 dB
A24-Y7NF	Yagi (7-element)	9.0 dBi	Fixed	2 m	11.1 dB
A24-Y9NF	Yagi (9-element)	10.0 dBi	Fixed	2 m	12.1 dB
A24-Y10NF	Yagi (10-element)	11.0 dBi	Fixed	2 m	13.1 dB
A24-Y12NF	Yagi (12-element)	12.0 dBi	Fixed	2 m	14.1 dB
A24-Y13NF	Yagi (13-element)	12.0 dBi	Fixed	2 m	14.1 dB
A24-Y15NF	Yagi (15-element)	12.5 dBi	Fixed	2 m	14.6 dB
A24-Y16NF	Yagi (16-element)	13.5 dBi	Fixed	2 m	15.6 dB
A24-Y16RM	Yagi (16-element, RPSMA connector)	13.5 dBi	Fixed	2 m	15.6 dB
A24-Y18NF	Yagi (18-element)	15.0 dBi	Fixed	2 m	17.1 dB
A24-F2NF	Omni-directional (Fiberglass base station)	2.1 dBi	Fixed/Mobile	20 cm	4.2 dB
A24-F3NF	Omni-directional (Fiberglass base station)	3.0 dBi	Fixed/Mobile	20 cm	5.1 dB
A24-F5NF	Omni-directional (Fiberglass base station)	5.0 dBi	Fixed/Mobile	20 cm	7.1 dB
A24-F8NF	Omni-directional (Fiberglass base station)	8.0 dBi	Fixed	2 m	10.1 dB
A24-F9NF	Omni-directional (Fiberglass base station)	9.5 dBi	Fixed	2 m	11.6 dB
A24-F10NF	Omni-directional (Fiberglass base station)	10.0 dBi	Fixed	2 m	12.1 dB
A24-F12NF	Omni-directional (Fiberglass base station)	12.0 dBi	Fixed	2 m	14.1 dB
A24-F15NF	Omni-directional (Fiberglass base station)	15.0 dBi	Fixed	2 m	17.1 dB
A24-W7NF	Omni-directional (Base station)	7.2 dBi	Fixed	2 m	9.3 dB
A24-M7NF	Omni-directional (Mag-mount base station)	7.2 dBi	Fixed	2 m	9.3 dB
A24-P8SF	Flat Panel	8.5 dBi	Fixed	2 m	8.6 dB
A24-P8NF	Flat Panel	8.5 dBi	Fixed	2 m	8.6 dB
A24-P13NF	Flat Panel	13.0 dBi	Fixed	2 m	13.1 dB
A24-P14NF	Flat Panel	14.0 dBi	Fixed	2 m	14.1 dB
A24-P15NF	Flat Panel	15.0 dBi	Fixed	2 m	15.1 dB
A24-P16NF	Flat Panel	16.0 dBi	Fixed	2 m	16.1 dB
A24-P19NF	Flat Panel	19.0 dBi	Fixed	2 m	19.1 dB

*** If using the RF module in a portable application** (For example - If the module is used in a handheld device and the antenna is less than 20cm from the human body when the device is operation): The integrator is responsible for passing additional SAR (Specific Absorption Rate) testing based on FCC rules 2.1091 and FCC Guidelines for Human Exposure to Radio Frequency Electromagnetic Fields, OET Bulletin and Supplement C. The testing results will be submitted to the FCC for approval prior to selling the integrated unit. The required SAR testing measures emissions from the module and how they affect the person.

RF Exposure

WARNING: To satisfy FCC RF exposure requirements for mobile transmitting devices, a separation distance of 20 cm or more should be maintained between the antenna of this device and persons during device operation. To ensure compliance, operations at closer than this distance is not recommended. The antenna used for this transmitter must not be co-located in conjunction with any other antenna or transmitter.

The preceding statement must be included as a CAUTION statement in OEM product manuals in order to alert users of FCC RF Exposure compliance.

Europe (ETSI)

The XBee/XBee-PRO RF Module has been certified for use in several European countries. For a complete list, refer to www.maxstream.net.

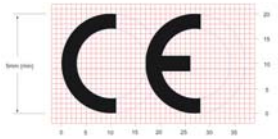
If the XBee/XBee-PRO RF Modules are incorporated into a product, the manufacturer must ensure compliance of the final product to the European harmonized EMC and low-voltage/safety standards. A Declaration of Conformity must be issued for each of these standards and kept on file as described in Annex II of the R&TTE Directive.

Furthermore, the manufacturer must maintain a copy of the XBee/XBee-PRO user manual documentation and ensure the final product does not exceed the specified power ratings, antenna specifications, and/or installation requirements as specified in the user manual. If any of these specifications are exceeded in the final product, a submission must be made to a notified body for compliance testing to all required standards.

OEM Labeling Requirements

The 'CE' marking must be affixed to a visible location on the OEM product.

Figure A-02. CE Labeling Requirements



The CE mark shall consist of the initials "CE" taking the following form:

- If the CE marking is reduced or enlarged, the proportions given in the above graduated drawing must be respected.
- The CE marking must have a height of at least 5mm except where this is not possible on account of the nature of the apparatus.
- The CE marking must be affixed visibly, legibly, and indelibly.

Restrictions

Power Output: The power output of the XBee-PRO RF Modules must not exceed 10 dBm. The power level is set using the PL command and the PL parameter must equal “0” (10 dBm).

France: France imposes restrictions on the 2.4 GHz band. Go to www.art-telecom.Fr or contact MaxStream for more information.

Norway: Norway prohibits operation near Ny-Alesund in Svalbard. More information can be found at the Norway Posts and Telecommunications site (www.npt.no).

Declarations of Conformity

MaxStream has issued Declarations of Conformity for the XBee/XBee-PRO RF Modules concerning emissions, EMC and safety. Files are located in the 'documentation' folder of the MaxStream CD.

Important Note

MaxStream does not list the entire set of standards that must be met for each country. MaxStream customers assume full responsibility for learning and meeting the required guidelines for each country in their distribution market. For more information relating to European compliance of an OEM product incorporating the XBee/XBee-PRO RF Module, contact MaxStream, or refer to the following web sites:

CEPT ERC 70-03E - Technical Requirements, European restrictions and general requirements: Available at www.ero.dk/.

R&TTE Directive - Equipment requirements, placement on market: Available at www.ero.dk/.

Approved Antennas

When integrating high-gain antennas, European regulations stipulate EIRP power maximums. Use the following guidelines to determine which antennas to design into an application.

XBee OEM RF Module

The following antenna types have been tested and approved for use with the XBee Module:

Antenna Type: Yagi
RF module was tested and approved with 15 dBi antenna gain with 1 dB cable-loss (EIRP Maximum of 14 dBm). Any Yagi type antenna with 14 dBi gain or less can be used with no cable-loss.

Antenna Type: Omni-directional
RF module was tested and approved with 15 dBi antenna gain with 1 dB cable-loss (EIRP Maximum of 14 dBm). Any Omni-directional type antenna with 14 dBi gain or less can be used with no cable-loss.

Antenna Type: Flat Panel
RF module was tested and approved with 19 dBi antenna gain with 4.8 dB cable-loss (EIRP Maximum of 14.2 dBm). Any Flat Panel type antenna with 14.2 dBi gain or less can be used with no cable-loss.

XBee-PRO OEM RF Module (@ 10 dBm Transmit Power, PL parameter value must equal 0)

The following antennas have been tested and approved for use with the embedded XBee-PRO RF Module:

- Dipole (2.1 dBi, Omni-directional, Articulated RPSMA, MaxStream part number A24-HABSM)
- Chip Antenna (-1.5 dBi)
- Attached Monopole Whip (1.5 dBi)

The RF modem encasement was designed to accommodate the RPSMA antenna option.

Canada (IC)

Labeling Requirements

Labeling requirements for Industry Canada are similar to those of the FCC. A clearly visible label on the outside of the final product enclosure must display the following text:

Contains Model XBee Radio, IC: 4214A-XBEE
Contains Model XBee-PRO Radio, IC: 4214A-XBEEPRO

The integrator is responsible for its product to comply with IC ICES-003 & FCC Part 15, Sub. B - Unintentional Radiators. ICES-003 is the same as FCC Part 15 Sub. B and Industry Canada accepts FCC test report or CISPR 22 test report for compliance with ICES-003.

Japan

In order to gain approval for use in Japan, the XBee-PRO RF Module must contain firmware that limits its transmit power output to 10 dBm.

For a list of module part numbers approved for use in Japan, contact MaxStream [call 1-801-765-9885 or send e-mail to sales@maxstream.net].

Labeling Requirements

A clearly visible label on the outside of the final product enclosure must display the following text:

ID: 005NYCA0378

Appendix B: Development Guide

Development Kit Contents

The XBee Professional Development Kit includes the hardware and software needed to rapidly create long range wireless data links between devices (XBee and XBee-PRO Starter Kits, that contain fewer modules and accessories, are also available).

Table B-01. Items Included in the Development Kit (Professional)

Item	Qty.	Description	Part #
XBee-PRO Module	2	(1) OEM RF Module w/ U.FL antenna connector (1) OEM RF Module w/ attached wire antenna	XBP24-AUI-001 XBP24-AWI-001
XBee Module	3	(1) OEM RF Module w/ U.FL antenna connector (1) OEM RF Module w/ attached whip antenna (1) OEM RF Module w/ chip antenna	XB24-AUI-001 XB24-AWI-001 XB24-ACI-001
RS-232 Development Board	4	Board for interfacing between modules and RS-232 devices (Converts signal levels, displays diagnostic info, & more)	XBIB-R
USB Development Board	1	Board for interfacing between modules & USB devices (Converts signal levels, displays diagnostic info, & more)	XBIB-U
RS-232 Cable (6', straight-through)	1	Cable for connecting RS-232 interface board with DTE devices (devices that have a male serial DB-9 port - such as most PCs)	JD2D3-CDS-6F
USB Cable (6')	1	Cable for connecting USB interface board to USB devices	JU1U2-CSB-6F
Serial Loopback Adapter	1	[Red] Adapter for configuring the module assembly (module + RS-232 interface board) to function as a repeater for range testing	JD2D3-CDL-A
NULL Modem Adapter (male-to-male)	1	[Black] Adapter for connecting the module assembly (module + RS-232 interface board) to other DCE (female DB-9) devices	JD2D2-CDN-A
NULL Modem Adapter (female-to-female)	1	[Gray] Adapter for connecting serial devices. It allows users to bypass the radios to verify serial cabling is functioning properly.	JD3D3-CDN-A
Power Adapter (9VDC, 1 A)	1	Adapter for powering the RS-232 development board	JP5P2-9V11-6F
Battery Clip (9V)	1	Clip for remotely powering the RS-232 board w/ a 9V battery	JP2P3-C2C-4I
RPSMA Antenna	2	RPSMA half-wave dipole antenna (2.4 GHz, 2.1 dB)	A24-HASM-450
RF Cable Assembly	2	Adapter for connecting RPSMA antenna to U.FL connector	JF1R6-CR3-4I
CD	1	Documentation and Software	MD0030
Quick Start Guide	1	Step-by-step instruction on how to create wireless links & test range capabilities of the modules	MD0026

Interfacing Options

The development kit includes an RS-232 and a USB interface board. Both boards provide a direct connection to many serial devices and therefore provide access to the RF module registries. Parameters stored in the registry allow OEMs and integrators to customize the modules to suite the needs of their data radio systems.

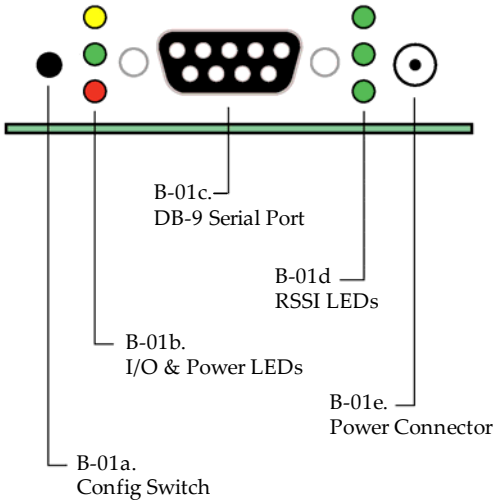
The following sections illustrate how to use the interface boards for development purposes. The MaxStream Interface board provides means for connecting the module to any node that has an available RS-232 or USB connector. Since the module requires signals to enter at TTL voltages, one of the main functions of the interface board is to convert signals between TTL levels and RS-232 and USB levels.

Note: In the following sections, an OEM RF Module mounted to an interface board will be referred to as a "Module Assembly".

RS-232 Development Board

External Interface

Figure B-01. Front View



B-01a. Reset Switch

The Reset Switch is used to reset (re-boot) the RF module. This switch only applies when using the configuration tabs of MaxStream's X-CTU Software.

B-01b. I/O & Power LEDs

LEDs indicate RF module activity as follows:

Yellow (top LED) = Serial Data Out (to host)
Green (middle) = Serial Data In (from host)
Red (bottom) = Power/Association Indicator (Refer to the D5 (DIO5 Configuration) parameter)

B-01c. Serial Port

Standard female DB-9 (RS-232) connector.

B-01d. RSSI LEDs

RSSI LEDs indicate the amount of fade margin present in an active wireless link. Fade margin is defined as the difference between the incoming signal strength and the module's receiver sensitivity.

3 LEDs ON	=	Very Strong Signal (> 30 dB fade margin)
2 LEDs ON	=	Strong Signal (> 20 dB fade margin)
1 LED ON	=	Moderate Signal (> 10 dB fade margin)
0 LED ON	=	Weak Signal (< 10 dB fade margin)

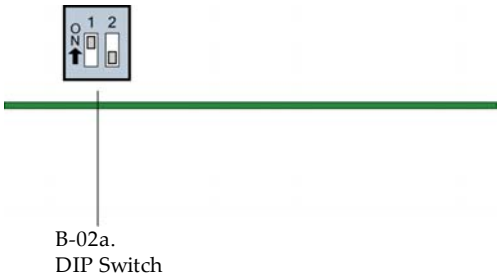
B-01e. Power Connector

5-14 VDC power connector

B-02a. DIP Switch

Figure B-02. Back View

DIP Switch functions are not supported in this release. Future downloadable firmware versions will support DIP Switch configurations.



RS-232 Pin Signals

Figure B-03. Pins used on the female RS-232 (DB-9) Serial Connector

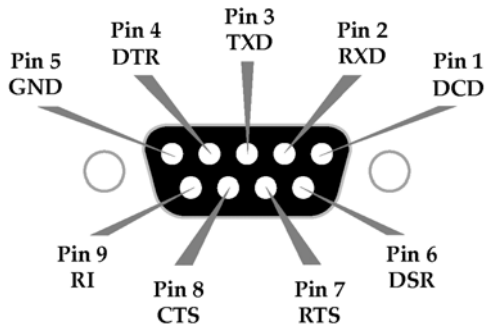


Table B-02. Pin Assignments and Implementations

DB-9 Pin	RS-232 Name	Description	Implementation
1	DCD	Data-Carrier-Detect	Connected to DSR (pin6)
2	RXD	Receive Data	Serial data exiting the module assembly (to host)
3	TXD	Transmit Data	Serial data entering into the module assembly (from host)
4	DTR	Data-Terminal-Ready	Can enable Power-down on the module assembly
5	GND	Ground Signal	Ground
6	DSR	Data-Set-Ready	Connected to DCD (pin1)
7	$\overline{\text{RTS}}$ / CMD	Request-to-Send / Command Mode	Enables $\overline{\text{RTS}}$ flow control or Command Mode
8	$\overline{\text{CTS}}$	Clear-to-Send	Provides $\overline{\text{CTS}}$ flow control
9	RI	Ring Indicator	Optional power input that is connected internally to the positive lead of the front power connector

* Functions listed in the implementation column may not be available at the time of release.

Wiring Diagrams

Figure B-04. DTE Device (RS-232, male DB-9 connector) wired to a DCE Module Assembly (female DB-9)

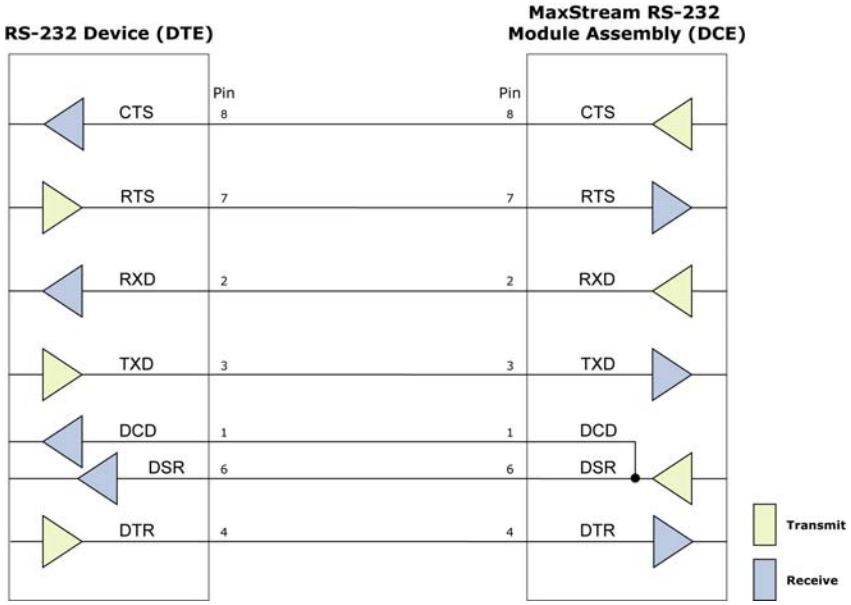
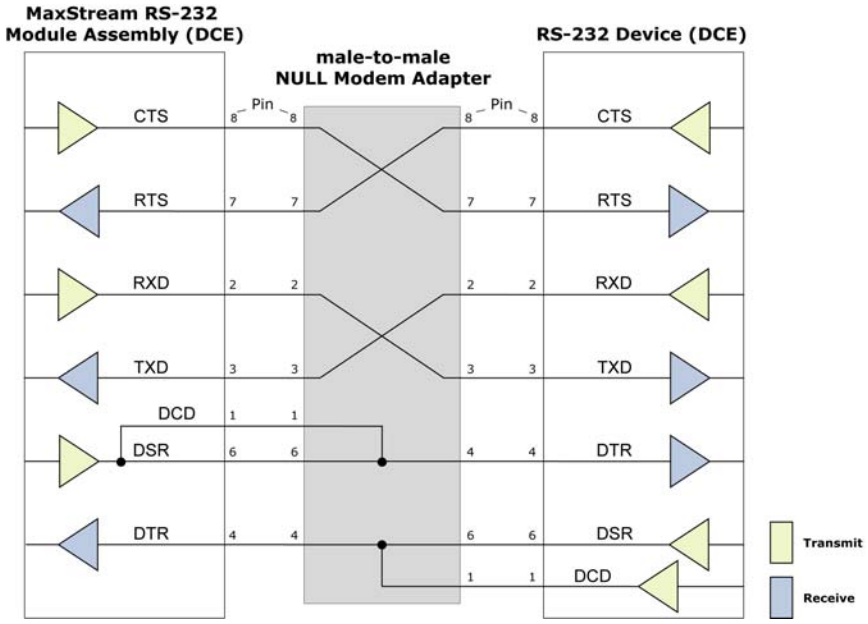
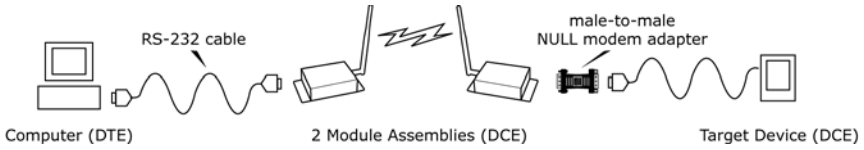


Figure B-05. DCE Module Assembly (female DB-9 connector) wired to a DCE Device (RS-232, male DB-9)



Sample Wireless Connection: DTE <--> DCE <--> DCE <--> DCE

Figure B-06. Typical wireless link between DTE and DCE devices



Adapters

The development kit includes several adapters that support the following functions:

- Performing Range Tests
- Testing Cables
- Connecting to other RS-232 DCE and DTE devices
- Connecting to terminal blocks or RJ-45 (for RS-485/422 devices)

NULL Modem Adapter (male-to-male)

Part Number: JD2D2-CDN-A (Black, DB-9 M-M) The male-to-male NULL modem adapter is used to connect two DCE devices. A DCE device connects with a straight-through cable to the male serial port of a computer (DTE).

Figure B-07. Male NULL modem adapter and pinouts

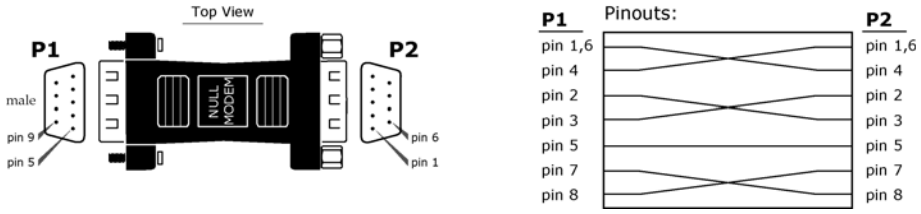
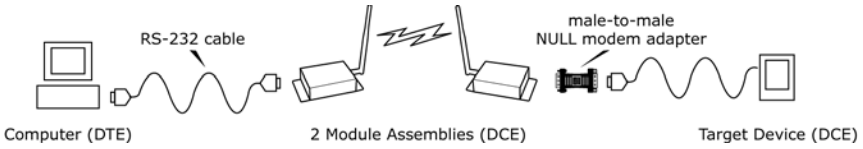


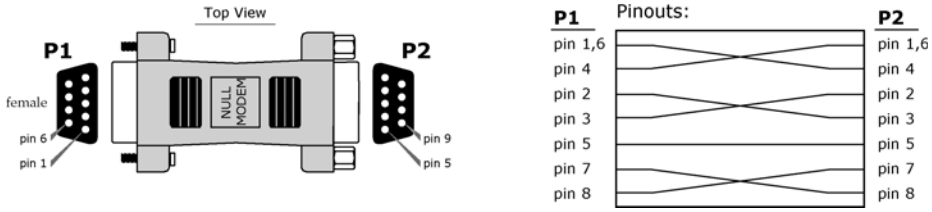
Figure B-08. Example of a MaxStream Radio Modem (DCE Device) connecting to another DCE device)



NULL Modem Adapter (female-to-female)

Part Number: JD3D3-CDN-A (Gray, DB-9 F-F) The female-to-female NULL modem adapter is used to verify serial cabling is functioning properly. To test cables, insert the female-to-female NULL modem adapter in place of a pair of module assemblies (RS-232 interface board + XTend Module) and test the connection without the modules in the connection.

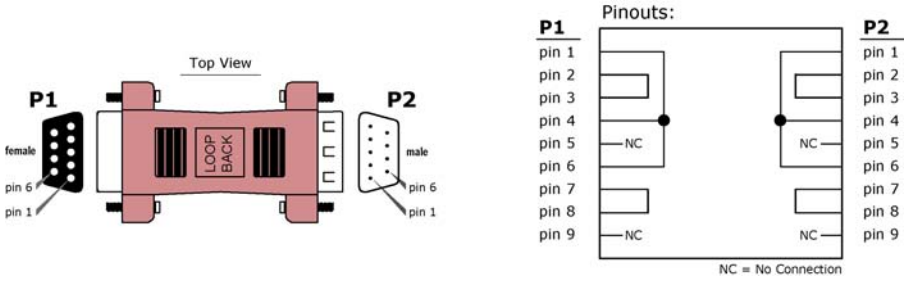
Figure B-09. Female NULL modem adapter and pinouts



Serial Loopback Adapter

Part Number: JD2D3-CDL-A (Red, DB-9 M-F) The serial loopback adapter is used for range testing. During a range test, the serial loopback adapter configures the module to function as a repeater by looping serial data back into the radio for retransmission.

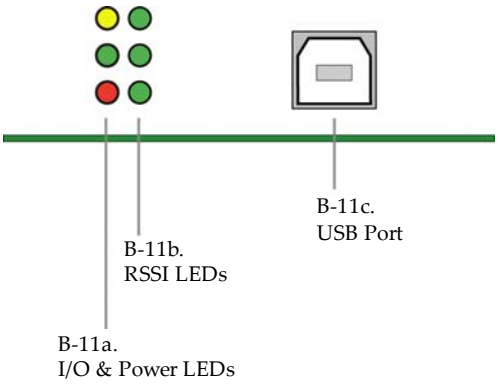
Figure B-10. Serial loopback adapter and pinouts



USB Development Board

External Interface

Figure B-11. Front View



B-11a. I/O & Power LEDs

LEDs indicate RF module activity as follows:

Yellow (top LED) = Serial Data Out (to host)
Green (middle) = Serial Data In (from host)
Red (bottom) = Power/Association Indicator (Refer to the D5 (DIO5 Configuration) parameter)

B-11b. RSSI LEDs

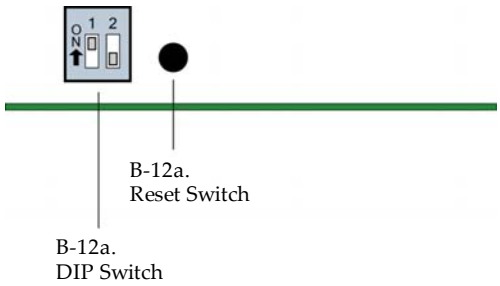
RSSI LEDs indicate the amount of fade margin present in an active wireless link. Fade margin is defined as the difference between the incoming signal strength and the module's receiver sensitivity.

3 LEDs ON	=	Very Strong Signal (> 30 dB fade margin)
2 LEDs ON	=	Strong Signal (> 20 dB fade margin)
1 LED ON	=	Moderate Signal (> 10 dB fade margin)
0 LED ON	=	Weak Signal (< 10 dB fade margin)

B-11c. USB Port

Standard Type-B OEM connector is used to communicate with OEM host and power the RF module.

Figure B-12. Back View



B-12a. DIP Switch

DIP Switch functions are not supported in this release. Future downloadable firmware versions will support the DIP Switch configurations.

B-12b. Reset Switch

The Reset Switch is used to reset (re-boot) the RF module.

USB Pin Signals

Table B-03. USB signals and their implantations on the XBee/XBee-PRO RF Module

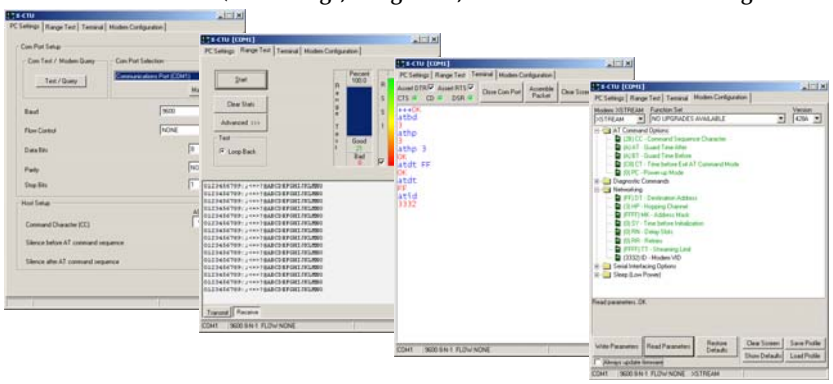
Pin	Name	Description	Implementation
1	VBUS	Power	Power the RF module
2	D-	Transmitted & Received Data	Transmit data to and from the RF module
3	D+	Transmitted & Received Data	Transmit data to and from the RF module
4	GND	Ground Signal	Ground

X-CTU Software

X-CTU is a MaxStream-provided software program used to interface with and configure MaxStream RF Modules. The software application is organized into the following four tabs:

- PC Settings tab - Setup PC serial ports for interfacing with an RF module
- Range Test tab - Test the RF module's range and monitor packets sent and received
- Terminal tab - Set and read RF module parameters using AT Commands
- Modem Configuration tab - Set and read RF module parameters

Figure B-13. X-CTU User Interface (PC Settings, Range Test, Terminal and Modem Configuration tabs)



NOTE: PC Setting values are visible at the bottom of the Range Test, Terminal and Modem Configuration tabs. A shortcut for editing PC Setting values is available by clicking on any of the values.

Installation

Double-click the "setup_X-CTU.exe" file and follow prompts of the installation screens. This file is located in the 'software' folder of the MaxStream CD and also under the 'Downloads' section of the following web page: www.maxstream.net/support/downloads.php

Setup

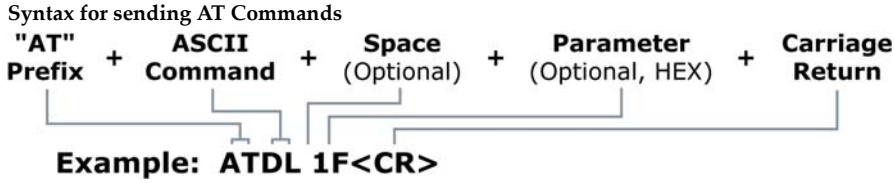
To use the X-CTU software, a module assembly (An RF module mounted to an interface Board) must be connected to a serial port of a PC.

NOTE: Failure to enter AT Command Mode is most commonly due to baud rate mismatch. The interface data rate and parity settings of the serial port ("PC Settings" tab) must match those of the module (BD (Baud Rate) and NB (Parity) parameters respectively).

Serial Communications Software

A terminal program is built into the X-CTU Software. Other terminal programs such as "HyperTerminal" can also be used to configure modules and monitor communications. When issuing AT Commands through a terminal program interface, use the following syntax:

Figure B-14. Syntax for sending AT Commands



NOTE: To read a parameter value stored in a register, leave the parameter field blank.

The example above issues the DL (Destination Address Low) command to change destination address of the module to "0x1F". To save the new value to the module's non-volatile memory, issue WR (Write) command after modifying parameters.

Appendix C: Additional Information

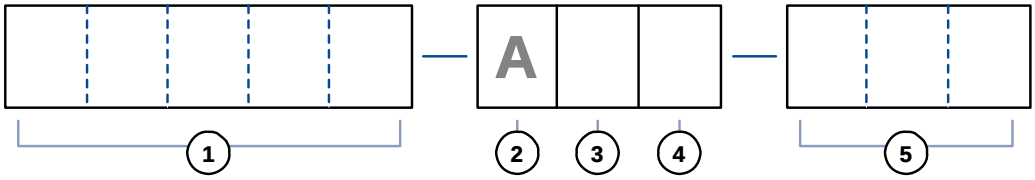
1-Year Warranty

XBee/XBee-PRO RF Modules from MaxStream, Inc. (the "Product") are warranted against defects in materials and workmanship under normal use, for a period of 1-year from the date of purchase. In the event of a product failure due to materials or workmanship, MaxStream will repair or replace the defective product. For warranty service, return the defective product to MaxStream, shipping prepaid, for prompt repair or replacement.

The foregoing sets forth the full extent of MaxStream's warranties regarding the Product. Repair or replacement at MaxStream's option is the exclusive remedy. THIS WARRANTY IS GIVEN IN LIEU OF ALL OTHER WARRANTIES, EXPRESS OR IMPLIED, AND MAXSTREAM SPECIFICALLY DISCLAIMS ALL WARRANTIES OF MERCHANTABILITY OR FITNESS FOR A PARTICULAR PURPOSE. IN NO EVENT SHALL MAXSTREAM, ITS SUPPLIERS OR LICENSORS BE LIABLE FOR DAMAGES IN EXCESS OF THE PURCHASE PRICE OF THE PRODUCT, FOR ANY LOSS OF USE, LOSS OF TIME, INCONVENIENCE, COMMERCIAL LOSS, LOST PROFITS OR SAVINGS, OR OTHER INCIDENTAL, SPECIAL OR CONSEQUENTIAL DAMAGES ARISING OUT OF THE USE OR INABILITY TO USE THE PRODUCT, TO THE FULL EXTENT SUCH MAY BE DISCLAIMED BY LAW. SOME STATES DO NOT ALLOW THE EXCLUSION OR LIMITATION OF INCIDENTAL OR CONSEQUENTIAL DAMAGES. THEREFORE, THE FOREGOING EXCLUSIONS MAY NOT APPLY IN ALL CASES. This warranty provides specific legal rights. Other rights which vary from state to state may also apply.

Ordering Information

Figure C-01. Divisions of the XBee/XBee-PRO RF Module Part Numbers



1 MaxStream Product Family
- XB24 = XBee 2.4 GHz
- XBP24 = XBee-PRO 2.4 GHz

2 Reserved for internal use
- Insert the letter 'A'

3 Antenna Option
- C = Chip Antenna
- U = U.FL RF Connector
- W = Integrated Whip Antenna

4 Rating
- I = Industrial (-40 to 85° C)

5 Protocol
- 001 = 802.15.4
- 002 = ZigBee

For example:

XBP24-AWI-001 = XBee-PRO OEM RF Module, 2.4 GHz, attached whip antenna, Industrial temperature rating, IEEE 802.15.4 standard

If operating in Japan, XBee-PRO RF Modules must contain firmware that limits transmit power output to 10 dBm. For a list of module part numbers approved for use in Japan, contact MaxStream [call 1-801-765-9885 or send e-mail to sales@maxstream.net].

Contact MaxStream

Free and unlimited technical support is included with every MaxStream Radio Modem sold. For the best in wireless data solutions and support, please use the following resources:

Documentation:	www.maxstream.net/support/downloads.php	
Technical Support:	Phone.	(866) 765-9885 toll-free U.S.A. & Canada (801) 765-9885 Worldwide
	Live Chat.	www.maxstream.net
	E-Mail.	rf-xperts@maxstream.net

MaxStream office hours are 8:00 am - 5:00 pm [U.S. Mountain Standard Time]